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Impact of magnetic activity on inferred stellar properties of main-sequence Sun-like stars

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ABSTRACT

The oscillation frequencies observed in Sun-like stars are susceptible to being shifted by magnetic activity effects. The measured shifts depend on a complex relationship involving the mode type, the field strength, and spatial distribution of activity, as well as the inclination angle of the star. Evidence of these shifts is also present in frequency separation ratios that are often used when inferring global properties of stars in order to avoid surface effects. However, one assumption when using frequency ratios for this purpose is that there are no near-surface perturbations that are non-spherically symmetric. In this work, we studied the impact on inferred stellar properties when using frequency ratios that are influenced by non-homogeneous activity distributions. We generate several sets of artificial oscillation frequencies with various amounts of shift and determine stellar properties using two separate pipelines. We find that for asteroseismic observations of Sun-like targets we can expect magnetic activity to affect mode frequencies that will bias the results from stellar modelling analysis. Although for most stellar properties this offset should be small, typically less than 0.5 per cent in mass, estimates of age and central hydrogen content can have an error of up to 5 per cent and 3 per cent, respectively. We expect a larger frequency shift and therefore larger bias for more active stars. We also warn that for stars with very high or low inclination angles, the response of modes to activity is more easily observable in the separation ratios and hence will incur a larger bias.

Key words: asteroseismology – stars: activity – stars: fundamental parameters.

1 INTRODUCTION

Sun-like stars with outer convective zones pulsate due to turbulent motion within these layers. These perturbations excite acoustic waves within the star producing a rich spectrum of modes of oscillation that can be studied via asteroseismology to investigate internal stellar physics and determine global properties. Thanks to the high-resolution photometric observations from CoRoT (Baglin et al. 2006), *Kepler* (Borucki et al. 2010; Howell et al. 2014), and more recently *TESS* (Ricker et al. 2015), we have measured acoustic oscillations for thousands of stars.

Surface magnetic activity is known to affect acoustic modes, changing their frequencies, enlarging damping rates, and suppressing amplitudes (e.g. Christensen-Dalsgaard 2002; Chaplin et al. 2007; Metcalfe et al. 2007; Fuller et al. 2015; Kiefer, Broomhall & Ball 2019). Several studies have found evidence of acoustic modes being shifted in frequency, an effect that varies with the 11-yr solar activity cycle (e.g. Woodard & Noyes 1985; Palle, Regulo & Roca Cortes 1989; Elsworth et al. 1990; Howe, Komm & Hill 2002; Chaplin et al. 2007; Broomhall et al. 2014) as well as with a quasi-biennial period (e.g. Fletcher et al. 2010; Broomhall et al. 2012; Simoniello

et al. 2012). Similar behaviour has also been found in other solar-type stars (e.g. García et al. 2010; Salabert et al. 2016; Karoff et al. 2018; Santos et al. 2018). Kiefer & Broomhall (2020) showed that mode frequencies from main sequence and subgiant stars are particularly sensitive to perturbations from magnetic activity. The sizes of frequency shifts tell us about activity related changes in the outer layers of stellar interiors enabling us to probe activity cycles (Kiefer et al. 2017; Santos et al. 2018), and relative sizes of shifts can reveal information about the surface activity distribution (Salabert et al. 2018; Thomas et al. 2019). It is important to account for activity related effects on asteroseismic measurements, since they are often used in stellar modelling or to infer global stellar properties such as mass, age, or radius (see e.g. Chaplin & Basu 2015; Kiefer et al. 2019; Pérez Hernández et al. 2019; Santos et al. 2019).

When modelling stars the description of the near-surface layers is generally incomplete causing a discrepancy between theory and observation. Different techniques have been developed to deal with this (see Section 1); however, generally these assume spherical symmetry within these regions which is not true for magnetic activity. The aim of this work was to determine the impact a non-homogeneous spread of near-surface activity has on the estimates of fundamental stellar properties made by asteroseismic modelling pipelines and in what situations the effect must be considered. Since this is a first attempt to quantify the expected bias due to magnetic

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activity, we considered Sun-like stars since the activity patterns on the Sun are well known. We generated artificial observations for Sun-like stars with various near-surface field strengths and spatial distributions of surface activity. We studied the difference between estimations of stellar models fitted to shifted and non-shifted sets of frequency separation ratios. Comparisons made between these results would reveal the impact of activity. The justification for using separation ratios is explained in Section 2. In Sections 3 and 4, we outline the model used to calculate activity-induced frequency shifts and our process for generating sets of frequencies. Section 5 contains a description of the two stellar modelling pipelines used to infer global properties. Our results are shown in Section 6 followed by discussion and conclusions.

2 USE OF SEPARATION RATIOS

Asteroseismology is a powerful tool to infer fundamental properties of solar-type stars. With long-timebase photometry from, for example, *Kepler* and *TESS*, it is possible to resolve individual modes of oscillation in stellar spectra giving us a window into the inner workings of stars. Asteroseismic modelling pipelines can be used to obtain precise properties of stars using inputs of mode frequencies along with complimentary non-seismic data, typically, but not limited to, effective temperature, metallicity, and luminosity derived using parallaxes. More robust and higher accuracy constraints on stellar properties, including mass, radius and age, are possible with the inclusion of individual mode frequencies, or combinations of frequencies, as opposed to solely using global seismic quantities (e.g. Gai et al. 2011; Lebreton & Goupil 2014; Metcalfe et al. 2014; Reese et al. 2016; Silva Aguirre et al. 2017). Using a set of input physics and evolutionary codes stellar models are computed, either on the fly or to build a predefined grid, where each stellar model corresponds to a combination of properties for a model star. For each model pulsation codes are then used to predict theoretical oscillation frequencies. Theoretical observables, including frequencies and additional non-seismic data, are fit to actual observations to obtain the best matching model and the corresponding stellar properties.

The oscillations are acoustic modes where pressure perturbations drive standing waves within a main sequence star. Spherical harmonics are used to describe the appearance of these modes on a sphere with oscillations usually described by three numbers: the radial order, n , the angular degree, l , and the azimuthal order, m . Solar-like oscillators produce a spectrum of modes, the frequencies of which depend on the star's properties and internal structure. However, for solar-type stars observed by *Kepler* and *TESS*, it is only possible to measure modes with $l \leq 3$ due to geometric cancellation for higher degrees.

When modelling oscillation frequencies there is a known systematic difference between models and observations called the surface effect. This frequency bias is caused by the incomplete modelling of near-surface layers of stars, for example by using approximations such as mixing-length theory, or inadequate modelling of the interactions between oscillations and convection [for more description, see Basu & Kinnane (2018) and references therein]. There are however several methods to allow for this effect. Correction terms have been included to account for the offset (Kjeldsen, Bedding & Christensen-Dalsgaard 2008; Gruberbauer et al. 2013; Ball & Gizon 2014; Sonoi et al. 2015), or the use of an asteroseismic phase to parametrize the frequency-dependent difference between model and observation (Roxburgh 2015).

Another method is to use combinations of frequencies when fitting rather than the individual frequencies themselves. These are known as 'separation ratios' and are useful, since they are roughly independent

of the structure of surface regions of stars, thereby mitigating the impact of the surface effect (Roxburgh & Vorontsov 2003). For this work, we use the r_{02} separation ratio defined as

$$r_{02}(n) = \frac{d_{02}(n)}{\Delta v_1(n)},$$

where

$$\begin{aligned} d_{02}(n) &= v_{n,0} - v_{n-1,2}, \\ \Delta v_1(n) &= v_{n,1} - v_{n-1,1}. \end{aligned} \quad (1)$$

Here, $v_{n,l}$ is the frequency of a mode with radial order n and angular degree l , $d_{02}(n)$ is the small frequency separation between $l = 0$ and $l = 2$ modes, and $\Delta v_1(n)$ is the large frequency separation for $l = 1$ modes. The sensitivity of low- l modes to near-surface conditions is independent of the degree. Therefore, the small separation is already fairly insensitive to surface layers, since it calculates the difference between two modes of very similar frequency that both propagate in the near-surface regions. This sensitivity is reduced even further when taking the ratio of small-to-large separations. Roxburgh & Vorontsov (2003) compared stellar models with the same interior structure but different surface layers to illustrate that frequency ratios are much less sensitive to the poorly-modelled outer layers' conditions. As a result, despite some loss of information when taking ratios, separation ratios can be used to isolate the effects of the deep stellar interior, a key focus for those determining ages and evolutionary states of stars. Due to this sensitivity to central conditions and being almost unaffected by surface regions, Silva Aguirre et al. (2013) argue that more reliable stellar properties can be obtained by using separation ratios rather than oscillation frequencies themselves. Basu & Kinnane (2018) showed that, as long as the surface effect is somehow compensated for when inferring stellar properties from models, then the obtained results are robust.

Nevertheless, one underlying assumption when using frequency ratios is that there are no non-spherically symmetric near-surface perturbations (Oti Floranes, Christensen-Dalsgaard & Thompson 2005), which would induce frequency shifts that depend on the degree of the mode. One example source would be a surface magnetic activity distribution such as that seen on the Sun. The Δv_l are calculated from modes with the same combination of m and l therefore changes in Δv_l due to activity will be negligible. However, d_{02} uses frequencies with different combinations of m and l that occupy different spatial regions on a star and hence experience different size shifts in the presence of non-spherically symmetric magnetic activity. For this reason d_{02} , and hence r_{02} , will carry a signature of magnetic field changes; for example the solar cycle. Chaplin et al. (2005) studied this effect using Sun-as-star observations from BiSON (Chaplin et al. 1996) and measured variations in the ratios with solar activity level. They attribute this change to acoustic asphericity from surface activity and advised that care must be taken to account for biases when using ratios from long data sets. For this reason in this study we use separation ratios when fitting stellar models, avoiding the need for a surface term and we know that any remaining effect will be caused by non-spherically symmetric activity.

3 MODELLING ACTIVITY-INDUCED FREQUENCY SHIFTS

The shift in frequencies due to surface activity will depend not only on the star's magnetic field strength but also the spatial distribution of the activity on the stellar surface. What's more, our ability to observe these shifts will depend on the inclination angle of the star, since this

dictates the mode visibility and hence our ability to observe mode components of different l and m . For this work, we build on the model from Thomas et al. (2019) but summarize the main principles here.

The response of each mode depends on the field strength in the region where the corresponding acoustic wave propagates, so the impact of a non-homogeneous distribution of activity on a mode will depend on the mode's spatial distribution. Assuming that the frequency shifts are caused by a source in the near-surface regions of the star, the shift experienced by modes of different m and l is given by Moreno-Insertis & Solanki (2000):

$$\delta v_{lm} \propto \left(l + \frac{1}{2}\right) \frac{(l - |m|)!}{(l + |m|)!} \int_{\theta_{\min}}^{\theta_{\max}} |P_l^{|m|}(\cos \theta)|^2 B(\theta) \sin \theta d\theta. \quad (2)$$

From this, we can see that a mode's sensitivity to activity has a term that depends on the mode m and l whose spatial response is described by the associated Legendre polynomials, $P_l^{|m|}(\cos \theta)$. This is combined with the magnetic field strength, $B(\theta)$, which is a function of the distribution of activity. The above describes this distribution using θ , the co-latitude on the sphere, however, for the rest of this paper we will use the latitude, λ , where $\theta = (\frac{\pi}{2} - \lambda)$. The arrangement of activity on the stellar surface therefore determines the relative magnitudes of shifts for modes of different l and m . To calculate these shifts, we assume the same top-hat model as Thomas et al. (2019), defined such that the magnetic activity is distributed in each hemisphere as a band of uniform field strength, B , lying between latitudes λ_{\min} and λ_{\max} , i.e.

$$B\left(\theta = \frac{\pi}{2} - \lambda\right) = \begin{cases} B, & \text{if } \lambda_{\min} \leq \lambda \leq \lambda_{\max}, \\ 0, & \text{otherwise.} \end{cases} \quad (3)$$

The Southern hemisphere is assumed to be a reflection of the Northern hemisphere, since the globally coherent modes have no sensitivity to differences between hemispheres.

Although theoretically we can describe the response of individual m modes to activity, it is not always possible to isolate them in a frequency spectrum. Typically, stellar modelling pipelines use only one frequency per n and l mode as input so the frequencies of the m components must be combined. The relative visibility of each azimuthal mode depends on the inclination angle of the star, i . By introducing a weighting factor, $\alpha(i)$, which is a function of the inclination angle, Thomas et al. (2019) defined how the contributions combine to give the central frequency of an $l = 1$ multiplet. For this work, we used this along with an equivalent weighting for the $l = 2$ multiplet so as to include the mode visibility dependence on i . Therefore, the measured frequency shift of the combined l peak will depend not only on the magnitudes of the individual m shifts but also on the inclination angle.

It is well known that activity-induced frequency shifts have a dependence on the radial order of the mode (Libbrecht & Woodard 1990; Chaplin et al. 1998). Higher frequency modes have shallower upper reflection points than their lower-frequency counterparts and are therefore more sensitive to the perturbations in the layers closer to the stellar surface. That they therefore show larger frequency shifts has been observed for the Sun and also other solar-like oscillators (Salabert et al. 2011, 2016; Kiefer et al. 2017; Salabert et al. 2018). To account for this in our artificial data we adjusted the shifts to have a Sun-like frequency dependence as represented by a polynomial relation in frequency (Chaplin et al. 1998; Howe et al. 2017).

Using the same frequency shift model, Thomas et al. (2019) found that the active latitudes required to produce the observed solar shifts (for solar cycle 23) extend between $\lambda_{\min} = 3.3^\circ$ and $\lambda_{\max} = 40.6^\circ$. This describes the spread of significant, large-scale field on the solar

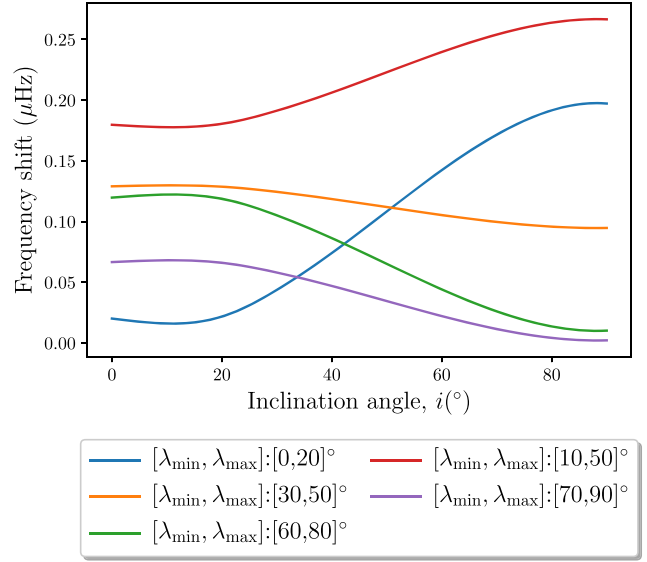


Figure 1. Example frequency shifts of $l = 1$ modes at various inclination angles in response to different magnetic activity distributions. The field strength was kept constant.

surface. We therefore re-parametrize equation (3) to replace B by a relative field strength B_{rel} , normalized to unity for the Sun:

$$B\left(\theta = \frac{\pi}{2} - \lambda\right) = \begin{cases} B_{\text{rel}}, & \text{if } \lambda_{\min} \leq \lambda \leq \lambda_{\max}, \\ 0, & \text{otherwise.} \end{cases} \quad (4)$$

To enable this, we introduced a multiplicative calibration constant $C_{\delta v}$ into the frequency shift calculation, turning the proportionality in equation (2) to an equality giving

$$\delta v_{lm} = C_{\delta v} B_{\text{rel}} \left(l + \frac{1}{2}\right) \frac{(l - |m|)!}{(l + |m|)!} \int_{\theta_{\min}}^{\theta_{\max}} |P_l^{|m|}(\cos \theta)|^2 \sin \theta d\theta. \quad (5)$$

The value of this calibration constant is fixed to $C_{\delta v} = 0.8$ in order to produce modelled shifts that match those from BiSON observations for $B_{\text{rel}} = 1$, $i = 90^\circ$, and the above-mentioned latitude parameters pertaining to the Sun.

Our model uses equation (5) to calculate the frequency shift of each m mode. As described above, we used the weighted contributions of the azimuthal components to calculate the central frequencies of the shifted $l = 1$ and $l = 2$ combined peaks. Finally, all frequencies were corrected for the radial order dependence. We used this model to generate artificial activity-affected frequencies sets.

From the above, we know that the measured (i.e. observed) frequency shift depends on the degree l , inclination angle i , relative magnetic field strength B_{rel} , and distribution of activity λ_{\min} and λ_{\max} . Increasing the magnetic field strength will induce a larger magnitude frequency shift. At certain inclination angles, it will be easier to observe particular m components due to the relative mode visibility. The response of modes and how we measure them is complex. Fig. 1 shows an example of how the measured frequency of a $l = 1$ mode responds to changes in inclination angle for a few different λ_{\min} and λ_{\max} combinations. We can see that the response is not necessarily straightforward. The $l = 2$ case is even less intuitive, since there are five m components to combine which depend on the activity distribution and whose relative contribution to the measured $l = 2$ frequency also depends on the inclination angle.

4 GENERATING ARTIFICIAL FREQUENCY SETS

We use two stellar modelling pipelines to infer properties for artificial stars from their ‘observed’ frequencies: steresoismic Inference on a Massive Scale (AIMS) and another grid-based approach which we call Yale Grid-based Modelling (YGM; see Section 5 for more details). Both methods can fit to separation ratios, thereby avoiding the need for a surface term.

To build our artificial data sets, we started with a set of ‘pristine’ frequencies, free from any simulated magnetic activity effects. At an activity minimum, we expect a more uniform distribution of activity across the stellar surface so all modes experience the same size of shift. This cancels out when taking the ratio of frequencies. Therefore, by using ratios when fitting stellar models, our pristine separation ratios are equivalent to what we would observe on a field-free star, and also what we would expect to observe at minimum levels of stellar activity. Chaplin et al. (2019) showed that minimum-epoch solar p modes should have frequencies very close to field-free case.

For the AIMS analysis presented in Section 6, the pristine frequencies were taken from the model in the grid which was most similar to the Sun in terms of mass and age (4.61 Gyr). The pristine frequencies for the YGM analysis were taken from a calibrated Standard Solar Model (SSM). This was created with the same input physics as the grid that was used for fitting, except for the atmospheric model, which was that of Krishna Swamy (1966) (see Section 5 for details of the physics of the grid). As is usual in constructing SSMs, we iterated over the mixing length parameter and the initial helium abundance in order to get a $1 M_{\odot}$ model that has the correct radius and luminosity at the solar age (4.57 Gyr). The converged model has a mixing-length parameter of 2.1566 and an initial helium abundance of 0.2734. The model has a convection-zone helium abundance of 0.2447, and Z/X of 0.02299. The base of the convection zone is at $0.71317 R_{\odot}$. For completeness, we repeated the analysis with the pristine frequency sets swapped; i.e. the AIMS pipeline was also run with data sets based on the SSM frequencies, and the YGM analysis using frequency sets based on those from the most solar-like AIMS model. The results were in agreement whichever set of pristine frequencies were used as a base.

Data sets were comprised of the 10 overtones of degrees $l = 0, 1, 2$ centred on ν_{\max} (to match the procedure of Ball & Gizon 2014). Frequency uncertainties were taken from BiSON 1-yr data and are comparable to uncertainties, given by *Kepler* data of duration a year or more from high-quality SNR targets.

Using the pristine data as the base, activity-affected frequency sets were generated by shifting the pristine modes according to our model and the chosen combination of B_{rel} , i , λ_{\min} , and λ_{\max} . The artificial data were created to represent solar-like oscillators at various inclination angles and with a variety of magnetic activity strengths and distributions.

To choose interesting combinations, we first determined those which would produce a set of shifted separation ratios that were, on average, discernibly different from those of the pristine set, i.e. beyond the uncertainty of the pristine ratios (Fig. 2 shows an example set of shifted r_{02} compared to the pristine r_{02} using $B_{\text{rel}} = 1.2$, $i = 0^{\circ}$, $\lambda_{\min} = 11^{\circ}$, and $\lambda_{\max} = 53^{\circ}$). This was motivated by our goal to find the combinations that would incur a significant bias in stellar property estimates from modelling pipelines. We constructed a grid of i , λ_{\min} and λ_{\max} , each in the range $0-90^{\circ}$ with increments of 1° , and calculated the minimum field strength, B_{\min} , needed to produce the desired shifted separation ratios. B_{\min} was in fact taken to be the weighted average minimum field strength over all of the ratios. Fig. 3

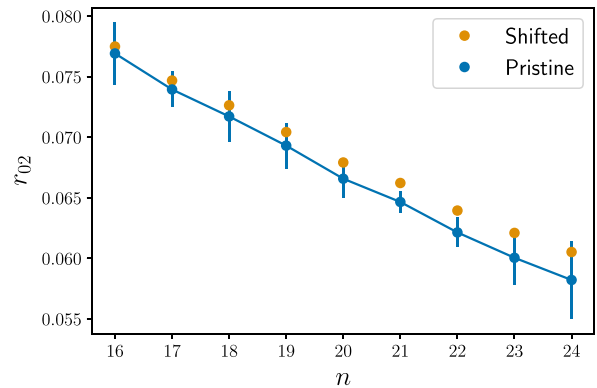


Figure 2. Example of artificially shifted r_{02} with respect to the pristine ratios, calculated using $B_{\text{rel}} = 1.2$, $i = 0^{\circ}$, $\lambda_{\min} = 11^{\circ}$ and $\lambda_{\max} = 53^{\circ}$. An effect of this size produces an average shifted r_{02} that lies just outside of uncertainty of the average pristine r_{02} .

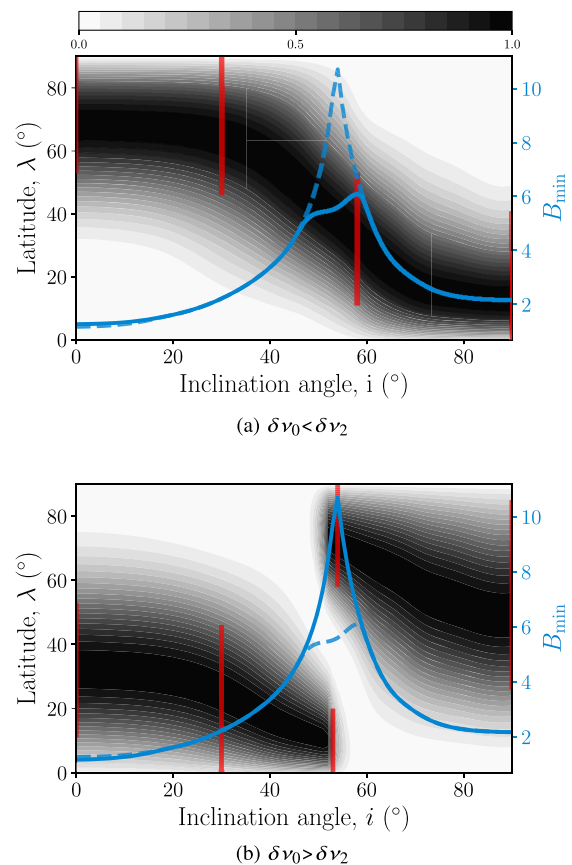


Figure 3. Determining the combination of parameters to produce separation ratios discernible from the pristine set, where B_{\min} is the minimum field strength needed to do this. The shaded areas show the latitudinal distribution of activity with darker regions indicating where a lower B_{\min} was necessary. The colourbar shows how the shading is inversely proportional to the field strength with the maximum value of 1.0 corresponding to $\frac{1}{B_{\min}}$ for that inclination angle. Top: The case for $(\delta\nu_0) < (\delta\nu_2)$. Bottom: The case for $(\delta\nu_0) > (\delta\nu_2)$. The solid blue lines are the smallest B_{\min} needed for a particular inclination angle. The dashed blue line is the same but for the opposite sign of shift. The red vertical bars indicate the latitudes occupied by the active band for each set of parameters we chose to focus on (see Table 1). Results were constructed from a grid covering $0 < i, \lambda_{\min}, \lambda_{\max} < 90^{\circ}$, hence containing 91^3 models.

Table 1. Combinations of parameters used to calculate frequency shifts for artificial data sets. The method for choosing parameters is explained in the main text. The pristine data set is representative of a field-free star. The Sun model uses the parameters necessary to produce solar-like frequency shifts from our model. The Sun 2 model is the same but for a Sun with stronger magnetic field strength in order to make significantly shifted separation ratios (i.e. $B_{\text{rel}} = B_{\text{min}}$).

	Relative magnetic field strength, B_{rel}	Inclination angle, $i(^{\circ})$	Minimum latitude, $\lambda_{\text{min}}(^{\circ})$	Maximum latitude, $\lambda_{\text{max}}(^{\circ})$
Pristine	0.0	–	–	–
i	1.2	0	11	53
ii	2.2	30	0	46
iii	9.7	53	0	20
iv	10.7	54	58	90
v	2.2	90	26	85
vi	1.7	0	53	90
vii	2.2	30	46	90
viii	6.1	58	11	53
ix	2.2	90	0	26
Sun	1.0	90	3.3	40.6
Sun 2	4.0	90	3.3	40.6

shows the latitudinal positions of activity bands (shaded regions) used to produce the required separation ratios across the range of inclination angles. For each element in the grid (corresponding to a particular i , λ_{min} and λ_{max}) we shaded the region in latitude and inclination space with a colour intensity that was proportional to $1/B_{\text{min}}$ for that element. This was repeated for the entire grid to build up Fig. 3. Therefore, the darker regions indicate where a lower B_{min} was necessary to sufficiently shift separation ratios beyond the pristine frequencies, and lighter areas where a much greater B_{min} was needed.

For each inclination angle, we took the $[\lambda_{\text{min}}, \lambda_{\text{max}}]$ pair corresponding to the smallest B_{min} , thereby compressing a 3D grid to 1D. We chose combinations to study both when the $l = 0$ shifts, $\delta\nu_0$, were larger than the $l = 2$ shifts, $\delta\nu_2$, and vice versa. The relative magnitudes of these shifts affect the direction of the bias, we get in the stellar property estimations from models. Fig. 3(a) shows the results for $\delta\nu_0 < \delta\nu_2$ shifts and Fig. 3(b) for $\delta\nu_0 > \delta\nu_2$ shifts. We can see that for each case the B_{min} is produced by activity bands at very different latitudes; for example to achieve B_{min} at high inclinations a lower latitude activity band would produce $\delta\nu_0 < \delta\nu_2$, whereas a band situated at higher latitudes would cause $\delta\nu_0 > \delta\nu_2$. The solid blue curve in each plot shows the smallest B_{min} value at each inclination angle and the dashed blue curve shows the same but for the opposite sign of shifts. We can see that at intermediate inclination angles the magnetic field strength would need to be larger than at low or high angles to induce the same size r_{02} shift. Smaller field strengths are necessary for the lowest and highest inclinations.

A variety of combinations were chosen to generate several sets of shifted frequencies. In addition, we also created artificial data to produce shifts that we would expect from the Sun using $i = 90^{\circ}$ and $[\lambda_{\text{min}}, \lambda_{\text{max}}] = [3.3, 40.6]^{\circ}$ as found by Thomas et al. (2019) for the Sun’s activity distribution. For one set of frequencies, we chose a solar-like magnetic field strength (i.e. $B_{\text{rel}} = 1$). For another, we used the same latitudes and the B_{min} value required to produce shifted ratios discernibly different from the pristine frequencies (which is higher than we see in the Sun). The red bars in Fig. 3 correspond to the chosen latitudes and inclination angles. The collections of parameters we used to produce each data set are summarized in Table 1.

We fitted stellar models to our sets of artificial frequencies and compared deviations between their estimations of stellar properties from application to the pristine frequencies and those from the activity-shifted sets. Any differences must be due to the simulated magnetic effects. If activity does not affect stellar model predictions, then all results will be similar to those obtained from pristine frequencies.

5 THE MODELLING PIPELINES

We used two different pipelines to fit stellar models to oscillation frequencies. Both used a predefined grid of models. There are many different choices for how to carry out the analysis and the constraints to use when fitting which will impact the uncertainty on estimated stellar properties. In particular, anchoring the lowest frequency modes can reduce error bars as we will show later. Below we detail the input physics and briefly cover the methods of each pipeline, one of which implemented anchoring.

5.1 AIMS

The AIMS pipeline (Reese 2016) uses individual oscillation frequencies, or in this case frequency ratios, along with classical constraints to determine global stellar properties. The grid of models we used was the same as the MS grid from Rendle et al. (2019). Models were computed using the CLÉS (Code Liégeois d’Évolution Stellaire; Scuflaire et al. 2008a) stellar evolution code and the grid was parametrized by mass in the range $0.75 M_{\odot}$ to $2.25 M_{\odot}$ with an interval of $0.02 M_{\odot}$, initial metallicity (Z_{init}) from 0.0032 to 0.0300 and initial hydrogen content (X_{init}) in the range of 0.691–0.745. The Z_{init} and X_{init} values used can be found in table 1 of Rendle et al. (2019). Microscopic diffusion with a fixed solar-calibrated mixing length of 1.81 was included, since Rendle et al. (2019) found it to produce more closely matching values for the Sun (Thoul, Bahcall & Loeb 1994). The convective overshoot was 0.05 times the local pressure scale height, Grevesse & Noels (1993) abundances were used to convert $[\text{Fe}/\text{H}]$ to Z/X , and nuclear reaction rates from taken Adelberger et al. (2011). The models were computed using opacities from Iglesias & Rogers (1996) and the equation of state from FreeEOS (Irwin 2012). Frequencies were calculated using the LOSC (Liège Oscillation Code; Scuflaire et al. 2008b) pulsation code.

AIMS combines approximating a set of best fitting models using a Markov Chain Monte Carlo (MCMC) algorithm (EMCEE; Foreman-Mackey et al. 2013) with interpolation implemented within the grid of models in order to refine constraints on properties. Interpolation is conducted using multidimensional Delaunay tessellation (see e.g. Field 1991) both linearly along an evolutionary track and between tracks.

Further details may be found in Rendle et al. (2019).

5.2 YGM

For YGM analysis, we constructed a uniform grid of models for masses in the range of 0.95 – $1.05 M_{\odot}$ with a spacing of $0.01 M_{\odot}$. For each mass, models were created with fifteen values of the mixing length parameter spanning $\alpha_{\text{MLT}} = 1.4$ to 2.625, initial helium abundances spanning from the primordial helium abundance of 0.248 (Steigman 2010) to 0.30 in steps of 0.01, and initial $[\text{Fe}/\text{H}]$ in the range -0.30 to $+0.30$ in steps of 0.01. We use the Grevesse & Sauval (1998) solar mixture to convert $[\text{Fe}/\text{H}]$ to Z/X . The stars were modelled using the Yale Stellar Evolution Code (YREC; Demarque et al. 2008). For each of the parameters, the models were evolved

from the zero-age main sequence to an age of 8 Gyr. Models were output at intermediate ages.

The models were constructed using the Opacity Project (OP) opacities (Badnell et al. 2005) supplemented with low temperature opacities from Ferguson et al. (2005). The OPAL equation of state (Rogers & Nayfonov 2002) was used. All nuclear reaction rates are obtained from Adelberger et al. (1998), except for that of the $^{14}\text{N}(p, \gamma)^{15}\text{O}$ reaction, for which we use the rate of Formicola et al. (2004). All models included gravitational settling of helium and heavy elements using the formulation of Thoul et al. (1994). The frequencies of the models were calculated with the code of Antia & Basu (1994).

To determine stellar properties, we defined a goodness of fit for each model in the grid as follows. For each of the spectroscopic observables, $[\text{Fe}/\text{H}]$, T_{eff} and luminosity L , we define a likelihood. For instance, the likelihood for effective temperature was define as

$$\mathcal{L}(T_{\text{eff}}) = C \exp\left(-\frac{1}{2}\chi^2(T_{\text{eff}})\right), \quad (6)$$

with

$$\chi^2(T_{\text{eff}}) = \frac{(T_{\text{eff}}^{\text{obs}} - T_{\text{eff}}^{\text{model}})^2}{\sigma_T^2}, \quad (7)$$

where σ_T is the uncertainty on the effective temperature, and C is the constant of normalization. We define the likelihoods for $[\text{Fe}/\text{H}]$ and L in a similar manner.

We considered the seismic data using the separation ratio r_{02} . For this, we need to take error correlations into account and thus

$$\chi^2(r_{02}) = (\bar{r}_{02}^{\text{obs}} - \bar{r}_{02}^{\text{model}})^T \mathbf{C}^{-1} (\bar{r}_{02}^{\text{obs}} - \bar{r}_{02}^{\text{model}}), \quad (8)$$

where $\bar{r}_{02}^{\text{obs}}$ is the vector defining the observe r_{02} , $\bar{r}_{02}^{\text{model}}$ is the vector defining the r_{02} for the model at the observed frequency, and \mathbf{C} is the error-covariance matrix. Thus,

$$\mathcal{L}(r_{02}) = D \exp\left(-\frac{1}{2}\chi^2(r_{02})\right), \quad (9)$$

D being the normalization constant.

The total likelihood is then

$$\mathcal{L}_{\text{total}} = \mathcal{L}(r_{02})\mathcal{L}(T_{\text{eff}})\mathcal{L}([\text{Fe}/\text{H}])\mathcal{L}(L). \quad (10)$$

The likelihood was normalized by the prior distributions of each property in order to convert to a probability density. The medians of the marginalized likelihoods of the ensemble of models was then used to determine the parameters of the star.

However, the total likelihood defined in equation (10) can result in erroneously high likelihood for some models. The surface term is smaller at low frequencies than at high frequencies, but the seismic likelihood function defined above does not take this into account. Presently, it could be possible to have a model with low $\chi^2(r_{02})$ but where the low frequency modes are badly fit. In order to down weight models for which frequency differences are large, we multiply equation (10) with the term

$$\mathcal{L}_{\text{reg}} = E \exp\left(-\frac{1}{100}\chi^2(\nu_{\text{low}})\right), \quad (11)$$

where $\chi^2(\nu_{\text{low}})$ is the χ^2 for the two lowest frequency modes of each degree and E is another normalization constant. Note that equation (11) is not a true likelihood function; the division of the χ^2 by 100 rather than 2 ensures that this term does not dominate the final selection process. One can set this anchoring of the low frequency modes in AIMS; however, in order to show the range of

results to expect using different analysis approaches here we ran AIMS without this constraint.

6 RESULTS

We determined stellar properties for the pristine and activity-affected stars using the pipelines described in the previous section. Both methods were supplied with the artificial sets of frequencies and fitted using the separation ratios r_{02} . Observational constraints of effective temperature $T_{\text{eff}} = 5777 \pm 80\text{K}$ and metallicity $[\text{Fe}/\text{H}] = 0 \pm 0.1\text{dex}$ were also provided and were the same for all data sets. Additionally, we refit the same frequency sets, this time with an extra constraint of luminosity $L = 1.00 \pm 0.03L_{\odot}$. The assumed use of a luminosity uncertainty of 3 per cent was based on *Gaia* (Gaia Collaboration 2018) parallaxes for Sun-like stars. Figs 4 and 5 show results from fitting using just frequencies, T_{eff} and $[\text{Fe}/\text{H}]$; Figs 6 and 7 show results from fitting including a luminosity constraint.

Presented are the median results taken from the posteriors of each property, either from the AIMS (panels a) or the YGM pipeline (panels b). The black circles indicate the median value of stellar properties obtained by fitting to a ‘pristine’, i.e. field-free, set of frequencies which act as a reference. The results obtained from other data sets have been spread along the x -axis for clarity. The grey band shows the uncertainties from 68 per cent confidence intervals on the estimates from stellar models applied to pristine frequencies. The horizontal grey dashed lines illustrate the underlying properties from the corresponding model used to generate pristine frequencies. There is a systematic offset between the underlying properties used to compute the pristine data set and the results from fitting to the pristine frequencies; however, they are generally well within error. The focus of this work is on how the results from fitting to shifted frequency ratios differ to those from fitting to pristine frequency ratios, since this will be due to magnetic activity effects.

For the majority of properties, the median estimates for the activity-affected data lie within the uncertainties of the equivalent pristine values. However, for all runs we can see that the largest differences between estimates from the pristine frequencies and those for different data sets are in age and central hydrogen abundance. For the case of the YGM pipeline, we can see there is also a considerable spread in the T_{eff} values. The spread is more significant for the fits that included a luminosity constraint, since the uncertainty bars are smaller.

It is clear that for stars experiencing this amount of activity-induced frequency shift, some of the stellar properties we infer will have a notable bias. Focusing on mass and age, we find that the bias can be up to 5 per cent in age, but only up to 0.5 per cent in mass. This offset is therefore not a concern since for the analysis carried out in this work, the age parameter typically has a 4.5 per cent uncertainty and we see a 2.5 per cent error on mass.

As described in Section 4, there are four combinations of results: AIMS fitted to AIMS model frequencies, AIMS applied to frequencies built on the SSM data, YGM applied to the AIMS model frequencies, and finally YGM analysis of the SSM frequency sets. In general, we see similar results for all combinations. The uncertainties from YGM fitting are consistently smaller than those from AIMS, but this can be attributed to the additional constraints placed on the low-frequency modes (see Section 5). AIMS uncertainties match what we would expect from Rendle et al. (2019) (table 3) when fitting using separation ratios and a luminosity constraint.

In the plots where the absolute spread of stellar property estimates is discernible from the pristine values, we can see that there are two distinct groups of points above and below the pristine results. These

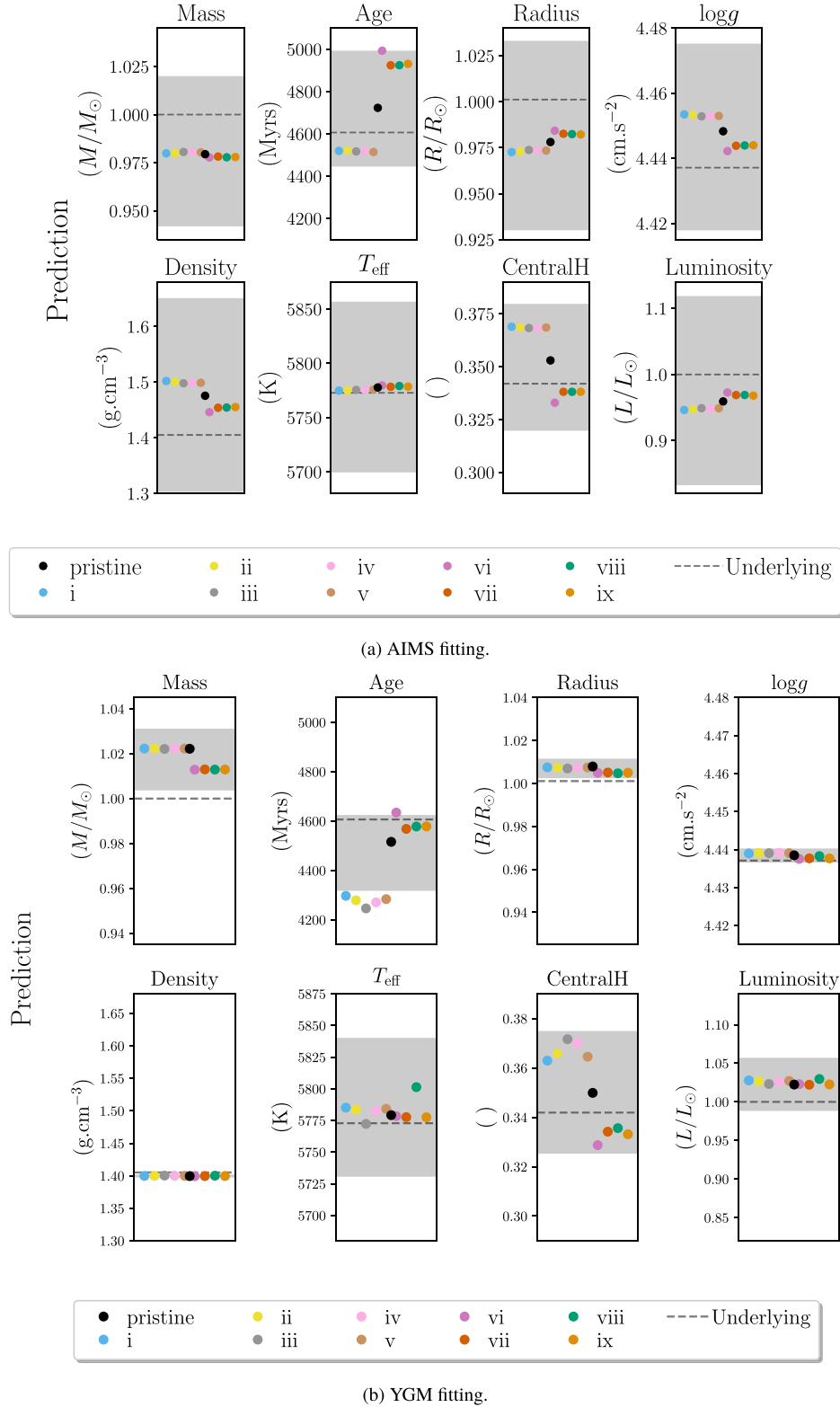
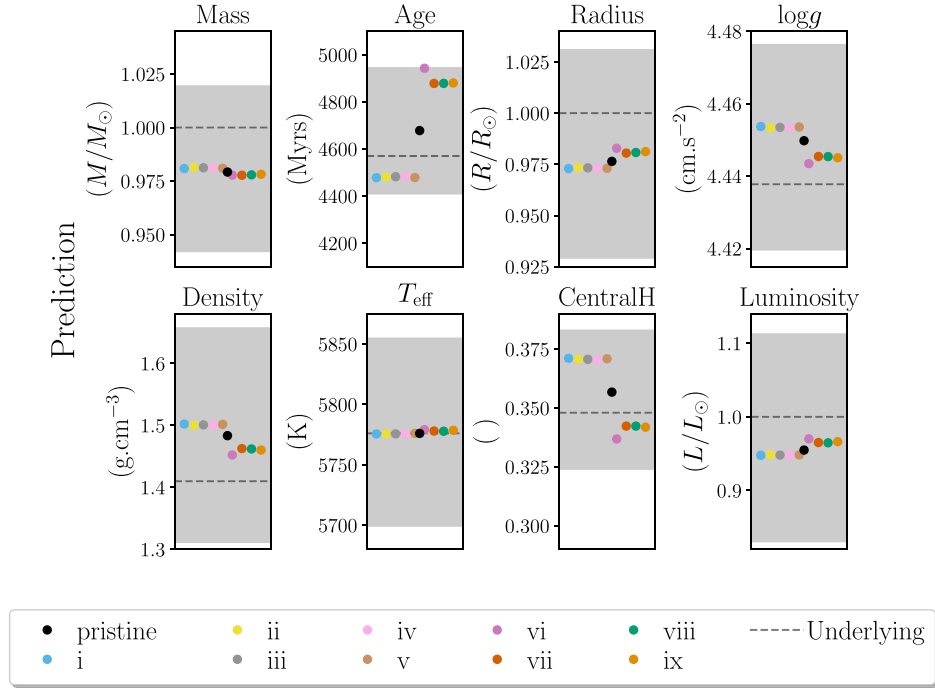
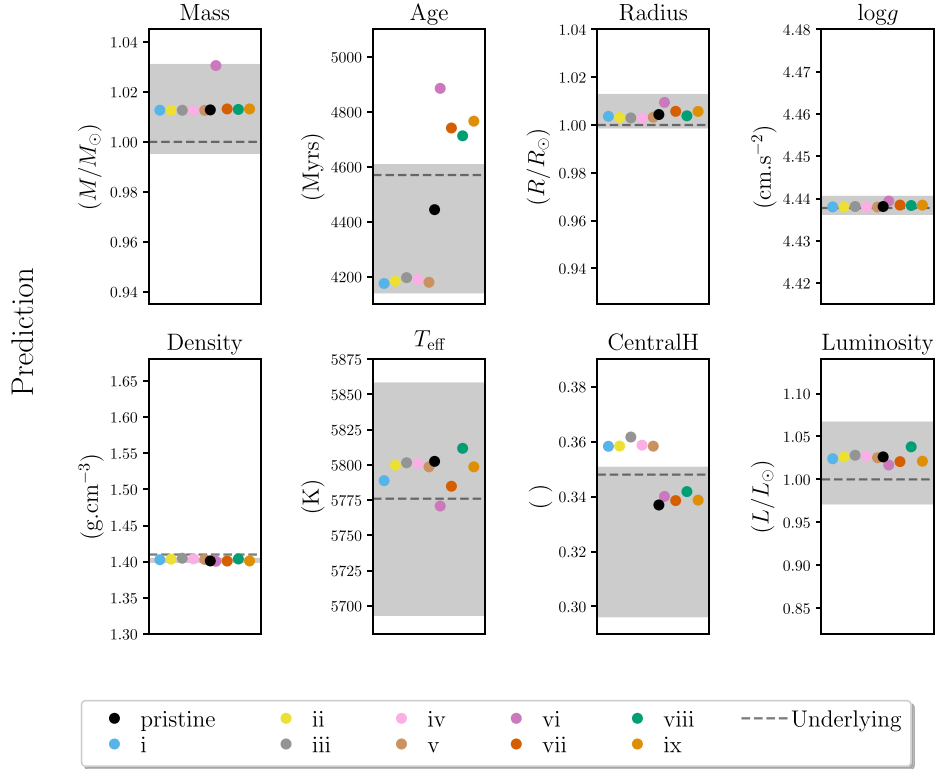


Figure 4. Predictions from fitting without a luminosity constraint. The pristine data set was based on the most solar-like model from the AIMS grid. Black circles indicate median results from the pristine data set with the grey band showing the uncertainty on the stellar model estimates from the pristine frequencies. The coloured circles correspond to the results from frequency sets shown in Table 1, and are spread along the x-direction for clarity; their position along the x-axis has no meaning. The same y-axis ranges have been used in Figs 4–8 to more easily allow a like-for-like comparison between plots.



(a) AIMS fitting.



(b) YGM fitting.

Figure 5. The same as in Fig. 4 but with the pristine data set based on the SSM.

correspond to where the underlying frequency shift at $l = 0$ is larger than the $l = 2$ shift and hence whether d_{02} is greater or smaller than for the pristine set. For example, if the shifted d_{02} is larger than the pristine d_{02} , i.e. $\delta\nu_0 > \delta\nu_2$, then the fitting will find a smaller age.

To verify that models were equally well fitted to shifted data sets as to the pristine frequency ratios we calculated the ratios of log-likelihoods between fits and found them to be approximately unity. We also tested the analysis methods described above by replacing

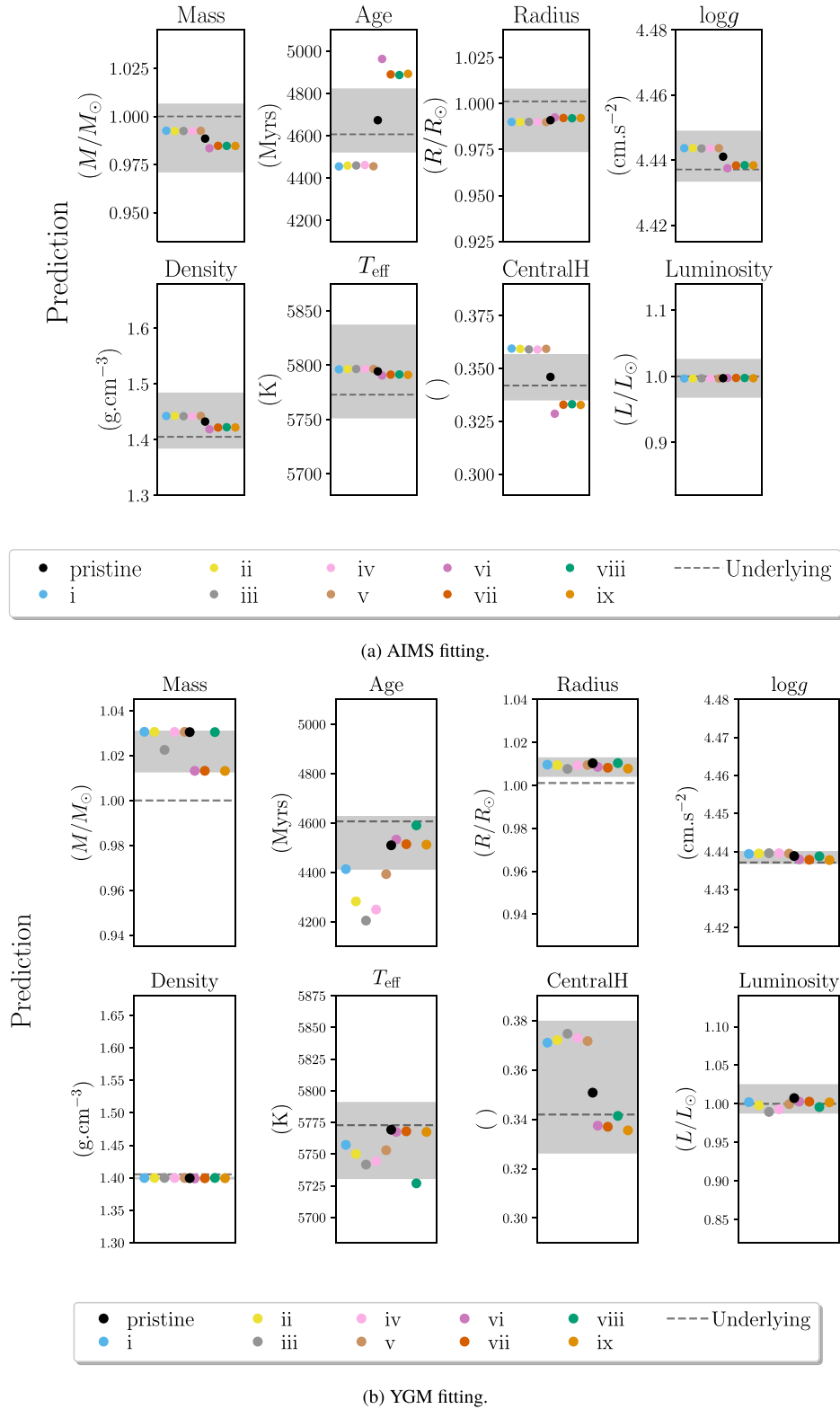


Figure 6. The same as in Fig. 4 with the pristine data set based on the most solar-like model from the AIMS grid but applying a luminosity constraint.

the r_{02} frequency constraint with r_{01} data, and separately using both r_{02} and r_{01} data simultaneously. The resulting posterior estimates of stellar properties showed very similar patterns to the r_{02} results presented here.

6.1 The Sun

In addition to the various combinations tested above, we also studied the bias we would expect for frequency shifts from a Sun-like star

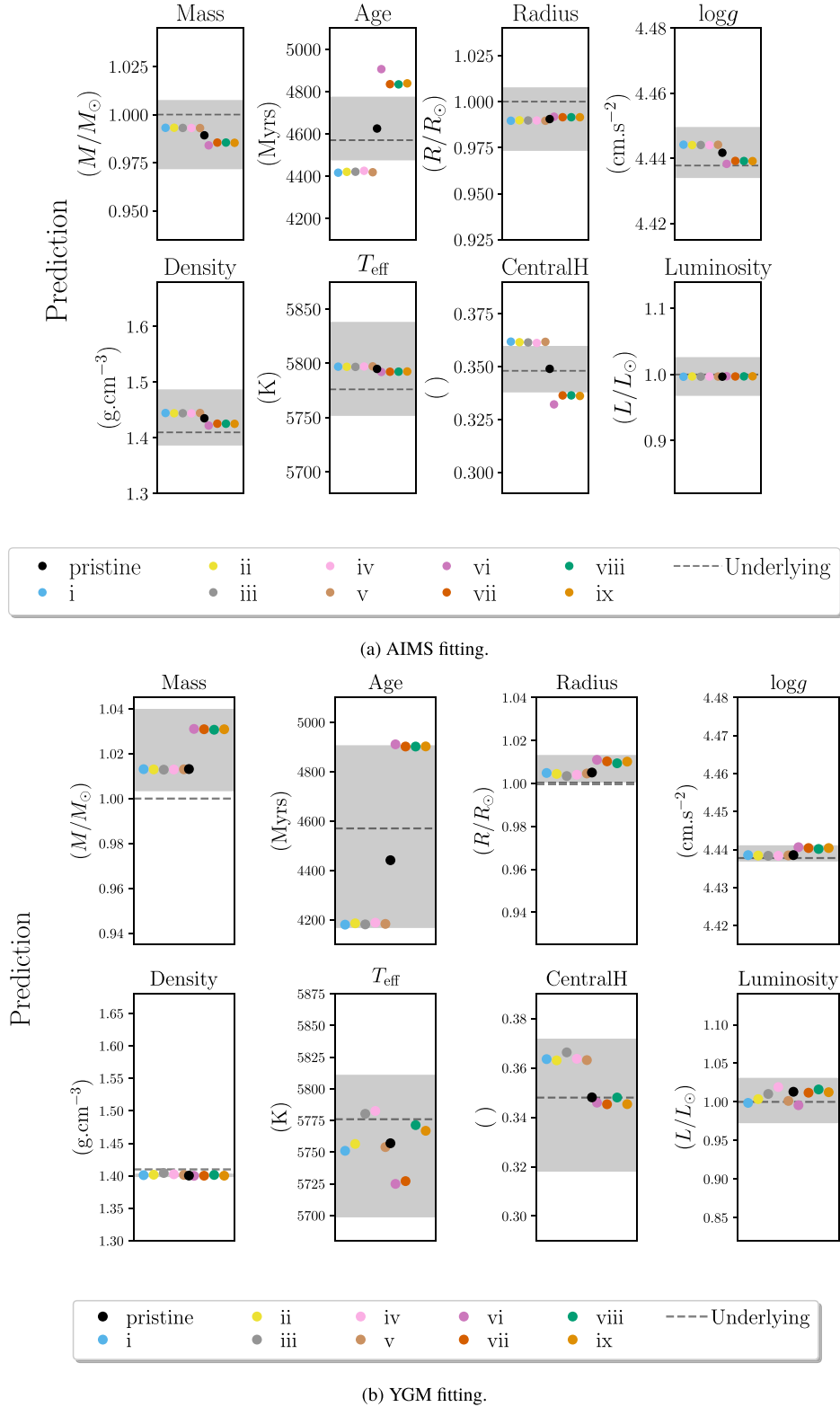


Figure 7. The same as Fig. 4 but with the pristine data set based on the SSM and applying a luminosity constraint.

compared to the pristine frequencies. As described earlier, shifts were calculated using $i = 90^\circ$, $B_{\text{rel}} = 1$, and $\lambda_{\text{min, max}} = [3.3, 40.6]^\circ$. Another set of frequencies was computed for the same parameter values except using $B_{\text{rel}} = 4.0$ to imitate a Sun with stronger magnetic field strength.

Fig. 8 shows the results. The estimated stellar properties were not notably different from those one would obtain from pristine frequencies for the solar-like case ($B_{\text{rel}} = 1$). However, with four-times the field strength we should expect a bias for all properties, being at the 1σ level for the estimated age and central hydrogen content.

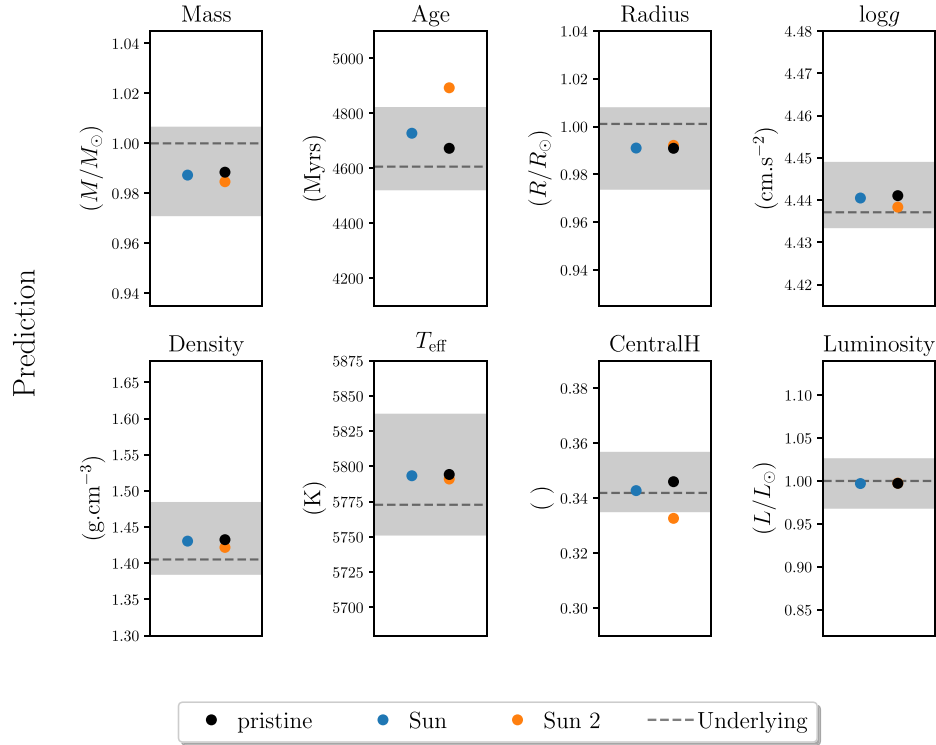


Figure 8. Results from fitting to two additional artificial sets: one using frequency shifts that we would expect to see in the Sun, and the other with same inclination angle and activity distribution as we would observe but with four times the magnetic field strength, i.e. $B = 4$. Fitting was conducted by AIMS including a luminosity constraint, and the pristine data set was based on the most solar-like AIMS model.

7 DISCUSSION AND CONCLUSIONS

We have demonstrated that for some distributions and strengths of surface stellar activity the oscillation frequencies would experience a shift that impacts the properties obtained from stellar modelling pipelines when applied to separation ratios. The shifts we measure depend on a star’s magnetic field strength, the activity distribution on the stellar surface, and its inclination angle (the angle affecting which azimuthal mode components are detectable). Measured shifts therefore show a complex relationship between these variables. We generated several artificial sets of ‘measured’ frequencies using shifts arising from various combinations of the above. By fitting to separation ratios (r_{02}) constructed from the frequencies, global properties for these fake stars were estimated by two pipelines and compared to results from a field-free star.

Our results showed that estimates on stellar properties split into two groupings either side of the pristine result based on whether the shifted d_{02} is greater or less than the pristine d_{02} . The most noticeable divide is in the age parameter which is lower for an increased d_{02} . By extension, given the small range of metallicities here, a lower age will automatically result in a higher central hydrogen abundance. In general, we see a greater mass for those shifted data sets with larger d_{02} which is as expected, given we are taking a cut in T_{eff} .

The division into two groups implies that by measuring the shift in small frequency separation, it is possible to determine the direction of the biases, i.e. whether the property is an under- or overestimate. Since the size of the bias depends on the frequency shifts experienced by the modes, and is therefore a complex function of the inclination angle, activity strength and distribution, it is more difficult to estimate the size of the bias. By pairing this with the methods of Thomas et al. (2019), it is possible to constrain the active latitudes present on the

star using observations of frequency shifts over time along with the stellar inclination angle. If there is some way to estimate the star’s magnetic field strength relative to the Sun, then it could be possible to understand the expected size of the bias on properties, albeit with fairly large uncertainty.

We found that, in general, to experience a bias in property estimation larger magnetic field strengths are necessary. The deviations from the underlying properties would be larger for stars with a stronger magnetic field, since this simply increases the magnitude of frequency shifts experienced by the modes. For the case of the Sun ($B_{\text{rel}} = 1$), the frequency shifts due to activity would not produce a significantly biased estimation of solar properties at the levels of precision tested here. In order for these to be affected, the field strength would need to be approximately four times stronger.

The measured frequencies from stars with intermediate inclination angles are least susceptible to magnetic activity effects. As discussed in Section 3, this is due to the relative visibilities of the individual azimuthal modes and how their contributions to a central mode frequency are balanced. At these inclinations, the field strength would need to be high for the observed separation ratios to be shifted far enough from the pristine r_{02} to have an impact on the estimated stellar properties. This can be seen in Fig. 3 where the B_{min} value peaks at $i \sim 55^\circ$, where B_{min} is the field strength required to produce shifted ratios discernibly different to the pristine ratios. However, these inclinations only account for ~ 20 per cent of stars (between 45° and 60°). Assuming an underlying isotropic distribution of inclination angles, the relative number of stars observed as a function of i is proportional to $\sin(i)$; therefore, observing a star with high inclination is more likely. For the lowest ($<40^\circ$) or highest ($>70^\circ$) inclinations, B_{min} is lower. This means that for stars at these inclination angles more care must be taken to consider the bias on stellar properties due to activity.

For this analysis, we took frequency uncertainties commensurate with *Kepler* data of a year or more. For shorter duration observations, the frequency resolution will be reduced thereby minimizing these effects since estimates of stellar properties will have larger uncertainties. The significance of the bias in properties will depend on the quality of data provided to the modelling pipeline. This includes additional spectroscopic measurements and whether low-frequency modes are constrained separately to separation ratios.

We find that for asteroseismic observations of Sun-like targets we can expect magnetic activity to affect mode frequencies that will bias the results from stellar modelling analysis. For most stellar properties, we studied this offset should not be an issue since it is smaller than the uncertainties, including those on mass. However, for age and central hydrogen content, the effect could be significant. Particular care must be taken when analysing long duration observations of stars with stronger magnetic field strengths than the Sun for which we expect higher magnitude frequency shifts. The same is true for stars with very high or low inclination angles, where, for the same field strength, the shift in measured frequency separation ratios is easier to observe and therefore will produce a more significant bias.

An obvious next step is to assess the fraction of asteroseismic targets in the *Kepler* and *TESS* samples that might be susceptible to these effects based on results from asteroseismic signatures of stellar activity cycles (e.g. Salabert et al. 2011; Régulo, García & Ballot 2016; Salabert et al. 2016; Kiefer et al. 2017, 2019; Santos et al. 2018) and proxies of magnetic activity (e.g. see Mathur et al. 2019 and references therein).

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DATA AVAILABILITY

The data underlying this article were generated with publicly available software: AIMS, <https://gitlab.com/sasp/aims>.

The data underlying this article will be shared on reasonable request to the corresponding author.

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