

Nanoscale Contact Mechanics between Two Grafted Polyelectrolyte Surfaces

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1 Nanoscale Contact Mechanics between Two Grafted Polyelectrolyte Surfaces

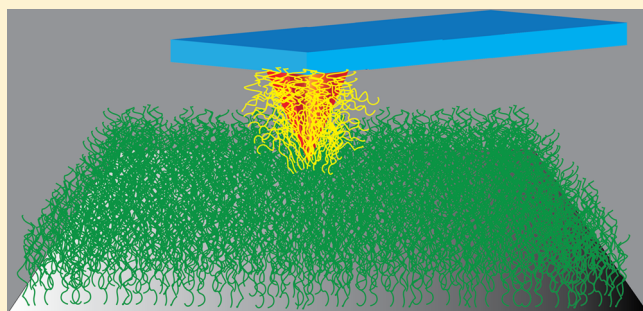
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6 **S** Supporting Information

7 **ABSTRACT:** The adhesive and frictional behavior of end-
 8 grafted poly[2-(dimethylamino)ethyl methacrylate] (PDMAE-
 9 MA) films (brushes) in contact with atomic force microscope
 10 tips from which PDMAEMA and poly(methacrylic acid)
 11 (PMAA) were grafted has been shown to be a strong function
 12 of pH in aqueous solution. The interaction between the brush-
 13 coated surfaces is determined by a combination of electrostatic
 14 and noncovalent interactions, modulated by the effect of the
 15 solvation state on the brush and the resulting area of contact
 16 between the probe and the surface. For cationic PDMAEMA–
 17 PDMAEMA contacts at low pH, the brushes are highly
 18 solvated; a combination of electrostatic repulsion and a high
 19 degree of solvation (leading to a significant osmotic pressure) leads to a small area of contact, weak adhesion, and energy
 20 dissipation through plowing. As the pH increases, the electrostatic repulsion and the osmotic pressure decrease, leading to an
 21 increase in the area of contact and a concomitant increase in the strength of adhesion through hydrophobic interactions; as a
 22 consequence, the friction–load relationship becomes nonlinear as shear processes contribute to friction and the mechanics are
 23 fitted by DMT theory and, at higher pH, by the JKR model. For PDMAEMA–PMAA, the electrostatic interaction is attractive at
 24 neutral pH, leading to a large adhesion force, a large area of contact, and a nonlinear friction–load relationship. However, as the
 25 pH becomes either very small or very large, a significant charge is acquired by one of the contacting surfaces, leading to a large
 26 amount of bound solvent and a significant osmotic pressure that resists deformation. As a consequence, the area of contact is
 27 small, adhesion forces are reduced, and the friction–load relationship is linear, with energy dissipation dominated by molecular
 28 plowing.



1. INTRODUCTION

29 Polymers end-grafted to surfaces are known as brushes and
 30 have assumed a technological importance because of real and
 31 potential applications in adhesion,^{1–3} lubrication and fric-
 32 tion,^{4–7} and controlled cell growth⁸ and biocompatibility.⁹
 33 Charged polymers, however, have a great deal of promise in
 34 these areas because their properties can be readily controlled by
 35 environmental pH and salt.^{4,10–17} The combination of
 36 positively and negatively charged polyelectrolytes in particular
 37 is particularly powerful because strong adhesion between the
 38 two occurs at intermediate pH. For example, the layer-by-layer
 39 technique provides polymer multilayers of controlled thick-
 40 ness,¹⁸ but the adhesion between oppositely charged
 41 polyelectrolytes can be reversed by a simple pH change.^{13,14}
 42 The interaction between charged polymers is of further
 43 interest because this situation includes two lubricating surfaces.
 44 For polymers of the same charge, the nature of the process is
 45 dependent on the relative motion of the two surfaces, the force
 46 applied, and the physical properties of the polymers (e.g., molar
 47 mass).¹⁹ The pH dependence of the interaction between
 48 polymers of the same charge is important because the lubricity
 49 of the polymers depends on their charged status. However, the

role of counterions is also important and can even facilitate an
 attraction between layers of the same charge.²⁰ Simply because
 both surfaces are good lubricants in water does not imply that
 they must be assumed to be lubricious when brought together.
 For the case of polyelectrolytes of opposite charge, the
 underlying mechanism for the adhesive interaction is unclear.
 Hydrogen bonds are known to be important in pH-dependent
 polymer interactions²¹ and even to control pH-switchable
 adhesion,²² and the relative roles of electrostatic and hydrogen
 bonding in the adhesion between oppositely charged
 polyelectrolytes have not been confirmed.¹⁴ The contact
 mechanics between charged surfaces provides a means to test
 the nature of these polymer–polymer interactions. For both
 situations (polycation with polycation or polycation with
 polyanion), the interaction will be strongly dependent upon
 pH.

The controllable lubricity of polyelectrolytes can be studied
 using friction force microscopy (FFM),^{23–26} a scanning probe
 microscopy (SPM) technique that allows the nanotribological

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69 characteristics of a surface to be probed using a well-defined
70 nanoscale atomic force microscope probe (AFM tip) that may
71 be chemically modified to control its interaction with the
72 surface.^{27–31} Some FFM experiments have been performed
73 with a colloidal probe,^{32–34} which can provide a better defined
74 surface than that offered by an AFM tip. However, an AFM tip
75 is preferred because the goal here is to understand single
76 asperity brush–brush contacts. Because SPM experiments can
77 be performed in solution, FFM is ideal for the investigation of
78 the adhesion and friction of end-grafted polyelectrolytes.¹⁵
79 Control and understanding of friction in polymer brush
80 contacts in general has been the subject of significant research
81 in recent years, particularly because polymer brushes are a
82 practical means of altering the tribological properties of a
83 surface.^{5,35–37} In an earlier study,¹⁵ it was shown that the
84 frictional interaction between poly[2-(dimethylamino)ethyl
85 methacrylate] (PDMAEMA, a polycation) brushes and AFM
86 tips depends strongly on the environmental pH, with a linear
87 friction–load relationship observed at the extremes of pH, and
88 adhesion-dominated behavior, consistent with either DMT or
89 JKR mechanics observed at intermediate pH. Importantly,
90 whether or not DMT or JKR behavior was observed depended
91 not only on the environmental pH but also on the chemical
92 nature of the AFM tip.

93 The mechanism of interaction between an AFM tip and a
94 polymer brush is not trivial. Different types of friction–load
95 relationships have been observed previously on a range of
96 polymer brush systems. Linear relationships, described by
97 Amontons' law,³⁸ which is a multiasperity model indicates that
98 the applied load, N , rather than the area of contact, A , is the
99 determining factor, and the frictional force is given by

$$100 \quad F = \mu N \quad (1)$$

101 where μ is the coefficient of macroscopic friction. Linear
102 relationships have been observed in different polymer brush
103 systems.^{15,35,39,40} However, with an AFM tip, single-asperity
104 contact mechanics would be expected and have indeed been
105 observed.^{15,17,41–43}

106 Single-asperity models of contact mechanics can be split into
107 two extremes. Softer materials are more able to conform to a
108 surface than those with a larger modulus, and this situation is
109 described by the Johnson–Kendall–Roberts (JKR) model,⁴⁴
110 which is given by

$$111 \quad A = \pi \left(\frac{R}{K} (N + 3\pi\gamma R + \sqrt{6\pi\gamma RN + (3\pi\gamma R)^2}) \right)^{2/3} \quad (2)$$

112 for a hemispherical (radius R) contact with a planar surface.
113 Here γ is the interfacial energy (thermodynamic work of
114 adhesion), and K is the effective elastic modulus of the medium
115 perturbed by the contact. A model proposed by Derjaguin,
116 Muller, and Toporov⁴⁵ caters for more rigid interfaces and is
117 given by

$$118 \quad A = \pi \left(\frac{R}{K} \right)^{2/3} (N + 4\pi\gamma R)^{2/3} \quad (3)$$

119 Both the DMT and JKR models reduce to the same (Hertz)
120 model⁴⁶ when $\gamma = 0$. It is not the case that a choice must be
121 made between JKR or DMT; a transition parameter,⁴⁷ α , can be
122 used as a scale between JKR ($\alpha = 1$) and DMT ($\alpha = 0$) to
123 evaluate the contact mechanics. This transition parameter
124 relates the contact radius, a (where $A = \pi a^2$), to the applied
125 load by

$$a = a_0 \left(\frac{\alpha + \sqrt{1 - N/N_{PO}}}{1 + \alpha} \right)^{2/3} \quad (4)$$

where N_{PO} is the force required to separate the two
components, known as the pull-off force.

129 Recently, the frictional force of single asperity contacts has
130 been shown to comprise a regime of low adhesion, when the
131 load applied to the surface, N , dominates and molecular
132 deformation “plowing” occurs, and an area-dependent high
133 adhesion term, when the surface is sheared by the tip.^{23,48,49}
134 During the friction measurement, work is done by perturbing
135 the conformation of the brush; the brush then returns to its
136 equilibrium conformation via the dissipation of energy as heat.
137 Here, the load-dependent term represents (irrecoverable)
138 energy dissipation through plowing. However, the shear-
139 dependent term, characterized by a surface shear strength τ ,
140 represents the stress required to maintain a sliding contact.
141 These can be synthesized into a frictional force dependent
142 upon two terms:^{50,51}

$$F = \mu(N + N_{PO}) + \tau\pi \left(\frac{R(N + N_{PO})}{K} \right)^{2/3} \quad (5)$$

144 Equation 5 has already been shown to explain qualitatively the
145 single asperity contact mechanics of a polyzwitterionic brush.¹⁷
146 Both load-dependent and area-dependent terms contribute to
147 the overall friction force, depending on the solvation state of
148 the polymer brush.

149 In this work, experiments are described in which
150 polyelectrolyte brush layers were grown from AFM tips,
151 chemically modified with a coating of an initiator layer. The
152 frictional properties of these brushes interacting with planar
153 brushes of the same or opposite charge were monitored as a
154 function of pH. As in the earlier work,¹⁵ it is shown that the pH
155 affects whether or not DMT or JKR behavior is observed, and
156 again Amontons-like behavior is observed at the extremes of
157 pH.

2. EXPERIMENTAL SECTION

158 **2.1. Materials.** Silicon wafers (boron doped, 0–100 Ω cm, and
159 (100) orientation) were purchased from Prolog Semicor (Ukraine).
160 Copper(I) chloride (99.999%), copper(II) bromide (99.999%), [11-
161 (2-bromo-2-methyl)propionyloxy]undecyltrichlorosilane, *p*-toluene-
162 sulfonic acid monohydrate (98.5%), pentamethyldiethylenetriamine
163 (99%), *t*-butyl methacrylate (99%), 1,4-dioxane (99.5%), dry toluene
164 (99.8%), 2-(dimethylamino)ethyl methacrylate ($C_8H_{15}NO_2$), HCl
165 (37%), and NaOH (>97%) were all purchased from Aldrich and
166 used as received. HPLC grade acetone, methanol, acetic acid, and
167 triethylamine were purchased from Fisher Scientific. 2,2'-Dipyridyl
168 (99%) was purchased from Acros.

169 **2.2. Brush Synthesis and Modification of the AFM Canti-
170 lever.** PDMAEMA brushes were grafted from silicon substrates and
171 silicon nitride AFM tips by atom transfer radical polymerization
172 (ATRP). Here, the initiator was immobilized on the substrate,
173 followed by the synthesis of the polymer brush layer.

174 To immobilize the initiator, the clean silicon wafer and AFM tip
175 were immersed for 6 h in 20 mL of dry toluene solution containing 50
176 μ L of [11-(2-bromo-2-methyl)propionyloxy]undecyltrichlorosilane
177 (initiator). When coated, the substrates and AFM tip were rinsed
178 with toluene and then dried under nitrogen gas. The AFM tips before
179 modification were nonconductive silicon nitride triangular probes
180 (MLCT, Bruker) with nominal spring constant 0.065 N m⁻¹ and
181 radius 20 nm.

182 To prepare cationic monomer solutions for ATRP, 2,2'-dipyridyl
183 (0.225 g), CuCl (0.0624 g), and CuBr₂ (0.0084 g) were added

184 together as catalysts. These catalysts were dissolved by adding
 185 degassed acetone (15.9 mL) and 1.5 mL of deionized water. The
 186 ATRP monomer solution was finally prepared by adding the 10.8 mL
 187 of 2-(dimethylamino)ethyl methacrylate (DMAEMA) to the catalyst
 188 solution. Finally, 20 mL of the ATRP solution was injected into a cell
 189 (sealed under nitrogen), which contained the initiator-coated silicon
 190 wafer and AFM tip. The PDMAEMA sample and the PDMAEMA-
 191 coated AFM tip were removed and rinsed with methanol after 16 h.
 192 AFM tips modified to contain a poly(methacrylic acid) (PMAA)
 193 brush were prepared in three stages. First, the trichlorosilane initiator
 194 monolayer was prepared in the same way as for the PDMAEMA
 195 brushes, then the synthesis of poly(*tert*-butyl methacrylate) brushes
 196 were synthesized by ATRP, and finally the poly(*tert*-butyl
 197 methacrylate) was hydrolyzed to produce PMAA brushes.

198 Poly(*tert*-butyl methacrylate) brushes were synthesized using ATRP
 199 on the surface-initiated AFM tip. Here, 20 mL of *tert*-butyl
 200 methacrylate, 10 mL of anhydrous dioxane, and 200 μ L of
 201 pentamethyldiethylenetriamine were added together. Then 20 mL of
 202 this ATRP solution was injected to the cell containing the initiated tip
 203 and wafer and 0.1 g of CuCl (I). This cell was left on a heater at 50 $^{\circ}$ C
 204 for \sim 18 h. Finally, the coated tips and surfaces were rinsed with 1,4-
 205 dioxane and acetic acid. For hydrolysis, 0.2 M of *p*-toluenesulfonic acid
 206 and 10 mL of 1,4-dioxane were added over the coated tip in the cell
 207 and heated at 100 $^{\circ}$ C for 24 h. After hydrolysis, the PMAA-coated tips
 208 were removed and rinsed with 1,4-dioxane and ethanol. PMAA
 209 brushes were also grown from planar silicon surfaces using the same
 210 methodology in order to characterize the thickness of the films.

211 **2.3. Brush Characterization.** The average thickness of the PMAA
 212 and PDMAEMA films was determined by spectroscopic ellipsometry
 213 with an M-2000 spectroscopic ellipsometer (J.A. Woollam) for both
 214 dry brushes and those immersed in different pH solutions.
 215 Ellipsometry measurements were taken using wavelengths from 200
 216 to 1000 nm, and the data were fitted using the analysis software
 217 WVASE32 (J.A. Woollam). The ellipsometric thicknesses of the
 218 PMAA and PDMAEMA brushes were first measured to be about 58
 219 and 64 nm, respectively, in the dry state. X-ray photoelectron
 220 spectroscopy (XPS) was used to monitor each stage of the process on
 221 the planar surfaces and AFM tips using a Kratos Axis Ultra
 222 spectrometer. A monochromated 150 W Al $K\alpha$ source was used to
 223 acquire the spectra under an \sim 10 $^{-6}$ Pa vacuum. All samples were left
 224 overnight at room temperature prior to analysis. Data were first
 225 recorded at a pass energy of 160 eV while high-resolution C(1s),
 226 O(1s), and N(1s) scans were recorded at a pass energy of 20 eV with a
 227 step size of 0.1 eV. Data were analyzed using CasaXPS software, and
 228 quantification was realized using the default Kratos RSF (relative
 229 sensitivity factor) library. Carbon spectra were charge corrected
 230 according to the value of aliphatic carbon C(1s) at 285 eV. High-
 231 resolution scans were taken of C(1s), O(1s), and S(2p) peaks. These
 232 high-resolution peaks were fitted using a Gaussian–Lorentzian model.
 233 The fwhm was kept below 1.7 eV. To check the thickness of
 234 PDMAEMA brushes on the cantilever, a Carl Zeiss 1540XB scanning
 235 electron microscope (SEM) was used to take images from a brush-
 236 modified cantilever. Free (i.e., not grafted) PDMAEMA was
 237 synthesized following the same protocol as that for the grafted
 238 PDMAEMA and characterized by gel permeation chromatography,
 239 from which a molar mass of 39 kg/mol was determined.¹⁵ The grafting
 240 density of the PDMAEMA was thus determined to be 0.84 chains/
 241 nm². Since the synthesis of the poly(*tert*-butyl methacrylate) followed
 242 the same procedure, a similar grafting density can be assumed. Given a
 243 dry thickness of 58 nm, the PMAA molar mass can therefore be taken
 244 to be 42 kg/mol.

245 **2.4. Friction Force Microscopy Experiments.** A Digital
 246 Instruments Nanoscope IIIa Multimode atomic force microscope
 247 was used for friction force measurements operating in contact mode
 248 with a liquid cell/tip holder. FFM experiments were performed at a
 249 scan rate (constant tip speed of 2 μ m/s) of 1 Hz with 256 points per
 250 (1 μ m) line. The spring constants of PMAA- and PDMAEMA-coated
 251 cantilevers were calibrated by a Digital Instruments PicoForce module
 252 and its associated software, based on the method of Hutter and
 253 Bechhoeffer.⁵² The PDMAEMA-coated tips were determined to have a

spring constant of 0.073 N m $^{-1}$, and those for the PMAA-coated tips 254
 were 0.080 N m $^{-1}$. (The unmodified cantilevers had spring constants 255
 in the range 0.063–0.068 N m $^{-1}$, close to the nominal value.) The 256
 optical lever sensitivity of each brush-coated cantilever was calibrated 257
 at neutral pH before each set of experiments. The lateral force was 258
 calibrated using the wedge method,^{53–55} with the cantilever scanning 259
 across a calibration grating (TGF11, MikroMasch, Tallinn, Estonia). 260

The frictional behavior between the PDMAEMA brush and each 261
 AFM-coated tip was measured in deionized water and solution with 262
 different pH (pH = 1–12) by the addition of HCl or NaOH as 263
 appropriate. A pH meter was routinely used to monitor pH. Buffer was 264
 not used to stabilize pH because of the contribution of the increased 265
 ionic strength to shielding the charges in the polyelectrolyte layers. 266

3. RESULTS

3.1. Brush Thickness. The variation of thickness with pH 267
 (from 1 to 12) of both PDMAEMA and PMAA brushes in 268
 solution was measured by ellipsometry using an effective 269
 medium approximation⁵⁶ to account for the nonuniform 270
 concentration profile of these brushes. Discrepancies due to 271
 the dry and ellipsometric thicknesses measured in solution can 272
 be taken as being due to the assumptions made in calculating 273
 the thickness. The ellipsometric thickness data are shown in 274

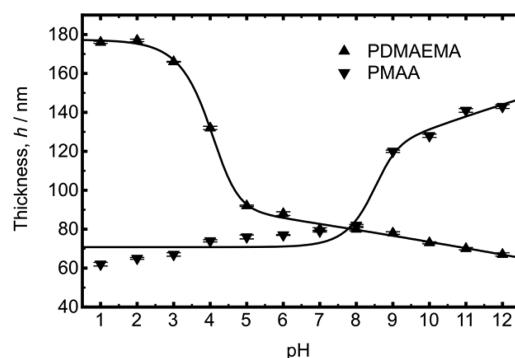


Figure 1. Ellipsometric characterization of the thickness of PDMAEMA and PMAA brushes grafted from planar silicon surfaces. The solid lines are fits to eq 6. The dry brush thicknesses (before immersion in solution) were respectively 64 and 58 nm. Error bars (not used in the fitting) were taken from 20 repeated measurements on different spots.

Figure 1. The solid lines in Figure 1 are fits to an empirical 275
 function for the thickness, given by 276

$$h = h_2 + \frac{h_1 - h_2}{2} \times \sqrt{\left(1 + \tanh\left(\frac{\text{pH} - \Delta_1}{\sigma_1}\right)\right) \left(1 + \tanh\left(\frac{\text{pH} - \Delta_2}{\sigma_2}\right)\right)} \quad (6)$$

where the parameters h_1 , h_2 , Δ_1 , Δ_2 , σ_1 , and σ_2 are fitting 278
 parameters with no substantive physical meaning. Equation 6 279
 exhibits an approximate form of the ellipsometry data, and its 280
 functional form enables a calculation of the thickness transition 281
 (equivalent to the $\text{p}K_a$) by setting its second derivative with 282
 respect to pH to be zero. As a result, the PDMAEMA brushes 283
 showed a thickness transition at pH = 4.1, which is significantly 284
 less than the $\text{p}K_a$ of dilute aqueous solutions of PDMAEMA, 285
 where $\text{p}K_a = 7.0$ has been measured.⁵⁷ Similarly, the transition 286
 for PMAA was observed at 8.5, considerably greater than that 287

288 for PMAA in dilute solution of 5.7.⁵⁸ (The uncertainty in these
 289 values is very small, but this uncertainty comes from taking eq 6
 290 as axiomatic, when it is in fact empirical.) The shift in the
 291 conformational transition relative to the bulk pK_a is due to the
 292 effects of counterion condensation⁵⁹ in the brushes. The
 293 osmotic pressure of the counterions is significant, and the
 294 solution can lower its energy if the polyelectrolyte is partially
 295 neutralized. The effect of confinement on the charge
 296 distribution in polyelectrolyte brushes is dependent upon
 297 grafting density.⁶⁰

298 To measure the brush thickness on the AFM tip is
 299 considerably more challenging, but an indication of the
 300 presence of dry PDMAEMA brush and its thickness was
 301 obtained using a SEM. In Figure 2 a SEM image is shown of a

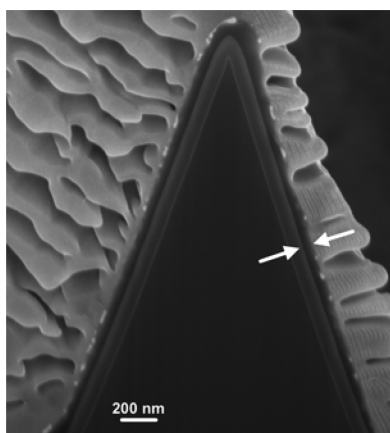


Figure 2. SEM image of PDMAEMA brush layer on the cantilever. The arrows indicate the location of the PDMAEMA brush. A layer of platinum, used to protect the brush layer during exposure to the gallium ion beam, is the outermost (wavy) structure shown in the micrograph.

302 cantilever from which a PDMAEMA brush was grown. A 5 nm
 303 gold layer was sputtered onto the brush and a 1 μm platinum
 304 strip subsequently attached. The platinum layer provides good
 305 protection for the brush from the milling process, which was
 306 performed with a 30 kV focused gallium ion beam. The
 307 thickness of 70 nm obtained using this procedure is consistent
 308 with the ellipsometry results.

309 **3.2. Adhesion.** The adhesive interactions were determined
 310 by checking the maximum force required in the retraction of
 311 the PDMAEMA- or PMAA-modified tips from contact with the
 312 PDMAEMA brush. Adhesion measurements were performed in
 313 solutions of different pH; 100 measurements were made for
 314 each pH. Figure 3 shows approach curves for the PDMAEMA-
 315 and PMAA-modified probes and the planar PDMAEMA brush
 316 layer immersed in solutions of different pH. It is revealing that
 317 for both samples the approach curves at intermediate pH
 318 indicate a stiffer interaction than at the extremes of pH, where
 319 the smaller slope indicates a smaller linear compliance. While
 320 surprising, these results do not contradict earlier data
 321 considering the effect of the polycation brush with different
 322 AFM tips coated with different surfaces.¹⁵ In those experiments,
 323 regardless of the nature of the surface, a linear friction-load
 324 relationship was observed at the extremes of pH. Under such
 325 conditions, the second area-dependent term in eq 5, associated
 326 with shearing (adhesive) contributions to friction, is small, and
 327 the load-dependent term dominates.

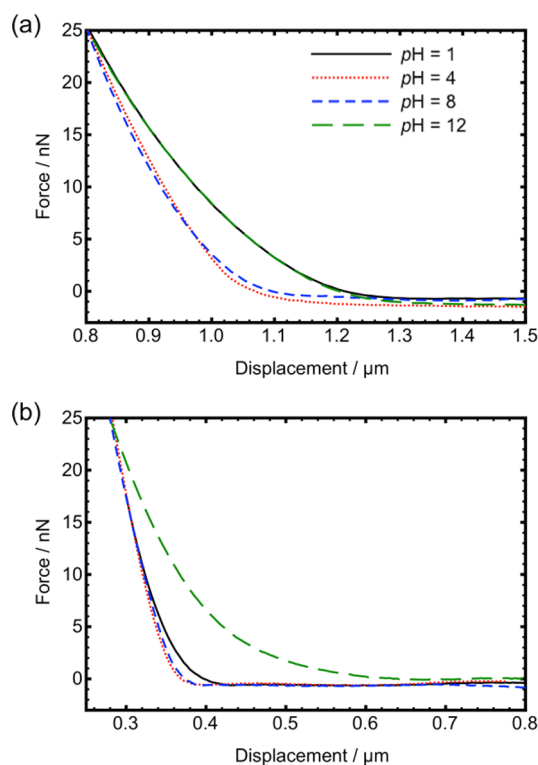


Figure 3. Approach curves for (a) PDMAEMA and (b) PMAA brush-coated tips to a PDMAEMA brush layer on a planar silicon substrate measured at four different pH values.

Retraction curves for the different systems are shown in 328
 Figure 4. The retraction curves, like the approach curves shown 329

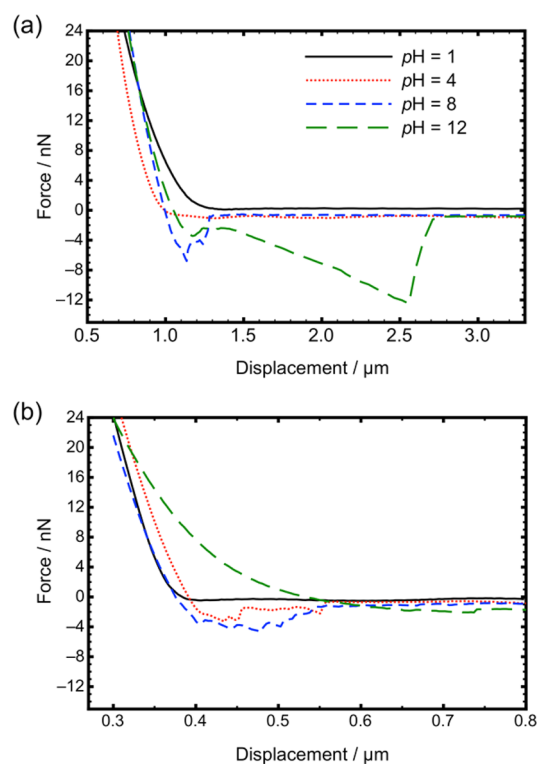


Figure 4. Retraction curves for (a) PDMAEMA and (b) PMAA brush-coated tips to a PDMAEMA brush layer on a planar silicon substrate measured at four different pH values.

330 in Figure 3, are presented as force as a function of displacement
 331 from the contact point, rather than force as a function of a
 332 distance from a predefined zero in order to ensure reproducible
 333 and reliable interpretation of the data.⁶¹ The adhesion increases
 334 with pH for the PDMAEMA–PDMAEMA interaction, whereas
 335 it reaches a maximum at pH = 6 for the PMAA–PDMAEMA
 336 system (Figure 5). The maximum adhesion values for the two

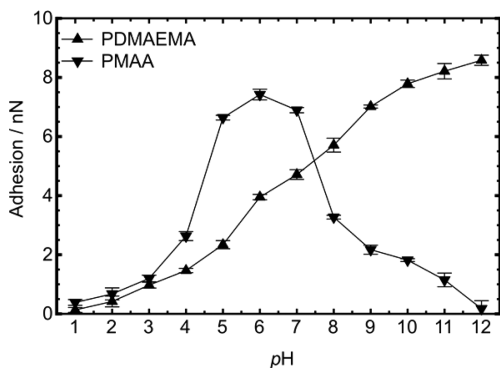


Figure 5. Adhesion results (pull-off force) for the PDMAEMA- and PMAA-coated tips with the PDMAEMA brush on a planar surface.

337 systems are similar. It is perhaps surprising that the maximum
 338 displacement for the PDMAEMA–PDMAEMA system at pH =
 339 12 is well over a micrometer greater than the other results
 340 shown in Figure 4, which may indicate that the brush layers
 341 (either on the probe, the planar substrate, or both) are being
 342 disrupted and pulled off the substrate. By way of contrast, there
 343 is no apparent attraction between PMAA and PDMAEMA at
 344 pH = 12, except a long-range repulsion, which is likely to be
 345 steric as the brushes are being compressed. The adhesion is well
 346 illustrated from the histograms shown in Figure 6 presenting
 347 the force required to separate the cantilever from the surface.

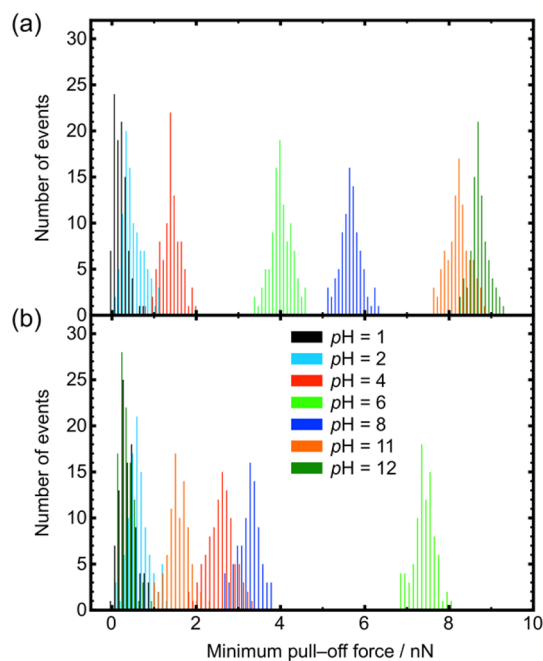


Figure 6. Adhesion histograms for the (a) PDMAEMA- and (b) PMAA-coated tips with the PDMAEMA brush on a planar surface. The legend applies to both histograms.

Here it is clear that the PDMAEMA–PDMAEMA interaction is
 stronger than that between PDMAEMA and PMAA, with more
 pH values experiencing relatively strong adhesion.

3.3. Friction. Friction force measurements were performed
 on the same tip–sample combinations over the same range of
 pH (1–12), over a scan size of $1\ \mu\text{m} \times 1\ \mu\text{m}$. Friction–load
 data are shown in Figure 7. For the PDMAEMA–PDMAEMA

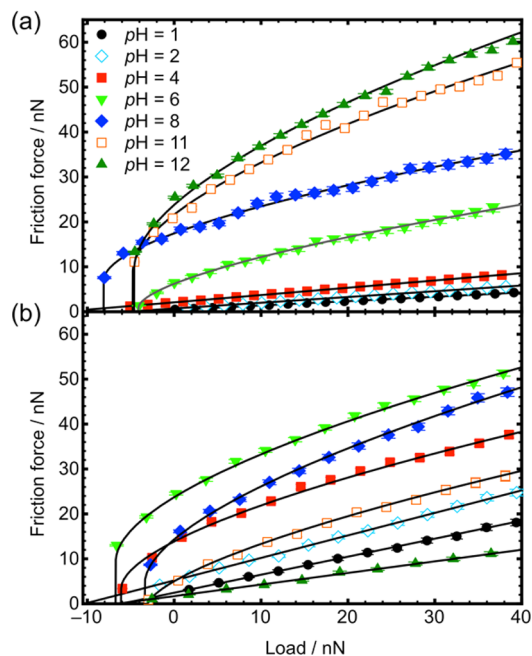


Figure 7. Friction–load plots for the (a) PDMAEMA- and (b) PMAA-coated tips with the PDMAEMA brush on a planar surface. The data were fitted either to a linear friction–load relationship or the JKR or DMT models (nonlinear friction–load relationship).

interaction, the friction force increased with pH across the
 range of loads studied. At low pH (≤ 4) the friction–load
 relationship is linear, but at pH = 6 it is nonlinear and it
 remains so as the pH is increased further. A linear friction–load
 relationship is associated with nonadhesive sliding, for both
 polymers and organic monolayers, and represents the limiting
 case of eq 5, in which the shear term is negligible. When there is
 energy dissipation through adhesive interactions, the shear term
 in eq 5 is nonzero and the friction–load relationship becomes
 nonlinear. Depending on the strength of the adhesive
 interaction, the contact mechanics may be modeled using
 either JKR or DMT theory, and the friction–load plots may be
 fitted using the general transition equation (eq 4).

For the PDMAEMA–PDMAEMA interaction at low pH,
 protonation of the amine groups is expected, leading to strong
 solvation of the polymer brushes as well as repulsive
 interactions between the similar electrostatic charges on the
 contacting surfaces. As a consequence, adhesive interactions are
 weak, and the area-dependent term in eq 5 is small; the load-
 dependent term dominates, yielding a linear friction–load
 relationship. The main pathways for energy dissipation are via
 molecular plowing, as was described previously for zwitterionic
 polymer brushes.¹⁷ As the pH is increased, the degree of
 protonation of the amine groups on the polymer decreases,
 with the consequence that the degree of solvation also
 decreases. At pH 6 the reduction in the degree of surface
 charge and solvation is such that attractive hydrophobic

interactions between the two surfaces yield a significant adhesive contact. As a result, the area-dependent term in eq 5 makes a significant contribution to the friction force, and behavior that is consistent with DMT mechanics is observed. As the pH increases further, the net adhesive interaction becomes stronger. While plowing contributes to friction, the shear term dominates at high pH when the friction–load relationship is fitted by JKR mechanics.

For the PMAA–PDMAEMA interaction the friction–load relationship is linear at pH = 1, 2, and 12. This indicates that the interaction is dominated by plowing; at either extreme of pH, one of the surfaces (PDMAEMA at pH 1 and 2 and PMAA at pH 12) is ionized and hence highly solvated, leading to a reduction in adhesion. However, the friction–load relationship is nonlinear at pH 4–11, as was the case for frictional behavior of PDMAEMA brushes with AFM tips coated with different monolayers.¹⁵ At these intermediate pH values, the contacting surfaces are partially ionized and solvated to varying degrees; there are net attractive interactions, and the shear term in eq 5 makes a significant contribution to the friction force. The friction force exhibits a maximum around pH = 7. At this pH, the adhesion force is close to its maximum value, probably because the brushes on opposing surfaces contain opposite charges which attract each other strongly. The frictional response of the PDMAEMA-coated tips with PDMAEMA brush films is more lubricious at low pH than that with PMAA brush films at any pH.

4. DISCUSSION

The friction–load behavior for the two polycationic brushes at low pH was fitted to the DMT model ($\alpha = 0$), while at high pH, the behavior was fitted by JKR theory. This is consistent with our knowledge of the charge state of the polymers: at low pH, they are cationic, and electrostatic repulsion causes them to stretch away from the surface. They are also extensively solvated by a substantial quantity of bound water. At higher pH, the polycationic brushes are relatively collapsed, with only a limited quantity of water contained within the layer. The DMT model is thought to apply to stiffer, less adhesive contacts, while the JKR model applies to softer, more adhesive contacts. The analysis of the contact mechanics is thus consistent with our understanding of the respective models: solvation of the brushes at low pH leads to reduced adhesion, and the significant osmotic pressure that results stiffens the brush layer under sliding. During sliding at low pH, the energy dissipation is largely through plowing. As the pH increases, the density of charges in the polymer decreases and the strength of adhesion increases. Although the work of adhesion remains low, the area of contact is large because of the small elastic modulus of a polymer brush layer, which results in a significant contribution of the area-dependent term. As the pH increases still further, and the brush becomes less fully solvated, the contact area increases. The work of adhesion remains low, but the increase in the contact area is equivalent to a reduction in the effective modulus of the contact, leading to a transition from DMT to JKR-type behavior. The interaction of PDMAEMA with a hydrophobic dodecanethiol tip at high pH has also been shown to follow JKR mechanics.¹⁵ In fact, the interaction between PDMAEMA and a hydrophilic silicon nitride tip follows DMT behavior at low pH, so there is consistency between these results and those presented previously.¹⁵

The adhesion of a PMAA-coated tip with PDMAEMA brushes with the tip follows a different pattern, reaching a maximum at pH = 6. A comparison between the respective maximum adhesion results for the PMAA- and PDMAEMA-coated tips allows some conclusions on the relative roles of hydrophobic and electrostatic interactions and noncovalent bonding.

To summarize the results, the following situations are categorized: oppositely charged polyelectrolyte brushes, uncharged polyelectrolyte brushes, similarly charged polyelectrolyte brushes, and brushes whereby one component is charged.

The oppositely charged brushes (PMAA–PDMAEMA) exhibit a maximum adhesion (pull-off force) of 7.4 nN (Figure 5), whereas when both brushes are uncharged (PDMAEMA–PDMAEMA) this is 8.6 nN. In the former case, attractions between opposite electrostatic charges are likely to contribute to the adhesive interaction, but in the latter case, there are no attractive electrostatic interactions and the attractive interactions are largely hydrophobic.

When both polymers have the same charge, a lubricious system with an adhesion of 0.13 nN is observed, which is smaller than any of the results for the PMAA–PDMAEMA system. This small adhesion between the two polycations can only be due to hydrogen bonding or van der Waals interactions. When only one of the components is charged, the adhesion is also weak. This is important because it indicates that hydrogen bonding is not significant in this case.

Hydrogen bonding cannot be considered a possible candidate for the interaction between the two PDMAEMA brushes at high pH because there is no suitable donor group available. Hydrogen bonding is possible between the two polycationic brushes at low pH, when the protonation provides a suitable donor moiety, but the weak pull-off force suggests that it is not contributing significantly. If hydrogen bonding is not contributing to the adhesion in the PDMAEMA–PDMAEMA case, it is perhaps reasonable to conclude that the adhesion between the oppositely charged (PMAA and PDMAEMA) brushes is dominated by electrostatic interactions. In principle, hydrogen bonding is possible over the entire range of pH for the oppositely charged brushes, although if it were significant, the adhesive pull-off force would not decrease as the extremes of pH were approached (Figure 5). Certainly, the repulsive interaction at pH 12 (Figure 4b) is incompatible with hydrogen bonding. However, neutral and charged polymers can exhibit pH-induced reversible adhesion, as has already been demonstrated for the interaction between a poly(acrylic acid) brush and a hydrogel of poly(*N,N*-dimethylacrylamide).²²

The contact mechanics can be presented in the context of the transition parameter, which is plotted in Figure 8. JKR behavior ($\alpha = 1$) is here associated with large adhesion and DMT behavior with smaller adhesion. Linear friction–load behavior (not shown in Figure 8) occurs when adhesion is weak and the area-dependent shear term in eq 5 is small. It is generally the case that DMT behavior is associated with stiff systems. Stiffness is of course relative and perhaps should be compared to the adhesive forces between the surfaces. This is the approach of Tabor, who pointed out that the height of the adhesive neck (i.e., the extension of the contact between adhesive systems as they are pulled apart) should scale as⁶²

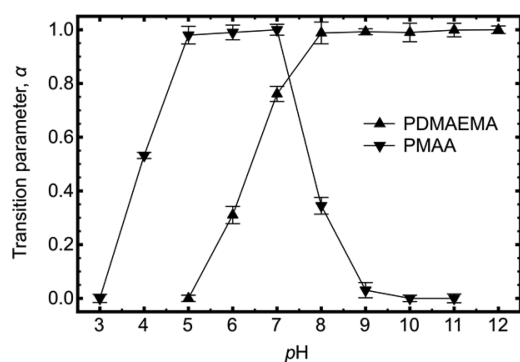


Figure 8. Transition parameter for the PDMAEMA- and PMAA-coated tips with a PDMAEMA surface as a function of pH.

$$h_n \approx \left(\frac{R\gamma^2}{K^2} \right)^{1/3} \quad (7)$$

503

504 In the present case, therefore stiffness may also be taken to
 505 mean weak adhesion. The cause of the stiffness may be taken to
 506 be the solvation of the brush and the weak adhesion due to the
 507 resultant osmotic pressure. A collapsed polymer excluding
 508 solvent is also expected to be stiff, but PDMAEMA is relatively
 509 hydrophilic and is expected to retain some water (although the
 510 data in Figure 1 indicate that the amount of water absorbed by
 511 the polymer at high pH cannot be large),⁵⁷ and so it is
 512 unsurprising perhaps that JKR behavior is observed at high pH
 513 for the PDMAEMA-coated tip interacting with the PDMAEMA
 514 planar surface. At high pH, PMAA is extended, and so DMT
 515 behavior is observed in the interaction with PDMAEMA.

5. CONCLUSIONS

516 The contact mechanics of polycations and polyanions grafted to
 517 an AFM tip with a planar polycationic brush surface have been
 518 measured using friction force microscopy. Adhesive interactions
 519 demonstrate that the greatest interactions are between the same
 520 polycations at high pH and a polycation and polyanion at
 521 intermediate pH. The weak interactions between the two
 522 polycations at low pH allow the conclusion that hydrogen and
 523 van der Waals bonding is largely responsible for the adhesion
 524 and electrostatic interactions for the adhesion between
 525 oppositely charged polyelectrolytes. The contact mechanics
 526 behavior observed for these polyelectrolyte brush systems can
 527 be rationalized by treating the friction force as the sum of an
 528 area-dependent shear term and a load-dependent plowing term.
 529 For highly solvated polycationic brushes, electrostatic repul-
 530 sions reduce adhesion. Plowing dominates, and the shear term
 531 is negligible. As the pH is increased, the polymer becomes less
 532 solvated, leading to an increase in the area of contact as the
 533 osmotic pressure decreases. As the degree of solvation
 534 decreases, the strength of adhesion increases, leading to a
 535 transition from behavior consistent with DMT mechanics to
 536 behavior that is fitted by JKR theory. For brushes with
 537 dissimilar charges, adhesion reaches a maximum around neutral
 538 pH, when electrostatic attractions also reach a maximum.

539 ■ ASSOCIATED CONTENT

540 ● Supporting Information

541 The Supporting Information is available free of charge on the
 542 ACS Publications website at DOI: 10.1021/acs.macro-
 543 mol.5b01540.

XPS characterization of PMAA brushes (PDF) 544

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549 Notes

The authors declare no competing financial interest. 550

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