# The large-time development of the solution to an initial-value problem for the generalized Burgers equation 

Leach, John

## DOI:

10.1093/qjmam/hbw006

License:
Creative Commons: Attribution-NonCommercial-NoDerivs (CC BY-NC-ND)

## Document Version

Peer reviewed version
Citation for published version (Harvard):
Leach, J 2016, 'The large-time development of the solution to an initial-value problem for the generalized Burgers equation', Quarterly Journal of Mechanics and Applied Mathematics.
https://doi.org/10.1093/qjmam/hbw006

Link to publication on Research at Birmingham portal

## Publisher Rights Statement:

This is a pre-copyedited, author-produced PDF of an article accepted for publication in Quarterly Journal of Mechanics and Applied Mathematics following peer review. The version of record J. A. Leach, The large-time development of the solution to an initial-value problem for the generalised burgers' equation, Q J Mechanics Appl Math 2016 : hbw006v1-hbw006 is available online at:
http://qjmam.oxfordjournals.org/content/early/2016/06/07/qjmam.hbw006.abstract

## General rights

Unless a licence is specified above, all rights (including copyright and moral rights) in this document are retained by the authors and/or the copyright holders. The express permission of the copyright holder must be obtained for any use of this material other than for purposes permitted by law.

> -Users may freely distribute the URL that is used to identify this publication.
> -Users may download and/or print one copy of the publication from the University of Birmingham research portal for the purpose of private study or non-commercial research.
> -User may use extracts from the document in line with the concept of 'fair dealing' under the Copyright, Designs and Patents Act 1988 (?)
> -Users may not further distribute the material nor use it for the purposes of commercial gain.
> Where a licence is displayed above, please note the terms and conditions of the licence govern your use of this document.
> When citing, please reference the published version.

## Take down policy

While the University of Birmingham exercises care and attention in making items available there are rare occasions when an item has been uploaded in error or has been deemed to be commercially or otherwise sensitive.
If you believe that this is the case for this document, please contact UBIRA@lists.bham.ac.uk providing details and we will remove access to the work immediately and investigate.

# The large-time development of the solution to an initial-value problem for the generalized Burgers' equation. 

J.A. Leach<br>School of Mathematics, University of Birmingham, Edgbaston, Birmingham, B15 2TT, U.K.

April 11, 2016


#### Abstract

In this paper, we consider an initial-value problem for the generalized Burgers' equation. The normalized Burgers' equation considered is given by $$
u_{t}+t^{\delta} u u_{x}=u_{x x}, \quad-\infty<x<\infty, \quad t>0
$$ where $-\frac{1}{2} \leq \delta \neq 0$, and $x$ and $t$ represent dimensionless distance and time respectively. In particular, we consider the case when the initial data has a discontinuous step, where $u(x, 0)=u_{+}$for $x \geq 0$ and $u(x, 0)=u_{-}$for $x<0$, where $u_{+}$and $u_{-}$are problem parameters with $u_{+} \neq u_{-}$. The method of matched asymptotic coordinate expansions is used to obtain the large- $t$ asymptotic structure of the solution to this problem, which exhibits a range of large- $t$ attractors depending on the problem parameters. Specifically, the solution of the initial-value problem exhibits the formation of (i) an expansion wave when $\delta>-\frac{1}{2}$ and $u_{+}>u_{-}$, (ii) a Taylor shock (hyperbolic tangent) profile when $\delta>-\frac{1}{2}$ and $u_{+}<u_{-}$, and (iii) the Rudenko-Soluyan similarity solution when $\delta=-\frac{1}{2}$.


## 1 Introduction

In this paper we consider the following initial-value problem for the variable coefficient Burgers' equation, namely,

$$
\begin{align*}
u_{t}+t^{\delta} u u_{x} & =u_{x x},  \tag{1.1}\\
u(x, 0) & = \begin{cases}u_{-}, & x<0 \\
u_{+}, & x \geq 0\end{cases}  \tag{1.2}\\
u(x, t) & \rightarrow\left\{\begin{array}{ll}
u_{-}, & x \rightarrow-\infty, \\
u_{+}, & x \rightarrow \infty,
\end{array} \quad t \geq 0\right. \tag{1.3}
\end{align*}
$$

where $u_{-}, u_{+}\left(\neq u_{-}\right)$and $\delta$ are problem parameters, and the initial distribution (1.2) is a discontinuous step. In what follows we label initial-value problem (1.1)-(1.3) as IVP. We will develop the large-time asymptotic solution to IVP for $-\frac{1}{2} \leq \delta \neq 0$ in both the expansive case when $u_{+}>u_{-}$and the compressive case when $u_{+}<u_{-}$.

The variable coefficient Burgers' equation

$$
\begin{equation*}
u_{t}+\Phi(t) u u_{x}=\Psi(t) u_{x x} \tag{1.4}
\end{equation*}
$$

is related to the generalized Burgers' equation

$$
\begin{equation*}
v_{\tau}+v v_{x}+f(\tau) v=v_{x x} \tag{1.5}
\end{equation*}
$$

where $f(\tau)=\frac{\mathrm{d}}{\mathrm{d} \tau} \ln \left(\frac{\Psi}{\Phi}\right)$, via the transformation

$$
\begin{equation*}
v(x, \tau)=\frac{\Phi(t)}{\Psi(t)} u(x, t), \quad \tau=\int^{t} \Psi(s) \mathrm{d} s . \tag{1.6}
\end{equation*}
$$

When $f(\tau)=0$ equation (1.5) reduces to the classical Burgers' equation. Although this equation is named after J.M. Burgers for his work on the theory of turbulence [3], the equation had already appeared in the works of A.R Forsyth [11] and H. Bateman [2] which preceded Burgers work on turbulence. Burgers' equation is a canonical equation combining diffusion and nonlinear convection and as such arises in the modelling of many physical phenomena involving diffusion-convection processes ([27], [5], [23] and [13]). It can be reduced to the heat equation by the Cole-Hopf transformation ([5] and [13]) and then solved in a straightforward manner.

The generalized Burgers' equation (1.5) has many applications in mathematical physics and was introduced in [14]. For example, equation (1.5) models the propagation of finite-amplitude sound waves in variable area ducts ([8], [10], [21] and [24]). We note that equation (1.4) where the coefficient of $u_{x x}$ alone is a function of time, given by

$$
\begin{equation*}
u_{t}+u u_{x}=\Psi(t) u_{x x} \tag{1.7}
\end{equation*}
$$

was introduced in [19] as a model of viscous effects in sound waves of finite amplitude, and derived in [12] as a model for the propagation of weakly nonlinear acoustic waves under the impact of geometrical spreading. J.F. Scott in [24] examined the large-time asymptotics of an initial value for (1.7) having continuous initial data $u(x, 0)=u_{0}(x)$ such that $u_{0}(x) \rightarrow u_{ \pm}$as $x \rightarrow \pm \infty$. He identified three cases:
(i) if $\Psi(t) / t \rightarrow \infty$ as $t \rightarrow \infty$ (supercylindrical case), then the solution, $u(x, t)$, of the initial value problem tends to an error function as $t \rightarrow \infty$.
(ii) if $\Psi(t) / t \rightarrow$ constant as $t \rightarrow \infty$ (cylindrical case), then the solution, $u(x, t)$, of the initial value problem tends to the Rudenko-Soluyan similarity solution [22] as $t \rightarrow \infty$.
(iii) if $\Psi(t) / t \rightarrow 0$ as $t \rightarrow \infty$ (subcylindrical case), then the solution, $u(x, t)$, of the initial value problem tends to an expansion wave when $u_{+}>u_{-}$or a Taylor Shock profile when $u_{+}<u_{-}$, as $t \rightarrow \infty$

It should be noted that in many applications (see for example, [25] and [7]) the coefficient of $u_{x x}, \Psi(t)$, is regularly approximated by a constant. The basis for this assumption often arises from the fact that diffusivity is only needed in thin shock regions (see [19]). However, it was pointed out by D.G. Crighton in [6] that shocks when they occur may not be thin, and in such cases one needs to consider the full time dependent effective viscosity, $\Psi(t)$. This class of generalized Burgers' equations have also been analyzed using the similarity method (see for example, [9] and [4]). The generalized Burgers' equation (1.5) is therefore central to the study of a number of applications. However, it has been established in [20] that there is no Bäcklund transformation for the generalized Burgers' equation (1.5), and hence it is doubtful that a linearizing transformation like the Cole-Hopf transformation exists in this case. Therefore, other methods of solution need to be investigated for this important class of equation.

Our interest in equation (1.1) is motivated by its relationship, via transformation (1.6), to the generalized Burgers' equation (1.5). However, as we shall see it is more convenient for the analysis presented in this paper to work with equation (1.1) rather than equation (1.5). In a recent paper [15] the large-time solution of an initial value problem for (1.4) with continuous initial data $u(x, 0)=u_{0}(x)$, where $u_{0}(x) \rightarrow u_{ \pm}$as $x \rightarrow \pm \infty$, was examined in the two cases

|  | $u_{+}<u_{-}$ | $u_{+}>u_{-}$ |
| :---: | :---: | :---: |
| $\delta>-\frac{1}{2}$ | Taylor Shock | Expansion Wave |
| $\delta=-\frac{1}{2}$ | Rudenko-Soluyan Similarity Solution |  |

Table 1: The type of large-time attractor connecting $u_{+}$to $u_{-}$in the solution of IVP as $t \rightarrow \infty$.
(i) $\Phi(t)=e^{t}, \quad \Psi(t)=1$,
(ii) $\Phi(t)=1, \quad \Psi(t)=e^{t}$.

We note that case (i) corresponds to equation (1.5) with $f(\tau)=\frac{1}{\tau}$, while case (ii) corresponds to equation (1.5) with $f(\tau)=-1$. As in [15], in this present paper we use the method of matched asymptotic coordinate expansions (see for example [28], [16], [17] and [18]) to obtain the complete large-time solution of IVP over all parameter values. We observe that equation (1.1) corresponds to equation (1.5) with $f(\tau)=\frac{\lambda}{\tau}$ (where $\lambda$ is a constant), where $\delta=-\frac{\lambda}{\lambda+1}(\in(-1, \infty))$. We note that $\delta=-\frac{1}{2}$ corresponds to Scott's cylindrical case, while $\delta>-\frac{1}{2}$ corresponds to Scott's sub-cylindrical case. Throughout we use the nomenclature of the method of matched asymptotic expansions, as given in [28]. We note that the initial data (1.2) is a discontinuous step and we place a restriction on the parameter $\delta$, in this analysis we consider $\delta \geq-\frac{1}{2}$ and examine the cylindrical and sub-cylindrical cases. The large-time structure of the solution of the initial-value problem is obtained by careful consideration of the asymptotic structures as $t \rightarrow 0(-\infty<x<\infty)$ and as $|x| \rightarrow \infty(t \geq O(1))$. The form of the large-time attractor for the solution, $u(x, t)$, of IVP as $t \rightarrow \infty$ depends on the problem parameters $u_{+}, u_{-}$and $\delta$, and is summarized in Table 1. Complete details of the large-time solution of IVP in each case are given in Section 2 with a summary of the main results being given in Section 3. The results presented are in agreement with Scott's results above for continuous initial data. However, they extend Scott's results by linking the initial data (through the asymptotic structures developed for $t \rightarrow 0(-\infty<x<\infty)$ and as $|x| \rightarrow \infty(t \geq O(1)))$ to the large-time attractor for the solution of IVP as $t \rightarrow \infty$. In particular, in the case when $\delta>-\frac{1}{2}$ and $u_{+}>u_{-}$ Scott postulated that the solution to IVP would approach the Talyor shock profile as $t \rightarrow \infty$, but was unable to determine the location of the wave-front (see equation (5.27) of [24]). In this paper we establish in this case that the solution to IVP approaches the Taylor shock profile as $t \rightarrow \infty$, and that the wave-front of this Taylor shock is located at $x=s(t)$ as $t \rightarrow \infty$, where $s(t)$ is given by (3.1).

Finally, to make the results presented in this paper readily accessible to equation (1.4) with $\Phi(t)=t^{\kappa}(-1<\kappa \neq 0)$ and $\Psi(t)=t^{\omega}(-1<\omega \neq 0)$ we note that equation (1.4) can when $\kappa \neq \omega$ be transformed to equation (1.1) (on dropping the over bars) by

$$
u=(\omega+1)^{-\delta} \bar{u}, \quad t=((\omega+1) \bar{t})^{\frac{1}{\omega+1}}
$$

where $\delta=\frac{\kappa-\omega}{\omega+1}(\in(-1, \infty))$.

## 2 Asymptotic solution to IVP as $t \rightarrow \infty$

In this section we develop the asymptotic structure of the solution to IVP as $t \rightarrow \infty$. To achieve this we must begin by examining the asymptotic structure of the solution to IVP as $t \rightarrow 0$.

### 2.1 Asymptotic solution to IVP as $\boldsymbol{t} \rightarrow \mathbf{0}$

Consideration of the initial data (1.2) indicates that the structure of the asymptotic solution to IVP as $t \rightarrow 0$ has three asymptotic regions for $x \in(-\infty, \infty)$, namely,

$$
\left.\begin{array}{lll}
\text { region I: } & x=o(1), & u(x, t)=O(1)  \tag{2.1}\\
\text { region } \mathrm{II}^{+}: & x=O(1)(>0), & u(x, t)=u_{+} \pm o(1) \\
\text { region } \mathrm{II}^{-}: & x=O(1)(<0), & u(x, t)=u_{-} \pm o(1)
\end{array}\right\} \quad \text { as } \quad t \rightarrow 0 .
$$

We first consider region I , in which $x=o(1)$ and $u(x, t)=O(1)$ as $t \rightarrow 0$. To examine region I, we introduce the scaled coordinate $\eta=x t^{-\gamma}=O(1)$ as $t \rightarrow 0$, with $\gamma>0$, and look for an expansion of the form

$$
\begin{equation*}
u(\eta, t)=\bar{u}(\eta)+o(1), \tag{2.2}
\end{equation*}
$$

as $t \rightarrow 0$ with $\eta=O(1)$. On substitution of expansion (2.2) into equation (1.1) (when written in terms of $\eta$ and $t$ ) we find that there are two cases to consider, these being $\delta=-\frac{1}{2}$ and $\delta>-\frac{1}{2}$, in both cases the most structured leading order balance (that balance which retains the most terms at leading order in the resulting differential equation) requires $\gamma=\frac{1}{2}$. At leading order we then obtain

$$
\begin{equation*}
\bar{u}_{\eta \eta}+\frac{\eta}{2} \bar{u}_{\eta}=0 \quad \text { when } \quad \delta>-\frac{1}{2}, \tag{2.3}
\end{equation*}
$$

and

$$
\begin{equation*}
\bar{u}_{\eta \eta}-\bar{u} \bar{u}_{\eta}+\frac{\eta}{2} \bar{u}_{\eta}=0 \quad \text { when } \quad \delta=-\frac{1}{2}, \tag{2.4}
\end{equation*}
$$

where $\eta=O(1)$. Equations (2.3) when $\delta>-\frac{1}{2}$ and (2.4) when $\delta=-\frac{1}{2}$ have to be solved subject to matching with regions $\mathrm{II}^{+}$(as $\eta \rightarrow \infty$ ) and $\mathrm{II}^{-}$(as $\eta \rightarrow-\infty$ ) and initial condition (1.2). This requires in both cases that

$$
\bar{u}(\eta) \rightarrow\left\{\begin{array}{lll}
u_{+} & \text {as } & \eta \rightarrow \infty  \tag{2.5}\\
u_{-} & \text {as } & \eta \rightarrow-\infty
\end{array}\right.
$$

We now consider the cases $\delta>-\frac{1}{2}$ and $\delta=-\frac{1}{2}$ separately.

### 2.1.1 $\quad \delta>-\frac{1}{2}$

The solution to (2.3), (2.5) is readily obtained as

$$
\begin{equation*}
\bar{u}(\eta)=u_{+}+\frac{\left(u_{-}-u_{+}\right)}{2} \operatorname{erfc}\left(\frac{\eta}{2}\right), \quad-\infty<\eta<\infty . \tag{2.6}
\end{equation*}
$$

In summary, when $\delta>-\frac{1}{2}$, we have in region I that $x=O\left(t^{\frac{1}{2}}\right)$ as $t \rightarrow 0$, and that

$$
\begin{equation*}
u(\eta, t)=\left(u_{+}+\frac{\left(u_{-}-u_{+}\right)}{2} \operatorname{erfc}\left(\frac{\eta}{2}\right)\right)+o(1) \tag{2.7}
\end{equation*}
$$

as $t \rightarrow 0$ with $\eta=x t^{-\frac{1}{2}}=O(1)$, and where $\operatorname{erfc}($.$) is the standard complementary$ error function (see [1]). From (2.7) we observe that

$$
u(\eta, t) \sim \begin{cases}u_{+}+\frac{\left(u_{-}-u_{+}\right)}{\eta \sqrt{\pi}} e^{-\frac{\eta^{2}}{4}}+\ldots & \text { as } \quad \eta \rightarrow \infty  \tag{2.8}\\ u_{-}-\frac{\left(u_{-}-u_{+}\right)}{(-\eta) \sqrt{\pi}} e^{-\frac{\eta^{2}}{4}}+\ldots & \text { as } \quad \eta \rightarrow-\infty\end{cases}
$$

As $\eta \rightarrow \infty$ we move into region $\mathrm{II}^{+}$, where $x=O(1)(>0)$ as $t \rightarrow 0$. The form of expansion (2.7) for $\eta \gg 1$ given by (2.8) ${ }_{1}$ suggests that in region $\mathrm{II}^{+}$we write

$$
\begin{equation*}
u(x, t)=u_{+}+\mathcal{S} e^{\phi(x, t)} \tag{2.9}
\end{equation*}
$$

with
$\phi(x, t)= \begin{cases}\phi_{0}(x) t^{-1}+\phi_{1}(x) \ln t+\phi_{2}(x)+o(1) & \text { when } \quad \delta>0, \\ \phi_{0}(x) t^{-1}+\phi_{1}(x) t^{\delta}+\phi_{2}(x) \ln t+\phi_{3}(x)+o(1) & \text { when } \quad-\frac{1}{2}<\delta<0,\end{cases}$
where $x=O(1)(>0)$ as $t \rightarrow 0, \phi_{0}(x)<0$ for $x>0$ and $\mathcal{S}=\operatorname{sign}\left(u_{-}-u_{+}\right)$. On substituting (2.9) (with $(2.10)_{1}$ when $\delta>0$ or $(2.10)_{2}$ when $\left.-\frac{1}{2}<\delta<0\right)$ into equation (1.1) and solving at each order in turn, we find (after matching with (2.7) as $x \rightarrow 0^{+}$) that
$u(x, t)=u_{+}+\left\{\begin{array}{c}\mathcal{S} \exp \left(-\frac{x^{2}}{4 t}+\frac{1}{2} \ln t-\ln x+\ln \left(\frac{\left|u_{-}-u_{+}\right|}{\sqrt{\pi}}\right)+O\left(t^{\delta}\right)\right) \\ \text { when } \delta>0, \\ \mathcal{S} \exp \left(-\frac{x^{2}}{4 t}+\frac{u_{+}}{2(\delta+1)} x t^{\delta}+\frac{1}{2} \ln t-\ln x+\ln \left(\frac{\left|u_{-}-u_{+}\right|}{\sqrt{\pi}}\right)+O\left(t^{2 \delta+1}\right)\right) \\ \text { when }-\frac{1}{2}<\delta<0,\end{array}\right.$
as $t \rightarrow 0$ with $x=O(1)(>0)$, and where $\mathcal{S}=\operatorname{sign}\left(u_{-}-u_{+}\right)$. Finally, we consider region $\mathrm{II}^{-}$, where $x=O(1)(<0)$ as $t \rightarrow 0$. The details regarding region $\mathrm{II}^{-}$follow, after minor modification, those given for region $\mathrm{II}^{+}$above and are not repeated here. In summary, we have in region $\mathrm{II}^{-}$that
$u(x, t)=u_{-}-\left\{\begin{array}{c}\mathcal{S} \exp \left(-\frac{x^{2}}{4 t}+\frac{1}{2} \ln t-\ln (-x)+\ln \left(\frac{\left|u_{-}-u_{+}\right|}{\sqrt{\pi}}\right)+O\left(t^{\delta}\right)\right) \\ \text { when } \delta>0, \\ \mathcal{S} \exp \left(-\frac{x^{2}}{4 t}+\frac{u_{+}}{2(\delta+1)} x t^{\delta}+\frac{1}{2} \ln t-\ln (-x)+\ln \left(\frac{\left|u_{-}-u_{+}\right|}{\sqrt{\pi}}\right)+O\left(t^{2 \delta+1}\right)\right) \\ \text { when } \quad-\frac{1}{2}<\delta<0,\end{array}\right.$
as $t \rightarrow 0$ with $x=O(1)(<0)$, and where $\mathcal{S}=\operatorname{sign}\left(u_{-}-u_{+}\right)$. The asymptotic structure as $t \rightarrow 0$ is now complete in this case, with the expansions in regions $\mathrm{I}, \mathrm{II}^{+}$and $\mathrm{II}^{-}$ providing a uniform approximation to the solution of IVP as $t \rightarrow 0$.

### 2.1.2 $\delta=-\frac{1}{2}$

On making the substitution

$$
\begin{equation*}
\bar{u}=\frac{1}{\sqrt{2}} \Omega, \quad \eta=\sqrt{2} \bar{z} \tag{2.13}
\end{equation*}
$$

equation (2.4) becomes

$$
\begin{equation*}
\Omega_{\bar{z} \bar{z}}-\Omega \Omega_{\bar{z}}+\bar{z} \Omega_{\bar{z}}=0, \quad-\infty<\bar{z}<\infty \tag{2.14}
\end{equation*}
$$

which was analyzed by Rudenko and Soluyan in [22]. It is straightforward to establish (see for example [24] and [22]) that equation (2.14) admits the family of implicit solutions

$$
\left.\begin{array}{l}
\Omega(\bar{z})=\bar{z}-2 F(\xi)  \tag{2.15}\\
\bar{z}=\gamma+\int_{\xi_{0}}^{\xi} \frac{d \xi}{F(\xi)}
\end{array}\right\} \quad \xi \geq \xi_{0}
$$

where,

$$
\begin{equation*}
F(\xi)= \pm\left(\xi-\xi_{0} e^{-2\left(\xi-\xi_{0}\right)}\right)^{\frac{1}{2}} \tag{2.16}
\end{equation*}
$$

and $\gamma, \xi_{0}\left(>-\frac{1}{2}\right)$ are constants. The wave profile $\Omega(\bar{z})$ is bounded with constant boundary conditions as $|\bar{z}| \rightarrow \infty$, and consists of two parts (the plus sign in (2.16) is taken to give $\Omega(\bar{z})$ for $\bar{z} \geq \gamma$, while the negative sign is taken in (2.16) to give $\Omega(\bar{z})$ for $\bar{z} \leq \gamma)$ which smoothly join at $\bar{z}=\gamma$. Further, the wave profile $\Omega(\bar{z})$ is monotonically increasing (decreasing) when $\xi_{0}$ is negative (positive) respectively. The limiting behaviour of (2.15) is given by

$$
\Omega(\bar{z}) \rightarrow \gamma \pm \Delta\left(\xi_{0}\right) \quad \text { as } \quad \bar{z} \rightarrow \pm \infty
$$

with the height of the wave being $2 \Delta\left(\xi_{0}\right)$, where $\Delta\left(\xi_{0}\right)$ can be determined numerically. It was established in [22] that in the limits $\xi_{0} \rightarrow 0, \xi_{0} \rightarrow \infty$ and $\xi_{0} \rightarrow-\frac{1}{2}$ the similarity solution (2.15) approaches an error function, Taylor shock (hyperbolic tangent) profile and expansion wave profile, respectively. In order to satisfy boundary conditions (2.5) we take $\gamma=\frac{\sqrt{2}\left(u_{+}+u_{-}\right)}{2}$, and determine $\xi_{0}$ such that $\Delta\left(\xi_{0}\right)=\frac{\sqrt{2}\left(u_{+}-u_{-}\right)}{2}$. We observe from (2.13) and (2.15) that

$$
\begin{equation*}
\bar{u}(\eta)=u_{+}+O\left(\eta^{-1} \exp \left(-\frac{\eta^{2}}{4}+u_{+} \eta\right)\right) \quad \text { as } \quad \eta \rightarrow \infty \tag{2.17}
\end{equation*}
$$

The corresponding asymptotic form for $\bar{u}(\eta)$ as $\eta \rightarrow-\infty$ follows (2.17) with $u_{+}$replaced by $u_{-}$.

As $\eta \rightarrow \infty$ we move into region $\mathrm{II}^{+}$, where $x=O(1)(>0)$ as $t \rightarrow 0$. The details of region $\mathrm{II}^{+}$in this case follow, after minor modification, those given in Section 2.1.1 and are not repeated here for brevity. Therefore, in region $\mathrm{II}^{+}$we have that

$$
\begin{equation*}
u(x, t)=u_{+}+\mathcal{S}_{0} \exp \left(-\frac{x^{2}}{4 t}+\frac{x u_{+}}{t^{\frac{1}{2}}}+\frac{1}{2} \ln t-\ln x+\ln \left|\mathcal{C}_{R}\right|+o(1)\right) \tag{2.18}
\end{equation*}
$$

as $t \rightarrow 0$ with $x=O(1)(>0)$, where $\mathcal{C}_{R}$ is a constant whose value depends on $\xi_{0}$ and is given by

$$
\mathcal{C}_{R}=2 \xi_{0} e^{2 \xi_{0}-u_{+}^{2}},
$$

and $\mathcal{S}_{0}=\operatorname{sign}\left(\mathcal{C}_{R}\right)$. We note that $\mathcal{C}_{R}<0\left(\mathcal{C}_{R}>0\right)$ when $u_{+}>u_{-}\left(u_{+}<u_{-}\right)$ respectively. Finally, we consider region $\mathrm{II}^{-}$, where $x=O(1)(<0)$ as $t \rightarrow 0$. The details regarding region $\mathrm{II}^{-}$follow, after minor modification, those given in Section 2.1.1 and are not repeated here. In summary, we have in region $\mathrm{II}^{-}$that

$$
\begin{equation*}
u(x, t)=u_{-}-\mathcal{S}_{0} \exp \left(-\frac{x^{2}}{4 t}+\frac{x u_{-}}{t^{\frac{1}{2}}}+\frac{1}{2} \ln t-\ln (-x)+\ln \left|\mathcal{C}_{L}\right|+o(1)\right) \tag{2.19}
\end{equation*}
$$

as $t \rightarrow 0$ with $x=O(1)(>0)$, and where $\mathcal{C}_{L}=\mathcal{C}_{R} \exp \left(u_{+}^{2}-u_{-}^{2}\right)$ is a constant. We note that $\mathcal{C}_{R}=\mathcal{C}_{L}$ when $u_{+}=u_{-}$(the trivial case) or when $u_{+}=-u_{-}$. The asymptotic structure as $t \rightarrow 0$ is now complete in this case, with the expansions in regions $\mathrm{I}, \mathrm{II}^{+}$ and $\mathrm{II}^{-}$providing a uniform approximation to the solution of IVP as $t \rightarrow 0$.

### 2.2 Asymptotic solution to IVP as $|x| \rightarrow \infty$

We now investigate the asymptotic structure of the solution to IVP as $|x| \rightarrow \infty$ with $t=O(1)$. We first determine the structure of the solution to IVP as $x \rightarrow \infty$ with $t=O(1)$. The form of expansions (2.11) (when $\delta>-\frac{1}{2}$ ) and (2.18) (when $\delta=-\frac{1}{2}$ ) of region $\mathrm{II}^{+}$for $x \gg 1$ as $t \rightarrow 0$ suggests that in this region, which we label as region $\mathrm{III}^{+}$, we write

$$
\begin{equation*}
u(x, t)=u_{+}+\mathcal{S} e^{-\Theta(x, t)} \tag{2.20}
\end{equation*}
$$

where

$$
\begin{equation*}
\Theta(x, t)=\theta_{0}(t) x^{2}+\theta_{1}(t) x+\theta_{2}(t) \ln x+\theta_{3}(t)+o(1) \tag{2.21}
\end{equation*}
$$

as $x \rightarrow \infty$ with $t=O(1)$. On substituting (2.20) and (2.21) into equation (1.1) and solving at each order in turn, we find (after matching as $t \rightarrow 0^{+}$with (2.11) when $\delta>-\frac{1}{2}$ or (2.18) when $\delta=-\frac{1}{2}$ ) that
$u(x, t)=u_{+}+\left\{\begin{array}{r}\mathcal{S} \exp \left(-\frac{x^{2}}{4 t}+\frac{u_{+}}{2(\delta+1)} x t^{\delta}-\ln x+\frac{1}{2} \ln t-\frac{u_{+}^{2}}{4(\delta+1)^{2}} t^{2 \delta+1}\right. \\ \left.+\ln \left(\frac{\left|u_{-}-u_{+}\right|}{\sqrt{\pi}}\right)+o(1)\right)^{\text {when }} \delta>-\frac{1}{2}, \\ \mathcal{S}_{0} \exp \left(-\frac{x^{2}}{4 t}+\left(u_{+}\right) x t^{-\frac{1}{2}}-\ln x+\frac{1}{2} \ln t+\ln \left|\mathcal{C}_{R}\right|+o(1)\right) \\ \text { when } \delta=-\frac{1}{2},\end{array}\right.$
as $x \rightarrow \infty$ with $t=O(1)$. Expansion $(2.22)_{1}$ remains uniform for $t \gg 1$ provided that $x \gg \lambda(t)$, but becomes nonuniform when $x=O(\lambda(t))$ as $t \rightarrow \infty$, where

$$
\lambda(t)= \begin{cases}t^{\delta+1}, & \delta>0  \tag{2.23}\\ t, & -\frac{1}{2}<\delta<0\end{cases}
$$

whereas, expansion $(2.22)_{2}$ remains uniform for $t \gg 1$ provided that $x \gg t$, but becomes nonuniform when $x=O(t)$ as $t \rightarrow \infty$. We next investigate the structure of the solution structure to IVP as $x \rightarrow-\infty$ with $t=O(1)$, which we label as region $\mathrm{III}^{-}$. The details in this case follow, after minor modification, those given above and we obtain in region $\mathrm{III}^{-}$that
$u(x, t)=u_{-}-\left\{\begin{array}{r}\mathcal{S} \exp \left(-\frac{x^{2}}{4 t}+\frac{u_{-}}{2(\delta+1)} x t^{\delta}-\ln (-x)+\frac{1}{2} \ln t-\frac{u_{-}^{2}}{4(\delta+1)^{2}} t^{2 \delta+1}\right. \\ \left.+\ln \left(\frac{\left|u_{-}-u_{+}\right|}{\sqrt{\pi}}\right)+o(1)\right) \quad \text { when } \quad \delta>-\frac{1}{2}, \\ \mathcal{S}_{0} \exp \left(-\frac{x^{2}}{4 t}+\left(u_{-}\right) x t^{-\frac{1}{2}}-\ln (-x)+\frac{1}{2} \ln t+\ln \left|\mathcal{C}_{L}\right|+o(1)\right) \\ \text { when } \delta=-\frac{1}{2},\end{array}\right.$
as $x \rightarrow \infty$ with $t=O(1)$. Expansion $(2.24)_{1}$ remains uniform for $t \gg 1$ provided that $x \gg \lambda(t)$, but becomes nonuniform when $x=O(\lambda(t))$ as $t \rightarrow \infty$, where $\lambda(t)$ is given by (2.23). Expansion $(2.24)_{2}$ remains uniform for $t \gg 1$ provided that $x \gg t$, but becomes nonuniform when $x=O(t)$ as $t \rightarrow \infty$.

### 2.3 Asymptotic solution to IVP as $\boldsymbol{t} \rightarrow \infty$

### 2.3.1 $\delta>0$ and $u_{+}>u_{-}$

As $t \rightarrow \infty$, the asymptotic expansions $(2.22)_{1}$ and $(2.24)_{1}$ of regions $\mathrm{III}^{+}(x \rightarrow \infty, t=$ $O(1))$ and $\mathrm{III}^{-}(x \rightarrow-\infty, t=O(1))$, respectively, continue to remain uniform provided $|x| \gg t^{\delta+1}$. However, as already noted, a nonuniformity develops when $|x|=O\left(t^{\delta+1}\right)$. We further note that in this case $\mathcal{S}=-1$. We begin by considering the asymptotic structure as $t \rightarrow \infty$ for $x>0$. To proceed we introduce a new region, region $\mathrm{IV}^{+}$when $x=O\left(t^{\delta+1}\right)$ as $t \rightarrow \infty$. To examine region $\mathrm{IV}^{+}$we introduce the scaled coordinate $y=x t^{-\delta-1}$, where $y=O(1)$ as $t \rightarrow \infty$, and write (as suggested by $\left.(2.22)\right)_{1}$

$$
\begin{equation*}
u(y, t)=u_{+}-e^{-F(y, t)} \tag{2.25}
\end{equation*}
$$

where

$$
\begin{equation*}
F(y, t)=F_{0}(y) t^{2 \delta+1}+F_{1}(y) \ln t+F_{2}(y)+o(1) \tag{2.26}
\end{equation*}
$$

as $t \rightarrow \infty$ with $y=O(1)$, and where $F_{0}(y)>0$. On substituting (2.25) and (2.26) into equation (1.1) (when written in terms of $y$ and $t$ ) and solving at each order in turn, we find (after matching with $(2.22)_{1}$ as $\left.y \rightarrow \infty\right)$ that

$$
\begin{align*}
u(y, t)=u_{+}-\exp & \left(-\frac{1}{4}\left(y-\frac{u_{+}}{\delta+1}\right)^{2} t^{2 \delta+1}-\left(\delta+\frac{1}{2}\right) \ln t\right. \\
& \left.-\ln \left(y-\frac{u_{+}}{\delta+1}\right)+\ln \frac{\left|u_{-}-u_{+}\right|}{\sqrt{\pi}}+o(1)\right) \tag{2.27}
\end{align*}
$$

as $t \rightarrow \infty$ with $y=O(1)\left(\in\left(\frac{u_{+}}{\delta+1}, \infty\right)\right)$. Expansion (2.27) becomes nonuniform when $y=\frac{u_{+}}{\delta+1}+O\left(t^{-\delta}\right)$ as $t \rightarrow \infty$. To proceed we introduce a localized region, region $\mathrm{V}^{+}$. To investigate region $\mathrm{V}^{+}$we introduce the scaled coordinate $\eta$ via

$$
\begin{equation*}
\eta=\left(y-\frac{u_{+}}{\delta+1}\right) t^{\delta} \tag{2.28}
\end{equation*}
$$

as $t \rightarrow \infty$ with $\eta=O(1)$, and look for an expansion of the form (as suggested by (2.27))

$$
\begin{equation*}
u(\eta, t)=u_{+}-e^{-\hat{F}(\eta, t)} \tag{2.29}
\end{equation*}
$$

where

$$
\begin{equation*}
\hat{F}(\eta, t)=\hat{F}_{0}(\eta) t+\hat{F}_{1}(\eta) \ln t+\hat{F}_{2}(\eta)+o(1) \tag{2.30}
\end{equation*}
$$

as $t \rightarrow \infty$ with $\eta=O(1)$, and where $\hat{F}_{0}(\eta)>0$. On substituting (2.29) and (2.30) into equation (1.1) (when written in terms of $\eta$ and $t$ ) and solving at each order in turn, we find (after matching with (2.27) as $\eta \rightarrow \infty$ ) that

$$
\begin{equation*}
u(\eta, t)=u_{+}-\exp \left(-\frac{\eta^{2}}{4} t-\frac{1}{2} \ln t+\hat{H}^{+}(\eta)+o(1)\right) \tag{2.31}
\end{equation*}
$$

as $t \rightarrow \infty$ with $\eta=O(1)$, and where the function $\hat{H}^{+}:(0, \infty) \rightarrow \mathbb{R}$ is undetermined being a remnant of the global evolution when $t=O(1)$, but having

$$
\hat{H}^{+}(\eta) \sim-\ln \eta+\ln \frac{\left|u_{-}-u_{+}\right|}{\sqrt{\pi}} \quad \text { as } \quad \eta \rightarrow \infty
$$

Expansion (2.31) becomes nonuniform when $\eta=O\left(t^{-\frac{1}{2}}\right)$ as $t \rightarrow \infty$ [that is, when $y=\frac{u_{+}}{\delta+1}+O\left(t^{-\delta-\frac{1}{2}}\right)$ as $\left.t \rightarrow \infty\right]$. Therefore, we must now introduce a second localized region $\mathrm{VI}^{+}$in which $y=\frac{u_{+}}{\delta+1}+O\left(t^{-\delta-\frac{1}{2}}\right)$ as $t \rightarrow \infty$. Thus we write

$$
\begin{equation*}
y=\frac{u_{+}}{\delta+1}+\xi t^{-\delta-\frac{1}{2}} \tag{2.32}
\end{equation*}
$$

in region $\mathrm{VI}^{+}$, with $\xi=O(1)$ as $t \rightarrow \infty$. It follows from (2.32), (2.28) and expansion (2.31) in region $\mathrm{V}^{+}$, that we should expand as

$$
\begin{equation*}
u(\xi, t)=u_{+}+\phi(t) G(\xi)+o(\phi(t)) \quad \text { as } \quad t \rightarrow \infty \tag{2.33}
\end{equation*}
$$

with $\xi=O(1)$, and the gauge function $\phi(t)=o(1)$ as $t \rightarrow \infty$ is to be determined. On substituting (2.33) into equation (1.1) (when written in terms of $\xi$ and $t$ ) we obtain

$$
\begin{equation*}
\phi^{\prime}(t) G-\frac{\xi}{2} G_{\xi} \frac{\phi(t)}{t}+\phi^{2}(t) t^{\delta-\frac{1}{2}} G G_{\xi}=\frac{\phi(t)}{t} G_{\xi \xi} . \tag{2.34}
\end{equation*}
$$

A nontrivial balance requires

$$
\phi^{2}(t) t^{\delta-\frac{1}{2}} \sim \frac{\phi(t)}{t} \quad \text { as } \quad t \rightarrow \infty
$$

and so, without loss of generality, we take,

$$
\begin{equation*}
\phi(t)=t^{-\delta-\frac{1}{2}} \tag{2.35}
\end{equation*}
$$

We observe that all terms in (2.34) are retained at leading order as $t \rightarrow \infty$ and (2.34) becomes

$$
\begin{equation*}
G_{\xi \xi}-G G_{\xi}+\frac{\xi}{2} G_{\xi}+\left(\delta+\frac{1}{2}\right) G=0, \quad-\infty<\xi<\infty \tag{2.36}
\end{equation*}
$$

We note that equation (2.36) admits the solution $G(\xi)=(\delta+1) \xi$. We further note that when $\delta=0$ equation (2.36) can be integrated to give a solvable Riccati equation and the general solution of (2.36) then obtained. However, for $-\frac{1}{2}<\delta(\neq 0)$ we have been unable to obtain the general solution of (2.36) in closed form. For completeness we observe that when $\delta=-\frac{1}{2}$ equation (2.36) reduces to the equation analyzed by Rudenko and Soluyan in [22], and which we will return to in Section 2.3.4. Therefore, in this case, when $\delta>0$, we will in what follows have to examine equation (2.36)
numerically. Now, matching expansion (2.31) (as $\eta \rightarrow 0^{+}$) with expansion (2.33) (as $\xi \rightarrow \infty)$ requires first that

$$
\begin{equation*}
\hat{H}^{+}(\eta) \sim 2 \delta \ln \eta+\ln \beta \quad \text { as } \quad \eta \rightarrow 0^{+} \tag{2.37}
\end{equation*}
$$

where $\beta(>0)$ is a constant to be determined, after which we require that

$$
\begin{equation*}
G(\xi) \sim-\beta \xi^{2 \delta} e^{-\frac{\xi^{2}}{4}} \quad \text { as } \quad \xi \rightarrow \infty \tag{2.38}
\end{equation*}
$$

Finally for $u$ to remain bounded as $t \rightarrow \infty$ when $y=\frac{u_{+}}{\delta+1}-O(1)$ then we require,

$$
\begin{equation*}
\xi^{-1} G(\xi) \quad \text { bounded as } \quad \xi \rightarrow-\infty \tag{2.39}
\end{equation*}
$$

The leading order problem is now complete, and is given by (2.36), (2.38) and (2.39). The boundary value problem (2.36)-(2.39) is both nonlinear and nonautonomous and there are two parameters $\delta$ (fixed) and $\beta(>0)$. A numerical study of initial-value problem (2.36) and (2.38) using a shooting method reveals that there exists a value $\beta=\beta^{*}$ such that boundary condition (2.39) is satisfied for each $\beta \in\left(0, \beta^{*}\right]$, whilst for each $\beta \in\left(\beta^{*}, \infty\right)$ the solution blows up at finite- $\xi$, say $\xi=\xi_{0}(\beta)$, with

$$
\begin{equation*}
G(\xi) \sim-\frac{2}{\left(\xi-\xi_{0}(\beta)\right)} \quad \text { as } \quad \xi \rightarrow \xi_{0}(\beta)^{+} \tag{2.40}
\end{equation*}
$$

Hence, boundary value problem (2.36), (2.38) and (2.39) has a unique solution for each $\beta \in\left(0, \beta^{*}\right]$ but no solution for $\beta \in\left(\beta^{*}, \infty\right)$. In particular, we have
(i) $0<\beta<\beta^{*}$ : A unique solution exists for each $\beta \in\left(0, \beta^{*}\right)$, say $G(\xi)=G_{N}(\xi)$, $-\infty<\xi<\infty$. Moreover, $G_{N}(\xi) \rightarrow 0^{+}$as $\xi \rightarrow-\infty$.
(ii) $\beta=\beta^{*}$ : A unique solution exits, say $G(\xi)=G^{*}(\xi),-\infty<\xi<\infty$. Moreover, $G^{*}(\xi)$ is monotone increasing with $-\infty<\xi<\infty$, so that $G^{*}(\xi)<0$ for all $\xi \in(-\infty, \infty)$ and

$$
\begin{equation*}
G^{*}(\xi)=(\delta+1) \xi+O\left((-\xi)^{-\frac{1}{2 \delta+1}}\right) \quad \text { as } \quad \xi \rightarrow-\infty \tag{2.41}
\end{equation*}
$$

A graph of $G(\xi)$ against $\xi$ illustrating solutions to (2.36) and (2.38) for representative values of the parameter $\beta$ in the ranges $\beta^{*}<\beta<\infty, 0<\beta<\beta^{*}$ and $\beta=\beta^{*}$ are shown in Figure 1. Thus we have two distinct cases to consider, namely, when (i) $\beta \in\left(0, \beta^{*}\right)$ or when (ii) $\beta=\beta^{*}$. However, we can reject case (i) as this choice leads to an asymptotic structure which fails to match to the far field $(2.24)_{1}$ as $y \rightarrow-\infty$, the details of which are omitted for brevity. We conclude that we require

$$
\beta=\beta^{*}
$$

and that $G(\xi)=G^{*}(\xi)$ for $\xi \in(-\infty, \infty)$.
As $\xi \rightarrow-\infty$ we move out of region $\mathrm{VI}^{+}$into region EW where $y=O(1)(\in$ $\left.\left(-\infty, \frac{u_{+}}{\delta+1}\right)\right)$. We have from (2.33), (2.35) and (2.41) that

$$
\begin{equation*}
u(\xi, t)=u_{+}+(\delta+1) \xi t^{-\delta-\frac{1}{2}}+O\left(t^{-\delta-\frac{1}{2}}(-\xi)^{-\frac{1}{2 \delta+1}}\right) \tag{2.42}
\end{equation*}
$$

as $t \rightarrow \infty$ with $-\xi \gg 1$. On writing in terms of $y$ we obtain that

$$
\begin{equation*}
u(y, t) \sim(\delta+1) y \tag{2.43}
\end{equation*}
$$

suggesting that in region EW that we look for an expansion of the form

$$
\begin{equation*}
u(y, t)=P(y)+o(1) \tag{2.44}
\end{equation*}
$$



Figure 1: A graph of $G(\xi)$ against $\xi$ illustrating solutions to $(2.36)$ for $\delta=1$. We note that the dashed line represents the solution $G(\xi)=(\delta+1) \xi$.
as $t \rightarrow \infty$ with $y=O(1)\left(\in\left(-\infty, \frac{u_{+}}{\delta+1}\right)\right)$. On substitution of expansion (2.44) into equation (1.1) (when written in terms of $y$ and $t$ ) we obtain at leading order that

$$
\begin{equation*}
P_{y}(P-(\delta+1) y)=0, \quad-\infty<y<\frac{u_{+}}{\delta+1} \tag{2.45}
\end{equation*}
$$

Equation (2.45) is to be solved subject to the matching condition with region $\mathrm{VI}^{+}$, that is

$$
\begin{equation*}
P(y) \sim(\delta+1) y \quad \text { as } \quad y \rightarrow\left(\frac{u_{+}}{\delta+1}\right)^{-} \tag{2.46}
\end{equation*}
$$

The solution of (2.45), (2.46) is readily obtained as

$$
\begin{equation*}
P(y)=(\delta+1) y, \quad-\infty<y<\frac{u_{+}}{\delta+1} \tag{2.47}
\end{equation*}
$$

Therefore, in region EW we have that

$$
\begin{equation*}
u(y, t)=(\delta+1) y+o(1) \tag{2.48}
\end{equation*}
$$

as $t \rightarrow \infty$ with $y=O(1)\left(\in\left(-\infty, \frac{u_{+}}{\delta+1}\right)\right)$.
We next consider the asymptotic structure of IVP as $t \rightarrow \infty$ for $x<0$. To proceed we introduce a new region, region $\mathrm{IV}^{-}$. The details of this region follow those given for region $\mathrm{IV}^{+}$and are not repeated here. In region $\mathrm{IV}^{-}$we have that

$$
\begin{align*}
u(y, t)=u_{-}+\exp & \left(-\frac{1}{4}\left(y-\frac{u_{-}}{\delta+1}\right)^{2} t^{2 \delta+1}-\left(\delta+\frac{1}{2}\right) \ln t\right. \\
& \left.-\ln \left(\frac{u_{-}}{\delta+1}-y\right)+\ln \frac{\left|u_{-}-u_{+}\right|}{\sqrt{\pi}}+o(1)\right) \tag{2.49}
\end{align*}
$$

as $t \rightarrow \infty$ with $y=O(1)\left(\in\left(-\infty, \frac{u_{-}}{\delta+1}\right)\right)$. Expansion (2.49) becomes nonuniform when $y=\frac{u_{-}}{\delta+1}+O\left(t^{-\delta}\right)$ as $t \rightarrow \infty$, and to continue the asymptotic structure in this
case we introduce the localized region, region $\mathrm{V}^{-}$. The details of region $\mathrm{V}^{-}$follow, after minor modification, those given for region $\mathrm{V}^{+}$and are summarized here for brevity. In region $\mathrm{V}^{-}$we have that

$$
\begin{equation*}
u(\hat{\eta}, t)=u_{-}+\exp \left(-\frac{\hat{\eta}^{2}}{4} t-\frac{1}{2} \ln t+\hat{H}^{-}(\hat{\eta})+o(1)\right) \tag{2.50}
\end{equation*}
$$

as $t \rightarrow \infty$ with $\hat{\eta}=\left(y-\frac{u_{-}}{\delta+1}\right) t^{\delta}=O(1)$, and where the function $\hat{H}^{-}:(-\infty, 0) \rightarrow \mathbb{R}$ is undetermined (being a remnant of the global evolution when $t=O(1)$ ), but having

$$
\hat{H}^{-}(\hat{\eta}) \sim-\ln (-\hat{\eta})+\ln \frac{\left|u_{-}-u_{+}\right|}{\sqrt{\pi}} \quad \text { as } \quad \hat{\eta} \rightarrow-\infty
$$

Expansion (2.31) becomes nonuniform when $\hat{\eta}=O\left(t^{-\frac{1}{2}}\right)$ as $t \rightarrow \infty$ [that is, when $y=\frac{u_{-}}{\delta+1}+O\left(t^{-\delta-\frac{1}{2}}\right)$ as $\left.t \rightarrow \infty\right]$, and to complete the asymptotic structure in this case we introduce a final localized region, region $\mathrm{VI}^{-}$. The details of region $\mathrm{VI}^{-}$follow those given for region $\mathrm{VI}^{+}$and are summarized here for brevity. In region $\mathrm{VI}^{+}$we look for an expansion of the form (as suggested by (2.50))

$$
\begin{equation*}
u(\xi, t)=u_{-}+G(\xi) t^{-\delta-\frac{1}{2}}+o\left(t^{-\delta-\frac{1}{2}}\right) \tag{2.51}
\end{equation*}
$$

as $t \rightarrow \infty$ with $\xi=\left(y-\frac{u_{-}}{\delta+1}\right) t^{\delta+\frac{1}{2}}=O(1)$. On substitution of expansion (2.51) into equation (1.1) (when written in terms of $\xi$ and $t$ ) we obtain at leading order

$$
\begin{equation*}
G_{\xi \xi}-G G_{\xi}+\frac{\xi}{2} G_{\xi}+\left(\delta+\frac{1}{2}\right) G=0, \quad-\infty<\xi<\infty . \tag{2.52}
\end{equation*}
$$

We first observe that differential equation (2.52) is invariant under the transformation

$$
G(\xi)=-G(-\xi)
$$

Further, equation (2.52) is to be solved subject to the matching condition with region EW, that is

$$
\begin{equation*}
G(\xi) \sim(\delta+1) \xi \quad \text { as } \quad \xi \rightarrow \infty \tag{2.53}
\end{equation*}
$$

Therefore, we select the unique solution $G(\xi)=-G^{*}(-\xi)$ (see region $\mathrm{VI}^{+}$above for details of $\left.G^{*}(\xi)\right)$ when $\beta=\beta^{*}$, with $G^{*}(\xi)<0$ for all $\xi \in(-\infty, \infty)$ [that is, $G(\xi)>0$ for all $\xi \in(-\infty, \infty)$. Specifically, we have that

$$
G(\xi) \sim \begin{cases}(\delta+1) \xi & \text { as } \quad \xi \rightarrow \infty  \tag{2.54}\\ \beta^{*}(-\xi)^{2 \delta} e^{-\frac{\xi^{2}}{4}} & \text { as } \quad \xi \rightarrow-\infty\end{cases}
$$

Finally, matching expansion (2.50) (as $\hat{\eta} \rightarrow 0^{-}$) with expansion (2.51) (as $\xi \rightarrow-\infty$ ) requires that

$$
\hat{H}_{-}(\hat{\eta}) \sim 2 \delta \ln (-\hat{\eta})+\ln \beta^{*} \quad \text { as } \quad \hat{\eta} \rightarrow 0^{-}
$$

and completes region $\mathrm{VI}^{+}$. On returning to region EW we established that

$$
\begin{equation*}
u(y, t)=(\delta+1) y+o(1) \tag{2.55}
\end{equation*}
$$

as $t \rightarrow \infty$ with $y=O(1)\left(\in\left(\frac{u_{-}}{\delta+1}, \frac{u_{+}}{\delta+1}\right)\right)$.
The asymptotic structure of IVP as $t \rightarrow \infty$ when $\delta>0$ and $u_{+}>u_{-}$is now complete. A uniform approximation has been given through regions $\mathrm{III}^{ \pm}, \mathrm{IV}^{ \pm}, \mathrm{V}^{ \pm}, \mathrm{VI}^{ \pm}$ and EW. A schematic representation of the location and thickness of the asymptotic regions as $t \rightarrow \infty$ is given for in Figure 2. The large-t attractor for the solution of IVP in this case is the expansion wave which allows for the adjustment of the solution from $u_{+}$to $u_{-}$.


Figure 2: A schematic representation of the asymptotic structure of $u(y, t)$ in the $(y, u)$ plane as $t \rightarrow \infty$ for IVP when $\delta>0$ and $u_{+}>u_{-}$. We recall that in this case $y=x t^{-\delta-1}$.

### 2.3.2 $\delta>0$ and $u_{+}<u_{-}$

We now investigate the asymptotic structure of IVP as $t \rightarrow \infty$ when $u_{+}<u_{-}$. As $t \rightarrow$ $\infty$, the asymptotic expansions $(2.22)_{1}$ and $(2.24)_{1}$ of regions $\mathrm{III}^{+}(x \rightarrow \infty, t=O(1))$ and $\mathrm{III}^{-}(x \rightarrow-\infty, t=O(1))$, respectively, continue to remain uniform provided $|x| \gg t^{\delta+1}$. However, as already noted, a nonuniformity develops when $|x|=O\left(t^{\delta+1}\right)$. As in Section 2.3.1 we introduce the scaled coordinate $y=x t^{-\delta-1}=O(1)$ as $t \rightarrow \infty$ and note in this case that $\mathcal{S}=+1$. We begin by summarizing the asymptotic structure as $t \rightarrow \infty$ in regions $\mathrm{IV}^{+}$and $\mathrm{IV}^{-}$(the details follow those given in Section 2.3.1 and are not repeated here):

Region IV $^{+}$

$$
\begin{align*}
u(y, t)=u_{+}+\exp & \left(-\frac{1}{4}\left(y-\frac{u_{+}}{\delta+1}\right)^{2} t^{2 \delta+1}-\left(\delta+\frac{1}{2}\right) \ln t\right.  \tag{2.56}\\
& \left.-\ln \left(y-\frac{u_{+}}{\delta+1}\right)+\ln \frac{\left|u_{-}-u_{+}\right|}{\sqrt{\pi}}+o(1)\right)
\end{align*}
$$

as $t \rightarrow \infty$ with $y=O(1)\left(\in\left(\frac{u_{+}}{\delta+1}, \infty\right)\right)$.
Region IV ${ }^{-}$

$$
\begin{align*}
& u(y, t)=u_{-}- \exp  \tag{2.57}\\
&\left(-\frac{1}{4}\left(y-\frac{u_{-}}{\delta+1}\right)^{2} t^{2 \delta+1}-\left(\delta+\frac{1}{2}\right) \ln t\right. \\
&\left.-\ln \left(\frac{u_{-}}{\delta+1}-y\right)+\ln \frac{\left|u_{-}-u_{+}\right|}{\sqrt{\pi}}+o(1)\right)
\end{align*}
$$

as $t \rightarrow \infty$ with $y=O(1)\left(\in\left(-\infty, \frac{u_{-}}{\delta+1}\right)\right)$.
Since $u_{+}<u_{-}$expansions (2.56) and (2.57) must become nonuniform as $y \rightarrow \alpha$, where $\alpha \in\left(u_{+}, u_{-}\right)$and is to be determined. To examine this region which we label
as region SS we introduce the scaled coordinate

$$
\begin{equation*}
z=(y-\alpha) \psi^{-1}=O(1) \tag{2.58}
\end{equation*}
$$

where $\psi(t)=o(1)$ as $t \rightarrow \infty$, is an as yet undetermined gauge function, and expand in the form (as suggested by (2.56) and (2.57))

$$
\begin{equation*}
u(z, t)=U(z)+o(1) \tag{2.59}
\end{equation*}
$$

as $t \rightarrow \infty$ with $z=O(1)$. On substituting (2.59) into equation (1.1) (when written in terms of $z$ and $t$ ) we find that to obtain the most structured leading order balance that we require

$$
\begin{equation*}
\psi(t)=t^{-2 \delta-1} \tag{2.60}
\end{equation*}
$$

At leading order we then obtain

$$
\begin{equation*}
U_{z z}-U U_{z}+\alpha(\delta+1) U_{z}=0, \quad-\infty<z<\infty \tag{2.61}
\end{equation*}
$$

On integrating (2.61) we obtain

$$
\begin{equation*}
U_{z}=\frac{U^{2}}{2}-\alpha(\delta+1) U+C, \quad-\infty<z<\infty \tag{2.62}
\end{equation*}
$$

where $C$ is a constant of integration. Equation (2.62) is to be solved subject to the leading order matching conditions

$$
U(z) \sim\left\{\begin{array}{lll}
u_{+} & \text {as } & z \rightarrow \infty  \tag{2.63}\\
u_{-} & \text {as } & z \rightarrow-\infty
\end{array}\right.
$$

The solution to (2.62) subject to boundary conditions (2.63) requires that

$$
\alpha=\frac{\left(u_{+}+u_{-}\right)}{2(\delta+1)} \quad \text { and } \quad C=\frac{u_{+} u_{-}}{2},
$$

and is given by the Taylor shock profile (see [26] and [27])

$$
\begin{equation*}
U(z)=\frac{\left(u_{+}+u_{-}\right)}{2}-\frac{\left(u_{-}-u_{+}\right)}{2} \tanh \left(\frac{\left(u_{-}-u_{+}\right)}{4} z+\phi_{c}\right), \quad-\infty<z<\infty \tag{2.64}
\end{equation*}
$$

where $\phi_{c}$ is a constant. G.I. Taylor obtained (2.64) in [26] for the structure of a weak thermoviscous shock. We note that

$$
U(z) \sim\left\{\begin{array}{lll}
u_{+}+\left(u_{-}-u_{+}\right) \exp \left(-\frac{\left(u_{-}-u_{+}\right)}{2} z-\phi_{c}\right) & \text { as } & z \rightarrow \infty  \tag{2.65}\\
u_{-}-\left(u_{-}-u_{+}\right) \exp \left(\frac{\left(u_{-}-u_{+}\right)}{2} z+\phi_{c}\right) & \text { as } & z \rightarrow-\infty
\end{array}\right.
$$

The similarity solution (2.64) represents a monotone decreasing wavefront connecting $u_{-}\left(>u_{+}\right)$to $u_{+}$. The wavefront is located at $x=\frac{\left(u_{+}+u_{-}\right)}{2(\delta+1)} t^{\delta+1}$ and is contained within a region of thickness $x=O\left(t^{-\delta}\right)$ as $t \rightarrow \infty$. The wavefront is steepening as $t \rightarrow \infty$ and has an accelerating velocity as $t \rightarrow \infty$ when $u_{+} \neq-u_{-}$, but is located at $x=0$ and is stationary when $u_{+}=-u_{-}$. In particular, when $u_{+}>-u_{-}$the wavefront is accelerating in the $+x$ direction, whereas when $u_{+}<-u_{-}$the wavefront is accelerating in the $-x$ direction.

Although expansion (2.59) ( $\left.\operatorname{with}(2.65)_{1}\right)$ as $z \rightarrow \infty$ matches with expansion (2.56) as $y \rightarrow \alpha^{+}$at leading order matching fails at next order and we require a transition region, which we label $\mathrm{TR}^{+}$. This failure in matching is indicative of the fact that expansion (2.56) will become nonuniform as $y \rightarrow(\alpha+\omega)^{+}$(where $\omega>0$ is a constant to be determined), and region $\mathrm{TR}^{+}$will be required to allow the solution in region
$\mathrm{IV}^{+}$(where $\left.u=u_{+}+o(1)\right)$ to adjust to the solution in region SS (where $u=O(1)$ ). To examine region $\mathrm{TR}^{+}$we introduce the scaled coordinate $\eta$ by

$$
\begin{equation*}
z=c(t)+\eta \tag{2.66}
\end{equation*}
$$

where

$$
\begin{equation*}
c(t)=\frac{\left(u_{-}-u_{+}\right)}{4(\delta+1)(2 \delta+1)} t^{2 \delta+1}+\frac{2(\delta+1)}{\left(u_{-}-u_{+}\right)} \ln t \tag{2.67}
\end{equation*}
$$

as $t \rightarrow \infty$ with $\eta=O(1)$, and look for an expansion of the form

$$
\begin{align*}
u(\eta, t)=u_{+} & +F(\eta) t^{-\delta-1} \exp \left(-\frac{\left(u_{-}-u_{+}\right)^{2}}{8(\delta+1)(2 \delta+1)} t^{2 \delta+1}\right) \\
& +o\left(t^{-\delta-1} \exp \left(-\frac{\left(u_{-}-u_{+}\right)^{2}}{8(\delta+1)(2 \delta+1)} t^{2 \delta+1}\right)\right) \tag{2.68}
\end{align*}
$$

as $t \rightarrow \infty$ with $\eta=O(1)$. On substituting expansion (2.68) into equation (1.1) (when written in terms of $\eta$ and $t$ ) we obtain at leading order that

$$
\begin{equation*}
F_{\eta \eta}+\frac{\left(u_{-}-u_{+}\right)(2 \delta+3)}{4(\delta+1)} F_{\eta}+\frac{\left(u_{-}-u_{+}\right)^{2}}{8(\delta+1)} F=0, \quad-\infty<\eta<\infty \tag{2.69}
\end{equation*}
$$

Equation (2.69) has to be solved subject to the matching conditions with regions $\mathrm{IV}^{+}$ and SS , that is

$$
F(\eta) \sim \begin{cases}\frac{2(\delta+1)}{\sqrt{\pi}} \exp \left(-\frac{\left(u_{-}-u_{+}\right)}{4(\delta+1)} \eta\right) & \text { as } \quad \eta \rightarrow \infty  \tag{2.70}\\ \left(u_{-}-u_{+}\right) e^{-\phi_{c}} \exp \left(-\frac{\left(u_{-}-u_{+}\right)}{2} \eta\right) & \text { as } \eta \rightarrow-\infty\end{cases}
$$

The solution of (2.69) subject to (2.70) is readily obtained as

$$
\begin{equation*}
F(\eta)=\frac{2(\delta+1)}{\sqrt{\pi}} \exp \left(-\frac{\left(u_{-}-u_{+}\right)}{4(\delta+1)} \eta\right)+\left(u_{-}-u_{+}\right) e^{-\phi_{c}} \exp \left(-\frac{\left(u_{-}-u_{+}\right)}{2} \eta\right) \tag{2.71}
\end{equation*}
$$

where $-\infty<\eta<\infty$. Therefore, the expansion in region $\mathrm{TR}^{+}$is given by (2.68) with (2.71).

Finally, we conclude this case by noting that matching expansion (2.59) (as $z \rightarrow$ $-\infty$ ) to expansion (2.57) (as $y \rightarrow \alpha^{-}$) fails and we require a final transition region, which we label $\mathrm{TR}^{-}$. To examine region $\mathrm{TR}^{-}$we introduce the scaled coordinate $\hat{\eta}$ by

$$
\begin{equation*}
y=-c(t)+\hat{\eta} \tag{2.72}
\end{equation*}
$$

as $t \rightarrow \infty$ with $\hat{\eta}=O(1)$, where $c(t)$ is given by (2.67), and look for an expansion of the form

$$
\begin{align*}
u(\hat{\eta}, t)=u_{-} & -F(\hat{\eta}) t^{-\delta-1} \exp \left(-\frac{\left(u_{-}-u_{+}\right)^{2}}{8(\delta+1)(2 \delta+1)} t^{2 \delta+1}\right)  \tag{2.73}\\
& +o\left(t^{-\delta-1} \exp \left(-\frac{\left(u_{-}-u_{+}\right)^{2}}{8(\delta+1)(2 \delta+1)} t^{2 \delta+1}\right)\right)
\end{align*}
$$

as $t \rightarrow \infty$ with $\hat{\eta}=O(1)$. On substituting expansion (2.73) into equation (1.1) (when written in terms of $\hat{\eta}$ and $t$ ) we obtain at leading order that

$$
\begin{equation*}
F_{\hat{\eta} \hat{\eta}}-\frac{\left(u_{-}-u_{+}\right)(2 \delta+3)}{4(\delta+1)} F_{\hat{\eta}}+\frac{\left(u_{-}-u_{+}\right)^{2}}{8(\delta+1)} F=0, \quad-\infty<\hat{\eta}<\infty . \tag{2.74}
\end{equation*}
$$

Equation (2.74) has to be solved subject to the matching conditions with regions IV $^{-}$ and SS, that is

$$
F(\hat{\eta}) \sim \begin{cases}\frac{2(\delta+1)}{\sqrt{\pi}} \exp \left(\frac{\left(u_{-}-u_{+}\right)}{4(\delta+1)} \hat{\eta}\right) & \text { as } \quad \hat{\eta} \rightarrow-\infty  \tag{2.75}\\ \left(u_{-}-u_{+}\right) e^{\phi_{c}} \exp \left(\frac{\left(u_{--} u_{+}\right)}{2} \hat{\eta}\right) & \text { as } \hat{\eta} \rightarrow \infty\end{cases}
$$



Figure 3: A schematic representation of the asymptotic structure of $u(y, t)$ in the $(y, u)$ plane as $t \rightarrow \infty$ for IVP when $u_{+}<u_{-}$. We recall that region SS is located at $y=\frac{u_{+}+u_{-}}{2(\delta+1)}$ (with thickness $O\left(t^{-2 \delta-1}\right)$ as $t \rightarrow \infty$ ), while regions $\mathrm{TR}^{ \pm}$are located at $y=\frac{\left(u_{-}+u_{+}\right)}{2(\delta+1)} \pm \frac{\left(u_{-}-u_{+}\right)}{4(\delta+1)(2 \delta+1)} \pm \frac{2(\delta+1)}{\left(u_{-}-u_{+}\right)} \frac{\ln t}{t^{2 \delta+1}}$ (with thickness $O\left(t^{-2 \delta-1}\right)$ ) as $t \rightarrow \infty$.

The solution of (2.74) subject to (2.75) is readily obtained as

$$
\begin{equation*}
F(\hat{\eta})=\frac{2(\delta+1)}{\sqrt{\pi}} \exp \left(\frac{\left(u_{-}-u_{+}\right)}{4(\delta+1)} \hat{\eta}\right)+\left(u_{-}-u_{+}\right) e^{\phi_{c}} \exp \left(\frac{\left(u_{-}-u_{+}\right)}{2} \hat{\eta}\right) \tag{2.76}
\end{equation*}
$$

where $-\infty<\hat{\eta}<\infty$. Therefore, the expansion in region $\mathrm{TR}^{-}$is given by (2.73) with (2.76).

The asymptotic structure of the solution of IVP as $t \rightarrow \infty$ when $u_{+}<u_{-}$is now complete. A uniform approximation has been given through regions $\mathrm{III}^{ \pm}, \mathrm{IV}^{ \pm}, \mathrm{TR}^{ \pm}$ and SS. A schematic representation of the location and thickness of the asymptotic regions as $t \rightarrow \infty$ is given in Figure 3. The large-t attractor for the solution of IVP when $u_{+}>u_{-}$is the Taylor shock profile which allows for the adjustment of the solution form $u_{+}$to $u_{-}$.

### 2.3.3 $-\frac{1}{2}<\delta<0$

As $t \rightarrow \infty$, the asymptotic expansion $(2.22)_{1}$ and $(2.24)_{1}$ of regions $\mathrm{III}^{+}(x \rightarrow \infty, t=$ $O(1))$ and $\mathrm{III}^{-}(x \rightarrow-\infty, t=O(1))$, respectively, continue to remain uniform provided $|x| \gg t$. However, as already noted, a nonuniformity develops when $|x|=O(t)$, We begin by considering the asymptotic structure as $t \rightarrow \infty$ for $x>0$. To proceed we introduce a new region, region $\mathrm{IV}^{+}$when $x=O(t)$ as $t \rightarrow \infty$. To examine region $\mathrm{IV}^{+}$ we introduce the scaled coordinate $\varphi=x t^{-1}$, where $\varphi=O(1)$ as $t \rightarrow \infty$, and write (as suggested by $(2.22))_{1}$

$$
\begin{equation*}
u(\varphi, t)=u_{+}+\mathcal{S} e^{-G(\varphi, t)} \tag{2.77}
\end{equation*}
$$

where

$$
\begin{equation*}
G(\varphi, t)=G_{0}(\varphi) t+G_{1}(\varphi) t^{\delta+1}+G_{2}(\varphi) t^{2 \delta+1}+G_{3}(\varphi) \ln t+G_{4}(\varphi)+o(1) \tag{2.78}
\end{equation*}
$$

as $t \rightarrow \infty$ with $\varphi=O(1)$, and where $G_{0}(\varphi)>0$ and $\mathcal{S}=\operatorname{sign}\left(u_{-}-u_{+}\right)$. On substituting (2.77) and (2.78) into equation (1.1) (when written in terms of $\varphi$ and $t$ )
and solving at each order in turn, we find (after matching with (2.22) as $\varphi \rightarrow \infty$ ) that

$$
\begin{array}{r}
u(\varphi, t)=u_{+}+\mathcal{S} \exp \left(-\frac{1}{4} \varphi^{2} t+\frac{u_{+}}{2(\delta+1)} \varphi t^{\delta+1}-\frac{u_{+}^{2}}{4(\delta+1)^{2}} t^{2 \delta+1}-\frac{1}{2} \ln t\right. \\
\left.+H^{+}(\varphi)+o(1)\right) \tag{2.79}
\end{array}
$$

as $t \rightarrow \infty$ with $\varphi=O(1)$, and where the function $H^{+}:(0, \infty) \rightarrow \mathbb{R}$ is undetermined (being a remnant of the global evolution when $t=O(1)$ ), but having

$$
H^{+}(\varphi) \sim-\ln \varphi+\ln \frac{\left|u_{-}-u_{+}\right|}{\sqrt{\pi}} \quad \text { as } \quad \varphi \rightarrow \infty
$$

Expansion (2.79) becomes nonuniform when $\varphi=O\left(t^{\delta}\right)$ as $t \rightarrow \infty$ [that is, when $x=O\left(t^{\delta+1}\right)$ as $t \rightarrow \infty$ ]. To proceed we relabel region $\mathrm{IV}^{+}$as region $\operatorname{IV}(\mathrm{a})^{+}$, and introduce a new region, region $\operatorname{IV}(\mathrm{b})^{+}$when $\varphi=O\left(t^{\delta}\right)$ as $t \rightarrow \infty$. To investigate region $\operatorname{IV}(\mathrm{b})^{+}$we introduce the scaled coordinate $y$ via

$$
y=\varphi t^{-\delta}=x t^{-\delta-1}
$$

where $y=O(1)$ as $t \rightarrow \infty$, and expand in the form

$$
\begin{equation*}
u(y, t)=u_{+}+\mathcal{S} e^{-F(y, t)} \tag{2.80}
\end{equation*}
$$

where

$$
\begin{equation*}
F(y, t)=F_{0}(y) t^{2 \delta+1}+F_{1}(y) \ln t+F_{2}(y)+o(1) \tag{2.81}
\end{equation*}
$$

as $t \rightarrow \infty$ with $y=O(1)$, and where $F_{0}(y)>0$ and $\mathcal{S}=\operatorname{sign}\left(u_{-} u_{+}\right)$. On substituting (2.80) and (2.81) into equation (1.1) (when written in terms of $y$ and $t$ ) and solving at each order in turn, we find (after matching with (2.79) as $y \rightarrow \infty$ ) that

$$
\begin{equation*}
u(y, t)=u_{+}+\mathcal{S} \exp \left(-\frac{1}{4}\left(y-\frac{u_{+}}{\delta+1}\right)^{2} t^{2 \delta+1}-\frac{1}{2} \ln t+\lambda+o(1)\right) \tag{2.82}
\end{equation*}
$$

as $t \rightarrow \infty$ with $y=O(1)\left(\in\left(\frac{u_{+}}{\delta+1}, \infty\right)\right)$, and where $\lambda$ is a constant. We note that matching expansion (2.80) ( $y \rightarrow \infty$ ) with expansion (2.79) $\left(\varphi \rightarrow 0^{+}\right)$requires that

$$
H^{+}(\varphi) \sim \lambda \quad \text { as } \quad \varphi \rightarrow 0^{+}
$$

We next consider the asymptotic structure of IVP as $t \rightarrow \infty$ for $x<0$. To proceed we introduce a new region, region $\operatorname{IV}(\mathrm{a})^{-}$. The details of this region follow those given for region $\operatorname{IV}(\mathrm{a})^{+}$and are not repeated here. In region $\operatorname{IV}(\mathrm{a})^{-}$we have that

$$
\begin{array}{r}
u(\hat{\varphi}, t)=u_{-}-\mathcal{S} \exp \left(-\frac{1}{4} \hat{\varphi}^{2} t+\frac{u_{-}}{2(\delta+1)} \hat{\varphi} t^{\delta+1}-\frac{u_{-}^{2}}{4(\delta+1)^{2}} t^{2 \delta+1}-\frac{1}{2} \ln t\right. \\
\left.+H^{-}(\hat{\varphi})+o(1)\right) \tag{2.83}
\end{array}
$$

as $t \rightarrow \infty$ with $\hat{\varphi}=\frac{x}{t}=O(1)$, and where the function $H^{-}:(-\infty, 0) \rightarrow \mathbb{R}$ is undetermined (being a remnant of the global evolution when $t=O(1)$ ), but having

$$
H^{-}(\hat{\varphi}) \sim-\ln (-\hat{\varphi})+\ln \frac{\left|u_{-}-u_{+}\right|}{\sqrt{\pi}} \quad \text { as } \quad \hat{\varphi} \rightarrow-\infty
$$

Expansion (2.83) becomes nonuniform when $\hat{\varphi}=O\left(t^{\delta}\right)$ as $t \rightarrow \infty$ [that is, when $-x=O\left(t^{\delta+1}\right)$ as $t \rightarrow \infty$ ]. To proceed we introduce a new region, region $\operatorname{IV}(\mathrm{b})^{-}$ when $\hat{\varphi}=O\left(t^{\delta}\right)$ as $t \rightarrow \infty$. The details of region $\operatorname{IV}(\mathrm{b})^{-}$follow those given for region $\operatorname{IV}(\mathrm{b})^{+}$above. Therefore, in region $\operatorname{IV}(\mathrm{b})^{-}$we have that

$$
\begin{equation*}
u(y, t)=u_{-}-\mathcal{S} \exp \left(-\frac{1}{4}\left(y-\frac{u_{-}}{\delta+1}\right)^{2} t^{2 \delta+1}-\frac{1}{2} \ln t+\hat{\lambda}+o(1)\right) \tag{2.84}
\end{equation*}
$$

as $t \rightarrow \infty$ with $y=\hat{\varphi} t^{-\delta}=O(1)\left(\in\left(-\infty, \frac{u_{-}}{\delta+1}\right)\right)$, and where $\hat{\lambda}$ is a constant. We note that matching expansion $(2.84)(y \rightarrow-\infty)$ with expansion $(2.83)\left(\hat{\varphi} \rightarrow 0^{-}\right)$requires that

$$
H^{-}(\hat{\varphi}) \sim \hat{\lambda} \quad \text { as } \quad \hat{\varphi} \rightarrow 0^{-}
$$

We now need to consider the cases when $u_{+}>u_{-}$and when $u_{+}<u_{-}$separately.
(a) $\boldsymbol{u}_{+}>\boldsymbol{u}_{-}$

The remaining asymptotic structure of the solution to IVP as $t \rightarrow \infty$ in this case follows, after minor modification, that given in Section 2.3.1 for regions $\mathrm{V}^{ \pm}, \mathrm{VI}^{ \pm}$and EW. We note that in this case $\mathcal{S}=-1$. In summary, we have that

Region $\mathrm{V}^{+} . \quad y=\frac{u_{+}}{\delta+1}+O\left(t^{-\delta}\right)$ as $t \rightarrow \infty$

$$
\begin{equation*}
u(\eta, t)=u_{+}-\exp \left(-\frac{\eta^{2}}{4} t-\frac{1}{2} \ln t+\hat{H}^{+}(\eta)+o(1)\right) \tag{2.85}
\end{equation*}
$$

as $t \rightarrow \infty$ with $\eta=\left(y-\frac{u_{+}}{\delta+1}\right)=O(1)$, and where the function $\hat{H}^{+}:(0, \infty) \rightarrow \mathbb{R}$ is undetermined, but having

$$
\hat{H}^{+}(\eta) \sim \begin{cases}\lambda & \text { as } \quad \eta \rightarrow \infty  \tag{2.86}\\ 2 \delta \ln \eta+\ln \beta^{*} & \text { as } \quad \eta \rightarrow 0^{+}\end{cases}
$$

Region $\mathrm{VI}^{+}$.

$$
\begin{align*}
& y=\frac{u_{+}}{\delta+1}+O\left(t^{-\delta-\frac{1}{2}}\right) \text { as } t \rightarrow \infty \\
& \quad u(\xi, t)=u_{+}+G^{*}(\xi) t^{-\delta-\frac{1}{2}}+o\left(t^{-\delta-\frac{1}{2}}\right) \tag{2.87}
\end{align*}
$$

as $t \rightarrow \infty$ with $\xi=\left(y-\frac{u_{+}}{\delta+1}\right) t^{\delta+\frac{1}{2}}=O(1)$, and where $G^{*}(\xi)$ is the solution to boundary value problem (2.36), (2.38) and (2.39) when $\beta=\beta^{*}$. Also,

$$
G^{*}(\xi) \sim \begin{cases}-\beta^{*} \xi^{2 \delta} e^{-\frac{\xi^{2}}{4}} & \text { as } \quad \xi \rightarrow \infty  \tag{2.88}\\ (\delta+1) \xi & \text { as } \xi \rightarrow-\infty\end{cases}
$$

Region EW.

$$
\begin{align*}
y=O(1)\left(\in\left(\frac{u_{-}}{\delta+1}, \frac{u_{+}}{\delta+1}\right)\right) \text { as } t \rightarrow \infty \\
u(y, t)=(\delta+1) y+o(1) \tag{2.89}
\end{align*}
$$

as $t \rightarrow \infty$ with $y=O(1)\left(\in\left(\frac{u_{-}}{\delta+1}, \frac{u_{+}}{\delta+1}\right)\right)$.
Region $\mathrm{VI}^{-} . \quad y=\frac{u_{-}}{\delta+1}+O\left(t^{-\delta-\frac{1}{2}}\right)$ as $t \rightarrow \infty$

$$
\begin{equation*}
u(\xi, t)=u_{-}+G(\xi) t^{-\delta-\frac{1}{2}}+o\left(t^{-\delta-\frac{1}{2}}\right) \tag{2.90}
\end{equation*}
$$

as $t \rightarrow \infty$ with $\xi=\left(y-\frac{u_{-}}{\delta+1}\right) t^{\delta+\frac{1}{2}}=O(1)$, and $G(\xi)=-G^{*}(-\xi)$ where $G^{*}(\xi)$ is the solution to boundary value problem (2.36), (2.38) and (2.39) when $\beta=\beta^{*}$. Also,

$$
G^{*}(\xi) \sim \begin{cases}\beta^{*}(-\xi)^{2 \delta} e^{-\frac{\xi^{2}}{4}} & \text { as } \xi \rightarrow-\infty  \tag{2.91}\\ (\delta+1) \xi & \text { as } \xi \rightarrow \infty\end{cases}
$$

Region $\mathrm{V}^{-} . \quad y=\frac{u_{-}}{\delta+1}+O\left(t^{-\delta}\right)$ as $t \rightarrow \infty$

$$
\begin{equation*}
u(\hat{\eta}, t)=u_{-}+\exp \left(-\frac{\hat{\eta}^{2}}{4} t-\frac{1}{2} \ln t+\hat{H}^{-}(\hat{\eta})+o(1)\right) \tag{2.92}
\end{equation*}
$$

as $t \rightarrow \infty$ with $\hat{\eta}=\left(y-\frac{u_{-}}{\delta+1}\right)=O(1)$, and where the function $\hat{H}^{-}:(-\infty, 0) \rightarrow \mathbb{R}$ is undetermined, but having

$$
\hat{H}^{-}(\hat{\eta}) \sim \begin{cases}\hat{\lambda} & \text { as } \hat{\eta} \rightarrow-\infty  \tag{2.93}\\ 2 \delta \ln (-\hat{\eta})+\ln \beta^{*} & \text { as } \hat{\eta} \rightarrow 0^{-}\end{cases}
$$

The asymptotic structure of the solution of IVP as $t \rightarrow \infty$ when $u_{+}>u_{-}$and $-\frac{1}{2}<\delta<0$ is now complete. A uniform approximation has been given through regions $\mathrm{III}^{ \pm}, \mathrm{IV}(a)^{ \pm}, \mathrm{IV}(\mathrm{b})^{ \pm}, \mathrm{V}^{ \pm}, \mathrm{VI}^{ \pm}$and EW . The large-t attractor for the solution of IVP when $u_{+}>u_{-}$is the expansion wave which allows for the adjustment of the solution form $u_{+}$to $u_{-}$.
(b) $\boldsymbol{u}_{+}<\boldsymbol{u}_{-}$

The remaining asymptotic structure of the solution to IVP as $t \rightarrow \infty$ in this case follows, after minor modification, that given in Section 2.3.2 for regions $\mathrm{TR}^{ \pm}$and SS . We note that $\mathcal{S}=1$. In summary, we have that

Region $\mathrm{TR}^{+} . \quad y=\frac{\left(u_{+}+u_{-}\right)}{2(\delta+1)}+\hat{c}(t) t^{-2 \delta-1}+O\left(t^{-2 \delta-1}\right)$ as $t \rightarrow \infty$

$$
\begin{align*}
u(\eta, t)=u_{+}+ & \left(e^{\lambda} \exp \left[-\frac{\left(u_{-}-u_{+}\right)}{4(\delta+1)} \eta\right]+\left(u_{-}-u_{+}\right) e^{-\phi_{c}} \exp \left[-\frac{\left(u_{-}-u_{+}\right)}{2} \eta\right]\right) \\
& \times t^{-\frac{\delta+1}{2 \delta+1}} \exp \left(-\frac{\left(u_{-}-u_{+}\right)^{2}}{8(\delta+1)(2 \delta+1)} t^{2 \delta+1}\right) \\
& +o\left(t^{-\frac{\delta+1}{2 \delta+1}} \exp \left(-\frac{\left(u_{-}-u_{+}\right)^{2}}{8(\delta+1)(2 \delta+1)} t^{2 \delta+1}\right)\right) \tag{2.94}
\end{align*}
$$

as $t \rightarrow \infty$ with $\eta=\left(y-\frac{\left(u_{-}+u_{+}\right)}{2(\delta+1)}-\hat{c}(t) t^{-2 \delta-1}\right) t^{2 \delta+1}=O(1)$, and where

$$
\begin{equation*}
\hat{c}(t)=\frac{\left(u_{-}-u_{+}\right)}{4(\delta+1)(2 \delta+1)} t^{2 \delta+1}+\frac{2(\delta+1)}{\left(u_{-}-u_{+}\right)(2 \delta+1)} \ln t \tag{2.95}
\end{equation*}
$$

as $t \rightarrow \infty$.
Region SS. $\quad y=\frac{\left(u_{+}+u_{-}\right)}{2(\delta+1)}+O\left(t^{-2 \delta-1}\right)$ as $t \rightarrow \infty$

$$
\begin{equation*}
u(z, t)=\left(\frac{\left(u_{+}+u_{-}\right)}{2}-\frac{\left(u_{-}-u_{+}\right)}{2} \tanh \left(\frac{\left(u_{-}-u_{+}\right)}{4} z+\phi_{c}\right)\right)+o(1) \tag{2.96}
\end{equation*}
$$

as $t \rightarrow \infty$ with $z=\left(y-\frac{\left(u_{+}+u_{-}\right)}{2(\delta+1)}\right) t^{2 \delta+1}=O(1)$, and where $\phi_{c}$ is a constant. The solution (2.96) represents a monotone decreasing wavefront connecting $u_{-}\left(>u_{+}\right)$to
$u_{+}$. The wavefront is located at $x=\frac{\left(u_{+}+u_{-}\right)}{2(\delta+1)} t^{\delta+1}$ and is contained within a region of thickness $x=O\left(t^{-\delta}\right)$ (recall that $-\frac{1}{2}<\delta<0$ in this case) as $t \rightarrow \infty$. The wavefront is stretching as $t \rightarrow \infty$ and has an decelerating velocity as $t \rightarrow \infty$ when $u_{+} \neq-u_{-}$, but is located at $x=0$ and is stationary when $u_{+}=-u_{-}$. In particular, when $u_{+}>-u_{-}$ the wavefront is decelerating in the $+x$ direction, whereas when $u_{+}<-u_{-}$the wavefront is decelerating in the $-x$ direction.

Region $\mathrm{TR}^{-} . \quad y=\frac{\left(u_{+}+u_{-}\right)}{2(\delta+1)}-\hat{c}(t) t^{-2 \delta-1}+O\left(t^{-2 \delta-1}\right)$ as $t \rightarrow \infty$

$$
\begin{align*}
u(\hat{\eta}, t)=u_{-}- & \left(e^{\hat{\lambda}} \exp \left[\frac{\left(u_{-}-u_{+}\right)}{4(\delta+1)} \hat{\eta}\right]+\left(u_{-}-u_{+}\right) e^{\phi_{c}} \exp \left[\frac{\left(u_{-}-u_{+}\right)}{2} \hat{\eta}\right]\right) \\
& \times t^{-\frac{\delta+1}{2 \delta+1}} \exp \left(-\frac{\left(u_{-}-u_{+}\right)^{2}}{8(\delta+1)(2 \delta+1)} t^{2 \delta+1}\right)  \tag{2.97}\\
& +o\left(t^{-\frac{\delta+1}{2 \delta+1}} \exp \left(-\frac{\left(u_{-}-u_{+}\right)^{2}}{8(\delta+1)(2 \delta+1)} t^{2 \delta+1}\right)\right)
\end{align*}
$$

as $t \rightarrow \infty$ with $\hat{\eta}=\left(y-\frac{\left(u_{-}+u_{+}\right)}{2(\delta+1)}+\hat{c}(t) t^{-2 \delta-1}\right) t^{2 \delta+1}=O(1)$, and where $\hat{c}(t)$ is given by (2.95).

The asymptotic structure of the solution of IVP as $t \rightarrow \infty$ when $u_{+}<u_{-}$and $-\frac{1}{2}<\delta<0$ is now complete. A uniform approximation has been given through regions $\mathrm{III}^{ \pm}, \mathrm{IV}(\mathrm{a})^{ \pm}, \mathrm{IV}(\mathrm{b})^{ \pm}, \mathrm{TR}^{ \pm}$and SS. The large-t attractor for the solution of IVP when $u_{+}<u_{-}$is the Taylor shock profile which allows for the adjustment of the solution form $u_{+}$to $u_{-}$.

### 2.3.4 $\delta=-\frac{1}{2}$

As $t \rightarrow \infty$, the asymptotic expansion $(2.22)_{2}$ and $(2.24)_{2}$ of regions $\mathrm{III}^{+}(x \rightarrow \infty, t=$ $O(1))$ and $\mathrm{III}^{-}(x \rightarrow-\infty, t=O(1))$, respectively, continue to remain uniform provided $|x| \gg t$. However, as already noted, a nonuniformity develops when $|x|=O(t)$, We begin by considering the asymptotic structure as $t \rightarrow \infty$ for $x>0$. To proceed we introduce a new region, region $\mathrm{IV}^{+}$when $x=O(t)$ as $t \rightarrow \infty$. To examine region $\mathrm{IV}^{+}$ we introduce the scaled coordinate $y=x t^{-1}$, where $y=O(1)$ as $t \rightarrow \infty$, and write (as suggested by $(2.22))_{2}$

$$
\begin{equation*}
u(y, t)=u_{+}+\mathcal{S}_{0} e^{-F(y, t)} \tag{2.98}
\end{equation*}
$$

where

$$
\begin{equation*}
F(y, t)=F_{0}(y) t+F_{1}(y) t^{\frac{1}{2}}+F_{2}(y) \ln t+F_{3}(y)+o(1) \tag{2.99}
\end{equation*}
$$

as $t \rightarrow \infty$ with $y=O(1)$, and where $F_{0}(y)>0$ and $\mathcal{S}_{0}=\operatorname{sign}\left(\mathcal{C}_{R}\right)$. On substituting (2.98) and (2.99) into equation (1.1) (when written in terms of $y$ and $t$ ) and solving at each order in turn, we find (after matching with $(2.22)_{2}$ as $y \rightarrow \infty$ ) that

$$
\begin{equation*}
u(y, t)=u_{+}+\mathcal{S}_{0} \exp \left(-\frac{1}{4} y^{2} t+\left(u_{+}\right) y t^{\frac{1}{2}}-\frac{1}{2} \ln t+H_{0}(y)+o(1)\right) \tag{2.100}
\end{equation*}
$$

as $t \rightarrow \infty$ with $y=O(1)$, and where the function $H_{0}:(0, \infty) \rightarrow \mathbb{R}$ is undetermined (being a remnant of the global evolution when $t=O(1)$ ), but having

$$
H_{0}(y) \sim-\ln y+\ln \left|\mathcal{C}_{R}\right| \quad \text { as } \quad y \rightarrow \infty
$$

We now make the assumption (which we will verify as consistent) that

$$
H_{0}(y) \sim-\ln y+\beta_{R} \quad \text { as } \quad y \rightarrow 0^{+}
$$

where $\beta_{R}$ is a constant to be determined. Expansion (2.100) becomes nonuniform when $y=O\left(t^{-\frac{1}{2}}\right)$ as $t \rightarrow \infty$ [that is, when $x=O\left(t^{\frac{1}{2}}\right)$ as $t \rightarrow \infty$ ]. To proceed we introduce a new region, region SS when $y=O\left(t^{-\frac{1}{2}}\right)$ as $t \rightarrow \infty$. To investigate region SS we introduce the scaled coordinate $z$ via

$$
z=y t^{\frac{1}{2}}=x t^{-\frac{1}{2}}
$$

where $z=O(1)$ as $t \rightarrow \infty$ and look for an expansion of the form

$$
\begin{equation*}
u(z, t)=U(z)+o(1) \tag{2.101}
\end{equation*}
$$

as $t \rightarrow \infty$ with $z=O(1)$. On substitution of (2.101) into equation (1.1) (when written in terms of $z$ and $t$ ) we obtain at leading order

$$
\begin{equation*}
U_{z z}-U U_{z}+\frac{z}{2} U_{z}=0, \quad-\infty<z<\infty \tag{2.102}
\end{equation*}
$$

Equation (2.102) has to be solved subject to matching with region $\mathrm{IV}^{+}$, that is

$$
\begin{equation*}
U(z) \sim u_{+}+\frac{\mathcal{S}_{0} e^{\beta_{R}}}{z} \exp \left(-\frac{z^{2}}{4}+u_{+} z\right) \quad \text { as } \quad z \rightarrow \infty \tag{2.103}
\end{equation*}
$$

On making the substitution

$$
\begin{equation*}
U=\frac{1}{\sqrt{2}} \Omega, \quad z=\sqrt{2} \bar{z} \tag{2.104}
\end{equation*}
$$

equation (2.102) becomes equation (2.14) of Section 2.1.2, which admits the similarity solution (2.15). Therefore, in region SS we have at leading order in expansion (2.101) the similarity solution of Rudenko and Soluyan which connects $u_{+}$(as $\left.z \rightarrow \infty\right)$ to $u_{-}$ (as $z \rightarrow-\infty$ ). This similarity solution is in a stretching frame of reference of thickness $x=O\left(t^{\frac{1}{2}}\right)$ as $t \rightarrow \infty$. We note that expansion (2.101) then satisfies the matching condition (2.103) and fixes

$$
\beta_{R}=\ln \left|\mathcal{C}_{R}\right| .
$$

We next consider the asymptotic structure as $t \rightarrow \infty$ for $x<0$. To proceed we introduce a new region, region $\mathrm{IV}^{-}$. The details of this region follow, after minor modification, those given for region $\mathrm{IV}^{+}$above and are not repeated here. Therefore, we have in region IV $^{-}$that

$$
\begin{equation*}
u(y, t)=u_{-}-\mathcal{S}_{0} \exp \left(-\frac{1}{4} y^{2} t+\left(u_{-}\right) y t^{\frac{1}{2}}-\frac{1}{2} \ln t+\hat{H}_{0}(y)+o(1)\right) \tag{2.105}
\end{equation*}
$$

as $t \rightarrow \infty$ with $y=O(1)$, and where the function $\hat{H}_{0}:(0, \infty) \rightarrow \mathbb{R}$ is undetermined (being a remnant of the global evolution when $t=O(1)$ ), but having

$$
\hat{H}_{0}(y) \sim-\ln (-y)+\ln \left|\mathcal{C}_{L}\right| \quad \text { as } \quad y \rightarrow \infty
$$

Expansion (2.105) becomes nonuniform when $y=O\left(t^{-\frac{1}{2}}\right)$ as $t \rightarrow \infty$ [that is, when $x=O\left(t^{\frac{1}{2}}\right)$ as $t \rightarrow \infty$. As $y \rightarrow 0^{-}$we move into region SS. Matching expansion (2.105) (as $y \rightarrow 0^{-}$) with expansion (2.101) (as $z \rightarrow-\infty$ ) follows directly, and requires that

$$
\hat{H}_{0}(y) \sim-\ln (-y)+\ln \left|\mathcal{C}_{L}\right| \quad \text { as } \quad y \rightarrow 0^{-} .
$$

The asymptotic structure of the solution to IVP as $t \rightarrow \infty$ when $\delta=-\frac{1}{2}$ is now complete. A uniform approximation has been given through regions $\mathrm{III}^{ \pm}, \mathrm{IV}^{ \pm}$and SS . A schematic representation of the location and thickness of the asymptotic regions as $t \rightarrow \infty$ is given in Figure 4. The large-time attractor for the solution of IVP when $\delta=-\frac{1}{2}$ is the similarity solution of Rudenko and Soluyan which allows for the adjustment of the solution from $u_{+}$to $u_{-}$.


Figure 4: A schematic representation of the asymptotic structure of $u(y, t)$ in the $(y, u)$ plane as $t \rightarrow \infty$ for IVP when $\delta=-\frac{1}{2}$. Here we illustrate the case when $u_{+}<u_{-}$, and recall that $y=\frac{x}{t}$.

## 3 Summary

In this paper we have obtained, via the method of matched asymptotic coordinate expansions, the uniform asymptotic structure of the large-time solution to the initialvalue problem IVP over all parameter values. In each case the large-time structure was obtained by careful consideration of the asymptotic structures as $t \rightarrow 0(-\infty<x<\infty)$ and as $|x| \rightarrow \infty(t \geq O(1))$. The form of the large-time attractor for the solution, $u(x, t)$, of IVP as $t \rightarrow \infty$ depends on the problem parameters, and is summarized in Table 1. Although the large-time attractors described in Table 1 (the Taylor shock, expansion wave and the Rudenko-Soluyan similarity solution) are generic coherent structures associated with equation (1.1), the analysis presented in Section 2 has for the first time allowed these structures to be rationally embedded into the large-time solution of initial-value problem IVP.

The form of the large-time attractor for the solution of initial-value problem IVP depends on the problem parameters $\delta, u_{+}$and $u_{-}$as follows:
(i) When $\delta>-\frac{1}{2}$ and $u_{+}>u_{-}$the solution $u(x, t)$ to IVP exhibits the formation of an expansion wave profile, where

$$
u(x, t) \sim \begin{cases}u_{+}, & x>\frac{u_{+}}{\delta+1} t^{\delta+1} \\ (\delta+1) x t^{-(\delta+1)}, & \frac{u_{-}}{\delta+1} \delta^{\delta+1}<x<\frac{u_{+}}{\delta+1} t^{\delta+1} \\ u_{-}, & x<\frac{u_{-}}{\delta+1} t^{\delta+1}\end{cases}
$$

as $t \rightarrow \infty$. We observe that $u(x, t)=(\delta+1) x t^{-(\delta+1)}$ is the degenerate solution of equation (1.1).
(ii) When $\delta>-\frac{1}{2}$ and $u_{+}<u_{-}$the solution $u(x, t)$ to IVP exhibits the formation of a Taylor shock (hyperbolic tangent) profile, where

$$
\begin{aligned}
u\left(\frac{\left(u_{+}+u_{-}\right)}{2(\delta+1)} t^{\delta+1}+z t^{-\delta}, t\right) & =\left[\frac{\left(u_{+}+u_{-}\right)}{2}\right. \\
-\frac{\left(u_{-}-u_{+}\right)}{2} & \left.\tanh \left(\frac{\left(u_{-}-u_{+}\right)}{4} z+\phi_{c}\right)\right]+o(1)
\end{aligned}
$$

as $t \rightarrow \infty$ with $z=O(1)$, and $\phi_{c}$ is a globally determined constant. It follows that the Taylor shock wave-front is at $x=s(t)$, where

$$
\begin{equation*}
s(t)=\frac{\left(u_{+}+u_{-}\right)}{2(\delta+1)} t^{\delta+1}+c t^{-\delta}+o\left(t^{-\delta}\right) \tag{3.1}
\end{equation*}
$$

as $t \rightarrow \infty$, with $c$ being a globally determined constant. The Taylor shock propagation speed is then

$$
\dot{s}(t)=\frac{\left(u_{+}+u_{-}\right)}{2} t^{\delta}-\delta c t^{-(\delta+1)}+o\left(t^{-(\delta+1)}\right)
$$

as $t \rightarrow \infty$. Therefore, when $u_{+}=-u_{-}$the Taylor shock profile is decelerating as $t \rightarrow \infty$ with $\dot{s}(t)=O\left(t^{-(\delta+1)}\right)$ as $t \rightarrow \infty$, whilst $s(t) \rightarrow 0\left(c t^{|\delta|}\right)$ as $t \rightarrow \infty$ for $\delta>0\left(-\frac{1}{2}<\delta<0\right)$ respectively. In each case the solution to IVP approaches a stationary Taylor shock profile located at $x=0$ and contained in a region of thickness $O\left(t^{-\delta}\right)$ as $t \rightarrow \infty$ (within this region the profile is steepening for $\delta>0$, whereas the profile is stretching for $-\frac{1}{2}<\delta<0$ ). Further, we observe that:
(a) When $\delta>0$ the Taylor shock profile is located at $x=s(t)$ and contained in a localized region of thickness $O\left(t^{-\delta}\right)$ as $t \rightarrow \infty$ (the profile steepens as $t \rightarrow \infty)$. The Taylor shock is accelerating in the $+x(-x)$ direction as $t \rightarrow \infty$ when $u_{+}>-u_{-}\left(u_{+}<-u_{-}\right)$respectively.
(b) When $-\frac{1}{2}<\delta<0$ the Taylor shock profile is located at $x=s(t)$ and contained within a region of thickness $O\left(t^{-\delta}\right)$ as $t \rightarrow \infty$ (the profile becomes stretched $t \rightarrow \infty)$. The Taylor shock is decelerating in the $+x(-x)$ direction as $t \rightarrow \infty$ when $u_{+}>-u_{-}\left(u_{+}<-u_{-}\right)$respectively.
(iii) When $\delta=-\frac{1}{2}$ the solution $u(x, t)$ to IVP exhibits the formation of the similarity solution found by Rudenko and Soluyan [22], and given by (2.15). We observe from Section 2.1.2 that this structure forms in the small-time solution of IVP when $x=O\left(t^{\frac{1}{2}}\right)$ as $t \rightarrow 0$, and that this similarity profile is in a stretching frame of reference of thickness $O\left(t^{\frac{1}{2}}\right)$ as $t \rightarrow \infty$.

## References

[1] M. Abramowitz and I. Stegun Handbook of Mathematical Functions. Dover (1965).
[2] H. Batemann. Some recent researches on the motion of fluids. Monthly Weather Review 43, 163-170 (1915).
[3] J.M. Burgers. A mathematical model illustrating the theory of turbulence. Adv. Appl. Mech. 1, 171-199 (1948).
[4] Q. Changzheng. Allowed transformations and symmetry classes of variable coefficient Burgers equation. IMA J. Appl. Math. 54, 203-225 (1995).
[5] J.D. Cole. On a quasilinear parabolic equation occuring in aerodyamics. Quart. Appl. Math. 9, 225-236 (1951).
[6] D.G. Crighton. Model equations of nonlinear acoustics. Ann. Rev. Mech. 11, 11-33 (1979).
[7] D.G. Crighton. Basic nonlinear acoustics. In: Sette D, editor. Frontiers in physical acoustics. Amsterdam: North-Holland; (1986).
[8] D.G. Crighton and J.F. Scott. Asymptotic solutions of model equations in nonlinear acoustics. Phil. Trans. R. Soc. Lond. A292, 101-134 (1979).
[9] J. Doyle and M.J. Englefield. Similarity solutions of a generalized Burgers equation. IMA J. Appl. Math. 50, 142-152 (1990).
[10] B.O. Enflo and O.V. Rudenko. To the theory of generalized Burgers' equations. Acta Acust 88, 1-8 (2002)
[11] A.R. Forsyth. Theory of Differential Equations Part 4 (Vol. 5-6). Reprinted: Dover, New York (1959).
[12] P.W. Hammerton and D.G. Crighton. Approximate solution methods for nonlinear acoustic propagation over long ranges. Proc. R. Soc. Lond. A 426:125152 (1989).
[13] E. Hopf. The partial differential equation $u_{t}+u u_{x}=\mu u_{x x}$. Comm. Pure Appl. Math. 3, 201-230 (1950).
[14] S. Leibovich and A. R. Seebass (Eds.) Nonlinear waves. Cornell University Press, Ithaca, N.Y.London, 1974.
[15] J.A. Leach. The large-time solution of Burgers' equation with variable coefficients. I. Exponential coefficients. (To appear: Stud. Appl. Math.)
[16] J.A. Leach and D.J. Needham Matched Asymptotic Expansions in ReactionDiffusion Theory. Springer Monographs in Mathematics (2003)
[17] J.A. Leach and D.J. Needham. The large-time development of the solution to an initial-value problem for the Korteweg-de Vries equation: I. Initial data has a discontinous expansive step. Nonlinearity 21 (2008) 2391-2408.
[18] J.A. Leach and D.J. Needham. The large-time development of the solution to an initial-value problem for the Korteweg-de Vries equation: II. Initial data has a discontinous compressive step. Mathematika 60 (2) (2014) 391-414.
[19] M.J. Lighthill. Viscosity effects in sound waves of finite amplitude. In: Surveys in Mechanics. Cambridge University Press, 250-351 (1956).
[20] J.J.C. Nimmo and D.G. Crighton. Bäcklund transformations for nonlinear parabolic equations: The general results. Proc. Roy. Soc. Lond. A384, 381-401 (1982).
[21] J.J.C. Nimmo and D.G. Crighton. Geometrical and diffusive effects in nonlinear acoustic propagation over long ranges. Proc. Roy. Soc. Lond. A320, 1-35 (1986).
[22] O.V. Rudenko and S.I. Soluyan. Theoretical foundations of nonlinear acoustics (English translation by R. T. Beyer). Consultants Bureau, Plenum. (1977).
[23] P.L. Sachdev. Nonlinear diffusive waves. Cambridge University Press, (2009).
[24] J.F. Scott. The long time asymptotics of the solutions to the generalized Burgers equation. Proc. Roy. Soc. Lond. A373, 443-456 (1981).
[25] P.N. Sionoid and A.T. Cates. The generalized Burgers and ZabolotskayaKhokhlov equations: transformations, exact solutions and qualitative properties. Proc. Roy. Soc. Lond. A447,253270 (1994).
[26] G.I. Taylor. The conditions necessary for discontinuous motion in gases. Proc. R. Soc. Lond. A84, 371-377 (1910).
[27] G.B. Whitham. Linear and Nonlinear Waves. Wiley, New York (1974).
[28] M. Van Dyke Perturbation Methods in Fluid Dynamics. Parabolic Press, Stanford, CA, (1975).

