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Machine learning aided management of motorway facilities using single vehicle accident data

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Abstract: Management of expressway networks has been mainly focused on defect management without looking at the correlations with accidental risks. This causes unsustainability in expressway infrastructure maintenance since such defects may not be a contributing factor towards public safety. Thus, it is necessary to incorporate accidental events for decision-making in infrastructure management. This study has developed a novel approach to machine learning (ML) that incorporates actual primary data from the last 10 years of single-vehicle accidents by collisions with motorway facilities (SVA) or so-called single-vehicle collisions with fixed objects. The ML is firstly aimed at identifying the influential factors of SVA in relation to finding the effective countermeasures for accidents by integrating the correlation analysis, multiple regression analysis and machine learning techniques. The study reveals that wet pavement conditions have a significant effect on SVA. The results show that improvement of the skid resistance is the most effective method to reduce SVA when the average vehicle speed (AVS) is less than 60 km/h. At the locations with gentle curve radii, ML indicates that it is crucial to redesign the speed-through management. Interestingly, the real data over 10 years indicates no relationship between equivalent single axle load (ESAL) and skid resistance, although many other studies have demonstrated the inverse relationship. In this study, the novel ML mean demonstrates excellent capability in providing suitable countermeasures for a reduction of SVA under a variety of uncertain and road quantitative aspects. The ML-based mitigation policies can also be applicable to other motorways and can contribute to their road safety, underpinning sustainable transport systems.

Keywords: safety management; risk management; sustainable maintenance; single vehicle; accidents; uncertainty; expressway; motorway.

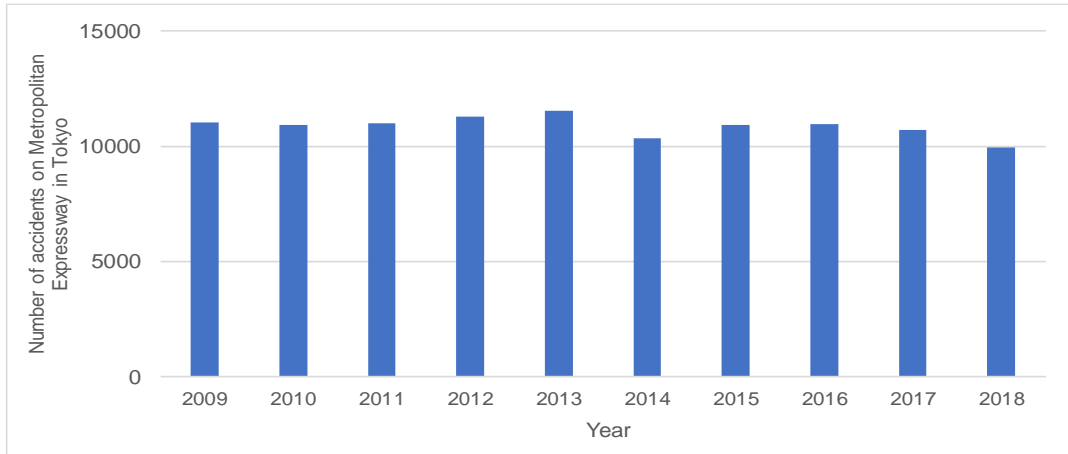
1. Introduction

Metropolitan Expressway Company Limited “MECL” was established in 1959 with the aim of reducing traffic congestion in and around the Tokyo area. To reach their goals they have taken a number of countermeasures for reducing heavy traffic congestion such as expressway network expansion, introduction of the electric toll collection system and provision of correct traffic information. Despite efforts and a significantly decreased amount of traffic congestion, road safety on the expressway remains a significant issue. The expressway has experienced a significant number of accidents since it opened in 1962. In fact, about 1 million vehicles use the expressway daily and around 30 accidents still occur every day.

Certainly, road safety can be closely related to traffic congestion, as explained by Li et al. [1], when they describe a strong correlation between traffic congestion and the probability of a rear-end collision. Thus, it was expected that through alleviating the traffic congestion this would reduce the number of traffic accidents [2]. However, it has been found that one of the major causes of accidents is

50 speeding and therefore, reducing traffic jams alone is not enough to reduce accidents. Despite the
51 unclear relationship between the mean speed and the accident rates, it is imperative to decrease the
52 number of SVA accidents and their consequences in order to positively affect the sustainable
53 development of a society. The traffic accidents lead to economic losses such as medical expenses,
54 loss of production and damage of vehicles and road facilities [3][4]. Statistically, in the Metropolitan
55 Expressway in Japan, the total number of accidents has not really changed in the last ten years, as
56 shown in Figure 1.

57



58
59

Figure 1. Transition of the number of accidents on Tokyo Metropolitan Expressway.

60 The literature has established that SVA and multiple-vehicle collisions have a wide variety of
61 variables, influences, and different circumstances [5]. It is also clear that few studies have been
62 conducted to examine SVA [6][7]. Moreover, for transportation infrastructure systems under the various
63 hazards, the details of SVA can be a safety performance and resilience indicator of the traffic flow on
64 the highways [8].

65 In addition, there is very limited research investigating single-vehicle accidents (SVA) by collisions
66 with motorway facilities or so-called 'single-vehicle collisions with fixed objects' in Tokyo. MECL is
67 seeking effective road safety methods for SVA in Japan, about which there has been very little research
68 conducted so far. Therefore, this study focuses on SVA to fill the research gap and provide the
69 Japanese transport industry with some important insights. Currently, data show that SVA tends to
70 happen on sharp curves [9], with most SVA in Metropolitan Expressway happening there in recent
71 years. Therefore, this study aims to identify factors influencing SVA with regard to quantitative influential
72 factors as well as the influential factors of uncertainty such as weather conditions, traffic volume, vehicle
73 speed, and skid resistance of a pavement. As for the skid resistance, the pavement condition based on
74 skid resistance of a pavement has been proven to be closely linked to the road accident rate [10].
75 However, MECL has not used skid resistance as the criteria of a pavement reconstruction because the
76 relationship between safety risk and the skid resistance has not been identified on the Metropolitan
77 Expressway. Hence, this research aims to focus on the relationship between the skid resistance and
78 SVA as well as to identify the relationships among other conceivable traffic accidental factors
79 demonstrated above. Furthermore, 30 locations, which have the biggest number of SVA over the last
80 10 years, are focused on in the analysis. The scope of this study is to identify the influential factors
81 behind SVA (see Figure 2).

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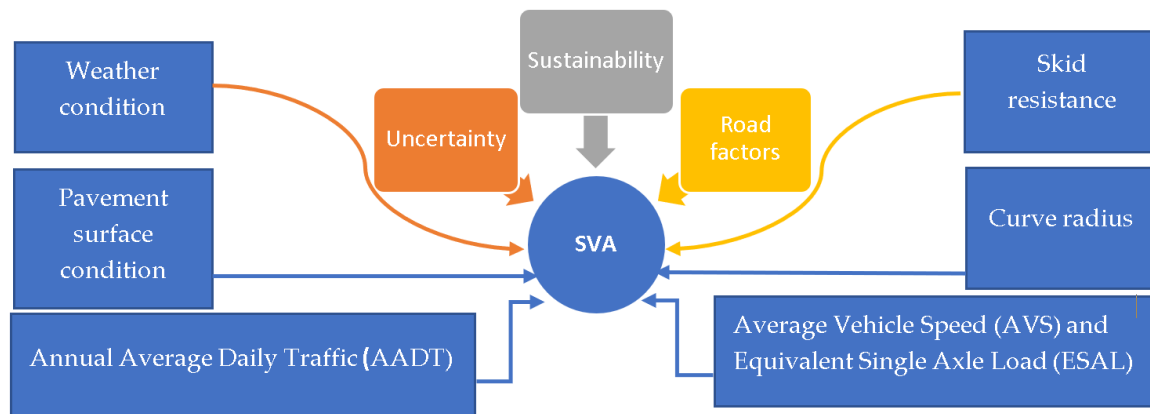


Figure 2. The influential factors causing SVA.

83
84

85

86 In addition, the study focuses on both quantitative road factors and uncertainty parameters. It aims to
87 investigate countermeasures corresponding to each factor:

- 88 • to identify the relationship between the influential factors and SVA from the viewpoint of both
89 uncertain and quantitative road factors, and;
- 90 • to investigate countermeasures for reducing the risk of SVA.

91 Since accidents involve complex interaction factors, novel techniques are required for better analytics,
92 including predictions and supporting real-time decisions utilizing ML.

93 Statistical models are designed for inference about the relationships between variables, and ML is
94 designed to make the most accurate predictions possible in order to obtain a general understanding of
95 the data to make predictions.

96 The ML has been proven to deliver more accurate analysis data than the traditional methods, and it can
97 deal with many dynamic factors in real-time when compared to statistical (regression) models. The ML
98 models can train and can be used for predictions, engineering redesign, and advanced analytics in
99 order to enhance safety and reduce SVA.

100 The outcome of this study will support decision-making processes in order to prioritize maintenance
101 and repair activities of the motorway facilities on the Tokyo Metropolitan Expressway, Japan.

102

103 2. Literature Review

104 A number of approaches to reduce traffic accidents have been adopted from various perspectives. At
105 present, it has become apparent that road safety factors can be mainly divided into three categories,
106 such as human factors, vehicle factors, road and various environmental factors [11][12][13][14][15].
107 Although most problems related to vehicle factors have already been tackled, other problems
108 associated with human and road environmental problems still exist in Japan [16][17]. Furthermore, more
109 than 90% of road traffic accidents are due to human factors [18] and as a result, many studies have
110 focused on human behaviours. Nishiuchi [19] [20] and Hung and Huyen [21] found that legislation,
111 enforcement and education were effective for the reduction of road traffic accidents. In addition, Rolison
112 et al. [22] demonstrated that road safety risk increases when law enforcement practices are inadequate,
113 according to expert views and accidental records. They concluded the inadequacies could cause
114 drivers' carelessness, which could cause road traffic accidents. Moreover, it has been found that the
115 most influential seven risk factors are related to human factors [23]. Many countries have tried to tackle
116 the issues by using measures related to those seven risk factors. In fact, the number of accidents from
117 driving under the influence of alcohol, which is one of the seven risk factors, has fallen in Japan by
118 means of increasing penalties. However, the number of road traffic accidents caused by drink-driving
119 and also distracted driving still remains high despite the fact that the Japanese government has also
120 taken countermeasures from an educational point of view [20][24]. Therefore, it is assumed that the
121 countermeasures against road traffic accidents from other points of view need to be considered at the
122 same time. Another unsolved road safety factor is the "road environmental factor", which is also

123 considered in this study. Uchida et al. [25] and Buss et al. [26] stated that road accidents related to
 124 human factors can be caused by the interaction with uncertain road environmental factors for drivers
 125 such as weather conditions and traffic situations. In other words, to identify a way to reduce road traffic
 126 accidents in terms of uncertain roads, environmental factors could reduce accidents linked with human-
 127 related factors. Jung et al. [27] revealed vehicle to vehicle crashes tend to occur on rainy days under
 128 certain conditions such as places where pavement surface material changes. In addition, Malin et al.
 129 [28] demonstrated the risk in poor weather and road conditions were higher on motorways compared
 130 to general roads, which are two lane or multiple lane roads, although the overall risk was lower on
 131 motorways. In addition, Üzümcüoğlu et al. [29] showed in their study that the traffic situation was closely
 132 related to driver behaviors; and it was found that these might be critical aspects in road safety.
 133 Moreover, quantitative road environmental factors such as road geometry and alignment also could be
 134 influential to road traffic accidents, much like uncertain road environmental factors such as weather
 135 conditions and traffic situations. Dadashova et al. [30] demonstrated that geometrical design factors
 136 such as narrow lanes, higher super-elevation, steeper slope and curve radius were found to contribute
 137 to the severity of the accident. Furthermore, Papadimitriou et al. [23] focused on road traffic accidents
 138 with road facilities as the risk factor in accidents. They then categorized road-infrastructure related crash
 139 risk factors based on how detrimental they are to road safety in consideration of safety risk level.
 140 Furthermore, Yan et al. [31] analyzed characteristics of rear-end accidents by the use of correlation
 141 analysis as well as multiple regression model, which can be suitable for this kind of research. The study
 142 also revealed seven influential road environmental factors, five factors related to the striking role and
 143 four factors related to the stuck role as the significant causation of rear-end accidents. As described
 144 above, both uncertainty factors and road quantitative aspects could influence road traffic accidents.
 145 Moreover, there have been very few studies, which focus either on SVA or on road traffic accidents that
 146 have occurred on city expressways. The correlation analysis to determine the relationship between road
 147 traffic accidents and the influential factors has been reported to be effective and suitable for this
 148 research. Hence, this study aims to identify the meaningful causation of SVA from the viewpoint of
 149 uncertainty parameters and road quantitative factors by the adoption of correlation analysis.

150 3. Methodology

151 The 10-year data sets, which include the number of SVA, AVS, Annual Average Daily Traffic (AADT)
 152 and skid resistance, are provided by MECL. This section describes methodologies utilized in the
 153 analysis.

154 3.1 Pearson's correlation coefficient analysis

155 Pearson's correlation coefficient generally shows the connection between two continuous variables. It
 156 is defined as the ratio of the covariance of the two variables to the product of their respective standard
 157 deviations, commonly expressed by "ρ". Pearson's correlation coefficient is illustrated in Equation (1).

$$158 \quad \rho = \frac{Cov(x,y)}{\sigma_x \sigma_y} \quad (1)$$

159 The sample correlation coefficient "r" can be obtained by applying the sample covariance and the
 160 sample standard deviations into Equation (2).

$$161 \quad r = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=1}^n (x_i - \bar{x})^2 \sum_{i=1}^n (y_i - \bar{y})^2}} \quad (2)$$

163 where:

$$164 \quad \bar{x} = \frac{\sum_{i=1}^n x_i}{n}, \bar{y} = \frac{\sum_{i=1}^n y_i}{n}$$

165

166 Pearson's correlation coefficient ranges from -1 to +1. If ρ is more than 0, two variables tend to increase
167 or decrease simultaneously, which means positive monotonic association. Furthermore, if ρ is less than
168 0, one variable tends to increase when the other decreases, which means negative monotonic
169 association. If ρ is 0, it corresponds to the absence of the monotonic association, or there is no
170 association in the case of bivariate normal data [32]. In addition to that, the value of ρ indicates the
171 strength of the monotonic relationship between the two variables. ρ of 1 indicates a complete linear
172 relationship.

173 This study uses the analysis method to identify the relationship between the number of SVA and both
174 uncertainty and quantitative road factors. These factors are independent so this method can be fully
175 adopted. In this case, annual data are used for the analyses of correlation coefficients.

176 3.2 Multiple regression analysis

177 In principle, multiple linear regression is a simple extension of linear regression. However, instead
178 of relating one dependent outcome variable y to one independent variable x , one tries to explain the
179 outcome value y as the weighted sum of influences from several multiple independent variables shown
180 in Equation (3).

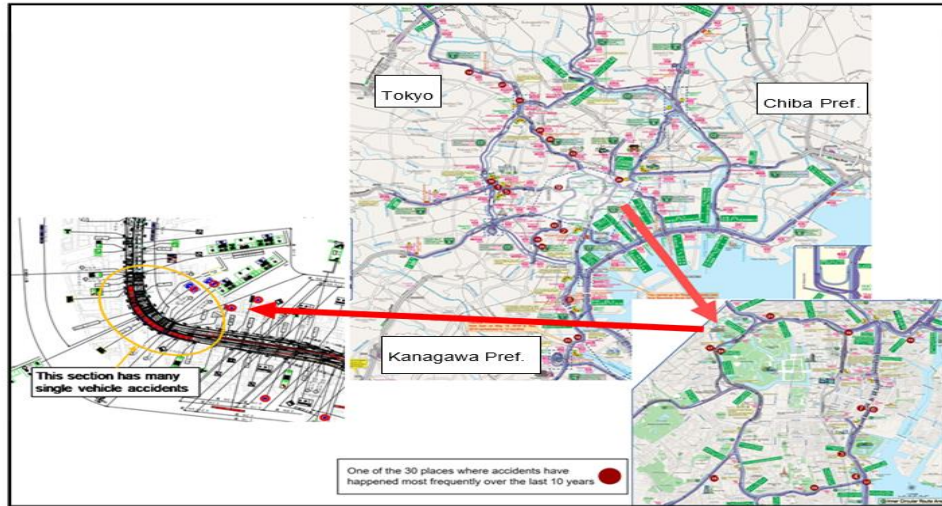
$$181 \quad y = k + ax_1 + bx_2 + cx_3 + \dots + \varepsilon \quad (3)$$

182 k illustrates the intercept of the line on the y -axis. a , b , and c are the slopes of the relations between y
183 and x_1 , x_2 , and x_3 , respectively. Moreover, " ε " shows the random error term. Basically, this equation
184 plots the best fitting line. However, it is plotted through $n + 1$ -dimensional space [33].

185 Multiple regression models are generally harder to yield best-fitting than single-parameter linear
186 regression models because different independent variables may not be independent of each other
187 (Cohen et al., 1983). Furthermore, independent variables need to be disentangled from each other
188 mathematically to optimize the multiple regression equation [33]. Therefore, a multiple regression model
189 is fitted by throwing out independent variables which have no significant relation to y and by normalizing
190 independent variables in a manner that removes how they are influenced by other variables. As a result,
191 a multiple regression model can be obtained. The final fitted model can explain the amount of an
192 increase in one unit in each independent variable. Although this analysis method is a linear
193 approximation and the equation may not fully or accurately account for the relationships between
194 variables and outcomes, in practice, linear models are generally examined at first by how well they
195 perform before considering more complicated nonlinear regression methods. It is noted that MECL has
196 not analyzed the relationship between SVA and the aspects focused on in the study before. Thus, this
197 study is imperative to identify the relationships among relevant factors and the combination of the
198 factors, which are likely to impact SVA. Moreover, for the smart analytics of AI, ML analysis and decision
199 tree methods that support nonlinearity have been considered, and some techniques are compared in
200 Section 9 Machine learning analysis.

201 4. Data

202 This study focuses on SVA and thus, SVA observation data are essential for the analysis. The research
203 makes use of data sets from 30 locations where the most frequent numbers of SVA occurred on the
204 Metropolitan Expressway between 2009 to 2019. Those places are shown in Figure 3 and Table 1.



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Figure 3. 30 places where accidents have happened most frequently over the last ten years on the Metropolitan Expressway with the example of a curve section.

Table 1. 30 places where accidents have happened most frequently over the last 10 years.

Number	Route	Direction	Start km post	End km post	Name of the area
1	Route 4 Shinjuku Line	Inbound	4.8	5.3	Sangubashi curve
2	Route 2 Meguro Line	Outbound	1.1	1.6	Furukawabashi curve
3	Inner Circular Route	Inner	3.5	4.0	Shiodome S curve, Shiodome JCT
4	Inner Circular Route	Inner	4.2	4.7	Hamasakibashi JCT
5	Route 4 Shinjuku Line	Outbound	4.3	4.8	Yoyogi S curve
6	Inner Circular Route	Outer	2.5	3.0	Ginza S curve
7	Inner Circular Route	Outer	2.4	2.9	Ginza curve
8	Route 1 Haneda Line	Outbound	3.6	4.1	Tennozu S curve
9	Route 4 Shinjuku Line	Inbound	0.9	1.4	Benkeibori curve
10	Route 1 Haneda Line	Inbound	11.4	11.9	Haneda tunnel
10	Central Circular Route	Outer	25.0	25.5	Itabashi JCT
12	Inner Circular Route	Outer	4.4	4.9	Hamasakibashi JCT
12	Route 5 Ikebukuro Line	Inbound	2.3	2.8	Omagari curve
12	Route 5 Ikebukuro Line	Outbound	14.1	14.6	Nakadai S curve
15	Route 2 Meguro Line	Outbound	0.4	0.9	Ichinohashi JCT
16	Route 6 Mukojima Line	Inbound	0.1	0.6	Hakozaki JCT - Edobashi JCT
17	Inner Circular Route	Outer	11.0	11.5	Chiyoda tunnel, Sanbancho curve
18	Yaesu Route	Southbound	0.6	1.1	Yaesu tunnel
19	Route 2 Meguro Line	Outbound	4.0	4.5	Osaki curve
20	Route 5 Ikebukuro Line	Inbound	4.7	5.2	Gokokuji S curve
21	Inner Circular Route	Outer	12.6	13.1	Takebashi JCT - Kandabashi exit
21	Route 2 Meguro Line	Inbound	0.8	1.3	Furukawabashi curve
23	Route 1 Haneda Line	Inbound	12.4	12.9	Haneda curve
24	Inner Circular Route	Inner	10.9	11.4	Chiyoda tunnel, Sanbancho curve
25	Route 2 Meguro Line	Outbound	5.0	5.5	Gotanda S curve
26	Route 1 Ueno Line	Inbound	0.0	0.5	Honcho entrance - Edobashi JCT
26	Route 5 Ikebukuro Line	Outbound	11.0	11.5	Itabashi-honcho curve
28	Route 5 Ikebukuro Line	Inbound	5.9	6.4	Hinode-daiichi curve
29	Inner Circular Route	Inner	5.4	5.9	Shibakouen S curve
30	Route 4 Shinjuku Line	Inbound	5.7	6.2	Shinjuku curve

209

210 It is notable that, uncertainties, weather conditions, traffic volume and AVS are the main focus of the
 211 analysis. In fact, Theofilatos and Yannis [34] stated that weather conditions are closely related to road
 212 traffic accidents. On the other hand, they do not analyze what kind of accidents were linked to weather
 213 conditions. Therefore, it is important for this study to find the association between weather conditions
 214 and SVA. The research focuses on pavement surface condition in terms of humidity, such as dry and
 215 wet conditions, similar to that which was studied by Theofilatos and Yannis [34]. As for traffic volume,
 216 this is known as one of the reasons for accidents involving collisions between vehicles [35]. However,
 217 previous studies have not shown the clear relationship between traffic volume and SVA, especially on
 218 the city expressway. Thus, this study analyses the relationship between SVA and traffic volume by use
 219 of Annual Average Daily Traffic (AADT). Moreover, AVS is utilized for the analysis. Generally speaking,

220 the vehicle speed is widely believed to be a key issue in the cause of road traffic accidents. Tanishita
 221 and Wee [4] focused on reducing speed on the rural expressway in Japan and they demonstrated the
 222 highest probability of an accident occurring is when speed reduces from 110 to 85 km/h. However,
 223 speed limitations on the rural expressway and the city expressway are quite different. Therefore, this
 224 study aims to identify the relationship between the vehicle speed on Metropolitan Expressway (which
 225 is the city expressway) and SVA. This study uses AVS as a criterion for expressing vehicle speed each
 226 year in each location. For the skid resistance of a pavement, although the relationship between the skid
 227 resistance and the risk of road accidents are tangible, as mentioned before, a measurement has not
 228 been conducted on the Metropolitan Expressway for many years. The Metropolitan Expressway was
 229 originally built to secure the transport capacity for the Tokyo Olympic Games in 1964. At that time, most
 230 parts of it were constructed over small water channels and limited public land. As a result, there are
 231 many sharp curves as well as many branching and merging points in a short section. Thus, MECL has
 232 placed heavy emphasis on countermeasures for road safety in consideration of the road alignment.
 233 They did not, however, consider the skid resistance. More recently, MECL has started to focus on the
 234 skid resistance to reduce SVA because those accidents have become more serious in recent times.
 235 Although the data for skid resistance have not been measured in whole road sections of the
 236 expressway, the data have been measured in places where SVA often occurs. The measurement
 237 frequency ranges from once a year to once every 10 years. In this study, 79 sets of data for the skid
 238 resistance of a pavement are obtained. To determine the effect of quantitative road factors, road curve
 239 radius is utilized. In addition, all locations in focus are curved sections, as demonstrated in Figure 4. In
 240 fact, most SVA happens in curve sections. Thus, in this part of the analysis, each curve radius in each
 241 curved section is determined. Table 2 provides general information for the input data used in the
 242 analysis, the raw data has been cleaned for analysis, and there are 30 locations and 10 years of data
 243 giving 300 data points. In addition, AADT, AVS, skid resistance and curve radius are set as independent
 244 variables; and the number of SVA is set as an explanatory variable.

245 *Table 2. Summary of the data focused on in the study.*

Input data	Number of data	Mean	Minimum	Maximum	Standard deviation
Number of SVA (accidents/year)	300	13	0	309	58
AADT (vehicles/day)	300	35,600	2,200	69,700	14,800
AVS (km/h)	300	58.2	25.7	80.6	12.3
Skid resistance (coefficient of friction: non-unit)	79	0.38	0.02	0.63	0.10
Curve radius (m)	300	118	66	309	58

246

247 5. Data Analysis and Results

248 This section contains the analyses of the input data by using Pearson's Correlation analysis method.
 249 This study focuses on four (4) different types of independent variables such as AADT, AVS, skid
 250 resistance and curve radius. Table 3. demonstrates the correlation coefficient of each other variable.
 251 Generally, if the absolute correlation coefficient between two different variables is more than 0.8, then
 252 multicollinearity is a problem [36]. Thus, there is low possibility of multicollinearity occurring in the case
 253 of using those four (4) types of variables.

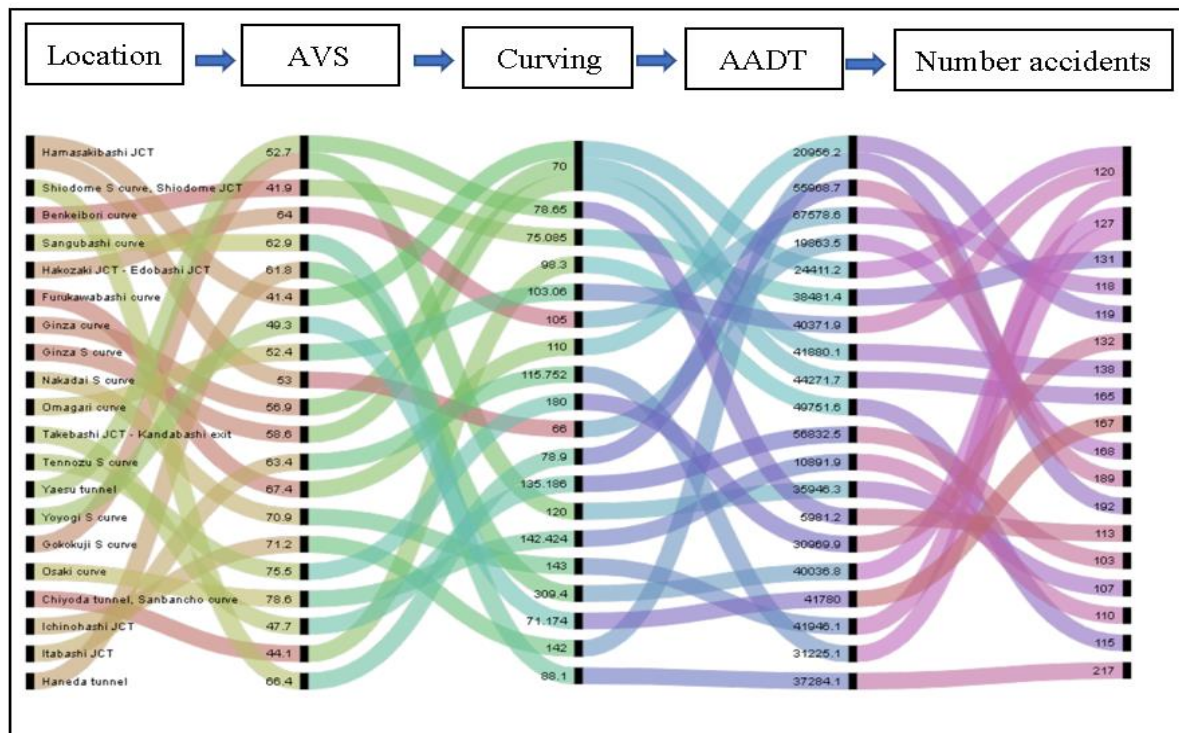
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Table 3. Correlation coefficient of four (4) types of independent variables focused on in the study.

	AADT	AVS	Skid resistance	Curve radius
AADT	-	-0.14	0.15	0.08
AVS	-	-	-0.18	0.33
Skid resistance	-	-	-	0.27
Curve radius	-	-	-	-

256
257

258 The correlations of the data in terms of uncertainty parameters, which include weather conditions,
259 AADT, AVS and skid resistance, with the number of SVA, are analysed. This can be seen in Figure 4,
260 which shows the overlapping of factors and the complexity level between them.



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Figure 4. This visualization alluvial diagram shows examples of the data set and the complexity between the factors that need to be analyzed.

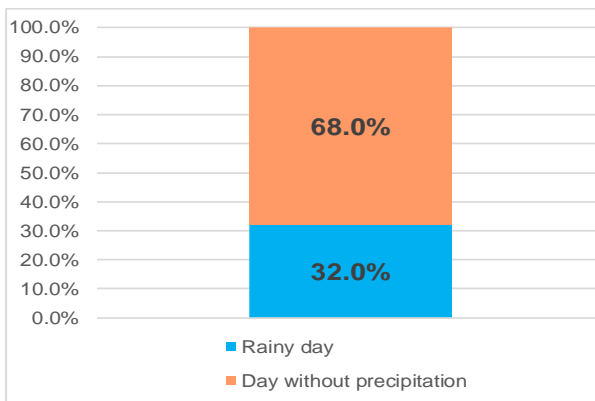
263 First of all, for weather conditions, Figure 5 shows the ratio of rainy days and days without
264 precipitation from 2009 to 2019, according to Japan Meteorological Agency [37]. In addition, Figure 6
265 demonstrates the ratio of three (3) types of road surface conditions at the time of accidents for the
266 analyzed period. According to those data, rainy days account only for about 30% of a year, however,
267 the road pavement surface in wet conditions dominates SVA by more than 75%. This aligns with a study
268 by Theofilatos and Yannis [34], which stated that road traffic accidents are more likely to happen on
269 rainy days than on the days without precipitation. Therefore, it is noted that the accidents are closely
270 related to weather conditions. This study then focuses on wet pavement conditions related to rainy days
271 and also dry pavement conditions, which means days without precipitation, in order to benchmark the
272 relationships between SVA and both uncertainty parameters and road condition aspects. With respect
273 to the traffic volume, Figure 7 shows the relationship between AADT in each place and the number of
274 SVA. Using the linear approximation best-fit in Figure 8, the number of SVA appears to climb with an
275 increase in AADT. However, the correlation is quite weak. The correlation coefficient between those
276 two aspects is almost 0. However, in the case of dry pavement surface conditions, the correlation
277 coefficient increases to 0.3, as shown in Table 4 and Figure 8.

278 Regarding the influence of ESAL, Figure 9 shows the relationship between ESAL in each place
 279 and the number of SVA (Number of single-vehicle accidents per year/place), which displays the number
 280 of SVA as a meagre increase with the increase in ESAL, but this link is not strong evidence, at least at
 281 this stage of data. In addition, the factors of pavement surface conditions (wet /dry) data do not produce
 282 an adequately clear relationship (see Figure 10).

283 In terms of the vehicle speed, although there is an unclear relationship with SVA demonstrated in
 284 Figure 11, a positive correlation between AVS and the number of SVA under wet pavement conditions
 285 can be observed, as demonstrated in Figure 12. Considering the skid resistance of a pavement surface,
 286 there appears to be a negative correlation between the skid resistance and the number of SVA, as
 287 illustrated in Figures 13 and 14, and also the increase between ESAL and skid resistance in Figure 15.
 288 In other words, the number of SVA reduces with an increase in the skid resistance, especially in wet
 289 pavement conditions.

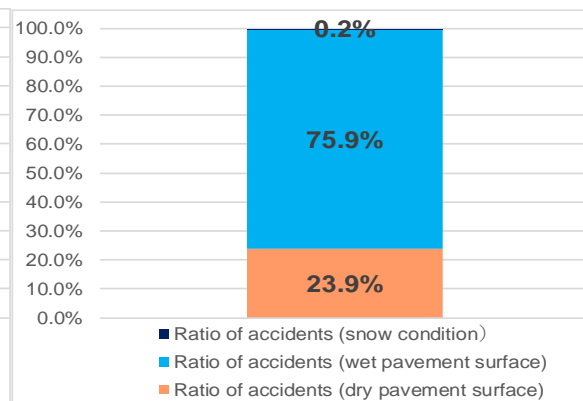
290 In addition, the curve radius can be used to represent the road quantitative factor, which is a
 291 physical parameter of road conditions. Figure 16 shows the relationship between the curve radius and
 292 the number of SVA in each location. Although there is very little connection between those two factors
 293 in Figure 16, a negative correlation can be observed to some extent in the case of dry road surfaces
 294 shown in Figure 17. In order to understand the relationships mentioned above, Table 4 demonstrates
 295 the correlation coefficients between the number of SVA and each conceivable factor. Although some
 296 correlations are clear in some cases, it is difficult to determine a clear association, since the biggest
 297 correlation coefficient is 0.3 at most. Therefore, further essential analysis is conducted by using cross-
 298 tabulation analysis, as provided in the next section.

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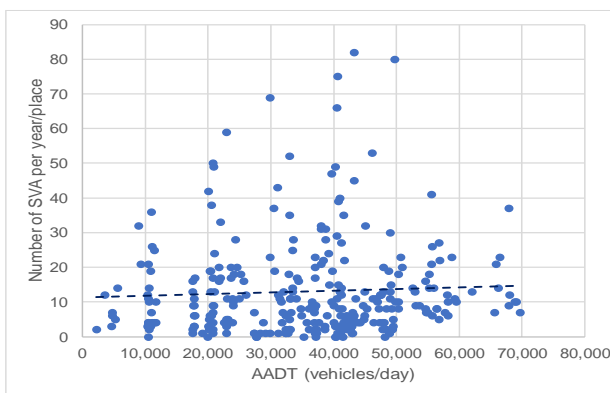
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301 *Figure 5. Ratio of rainy days and other days.*

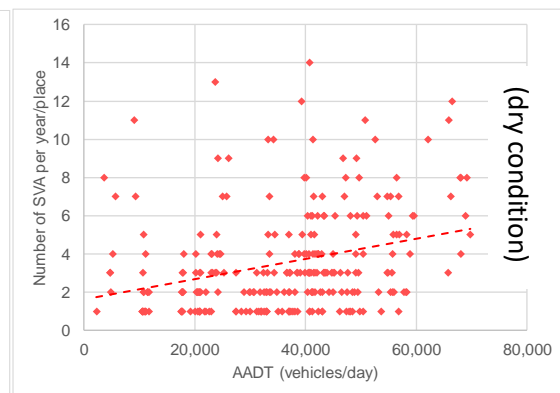


301

Figure 6. Ratio of each road surface condition at the time of SVA.

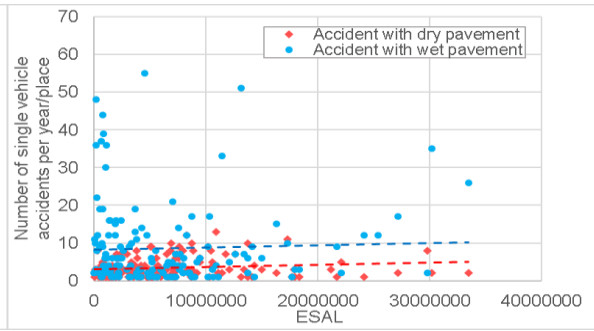
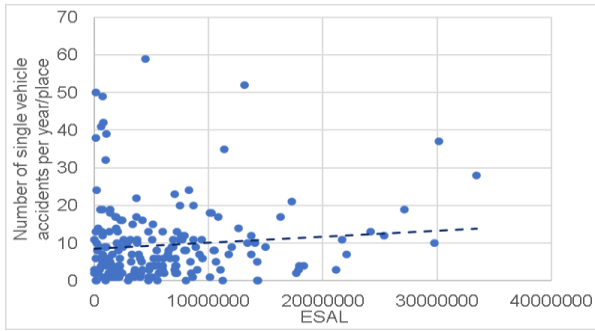


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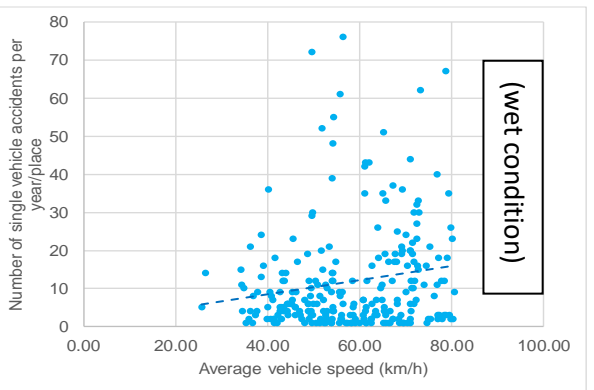
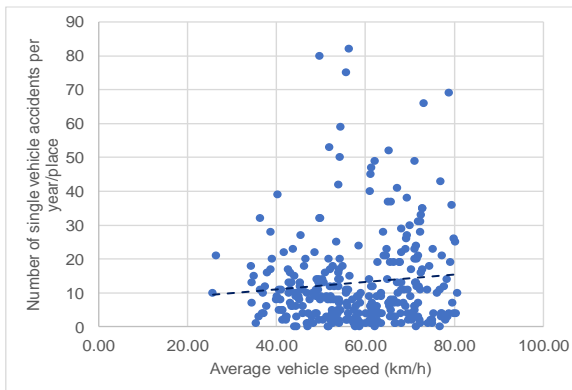
303

Figure 7. Relationship between AADT and the number of SVA. Figure 8. Relationship between AADT and the number of SVA (dry condition)



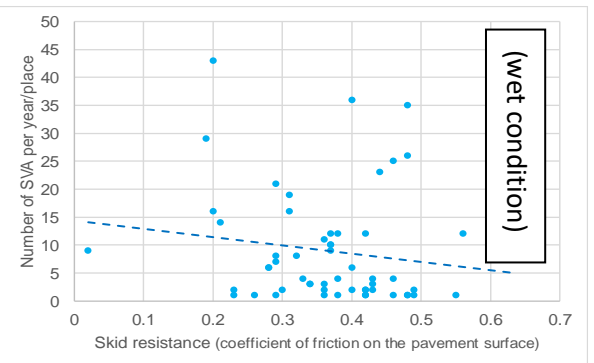
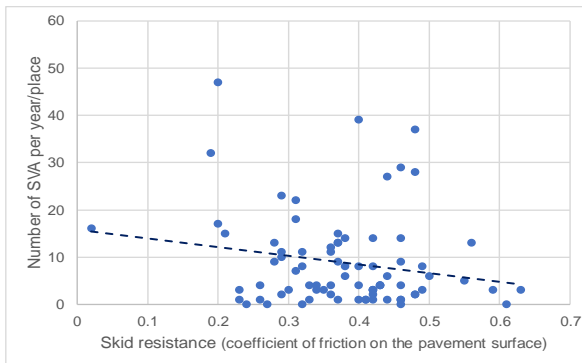
304

305 *Figure 9. Relationship between ESAL and the number of SVA. Figure 10. Relationship between ESAL and the number of SVA*
 306 *(dry/wet) condition.*



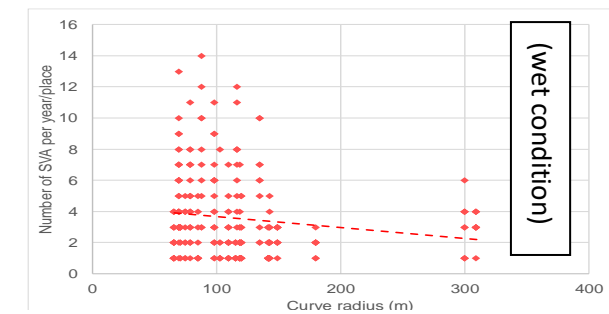
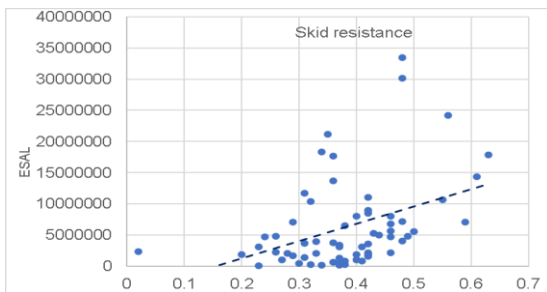
307

308 *Figure 11. Relationship between AVS and the number of SVA. Figure 12. Relationship between AVS and the number of SVA.*



309

310 *Figure 14. Relationship between skid resistance on the pavement surface and the number of SVA. Figure 13. Relationship between skid resistance on the pavement surface and the number of SVA.*



311

312 *Figure 16. Relationship between Skid resistance and ESAL. Figure 15. Relationship between curve radius and the number of SVA.*

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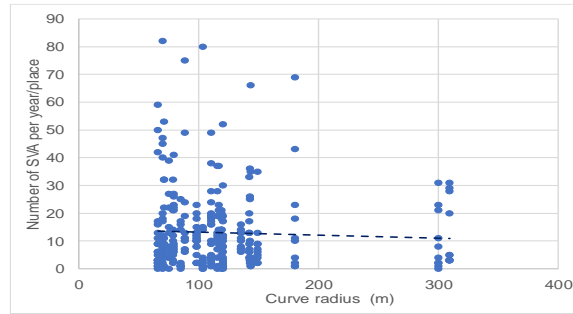


Figure 17. Relationship between curve radius and the number of SVA.

Table 4: Coefficient of correlation between the number of SVA and conceivable aspects.

SR= Skid resistance CR = Curve radius	Uncertain Aspects			Quantitative road aspect
	AADT	AVS	SR	CR
Number of SVA	0.1	0.1	-0.2	0.0
Number of SVA (Dry condition)	0.3	-0.2	0.0	-0.2
Number of SVA (Wet condition)	0.0	0.2	-0.2	0.0

323 **6. Cross Tabulation Analysis and Results**

324 The relationships between the number of SVA and several key factors are shown in Figures 18-
325 25. Here, each factor can be divided into groups based on probabilistic criteria. The results without skid
326 resistance are divided into two parts by adopting the criteria below. For the results with skid resistance,
327 MECL has not considered such factors and there are no specific criteria for justification. Thus, the skid
328 resistance is excluded from the group.

- 329
- 330 ● The criterion of AADT
331 30,000 vehicles/day can be the criterion, in 30 places focused is about 30,000 vehicles/day.
 - 332 ● The criterion of AVS
333 60km/h can be the criterion because it is the speed limit on most routes on the Metropolitan
334 Expressway [3][4]
 - 335 ● The criterion of curve radius
336 Curve radius of 100m can be the criterion because MECL defines the curve section of which curve
337 radius is less than 100m as a sharp curve, while the curved section needs to have fences, which
338 stops every vehicle falling off the expressway.

339

340 Then, each correlation coefficient is calculated between the number of SVA and each factor categorized
341 by the criteria defined above. As a result of the analyses, Table 5 is obtained. These analyses focus on
342 the correlation coefficient that is more than 0.3. Mukaka [38] stated if a correlation coefficient is 0.3 after
343 excluding outliers, it may be interpreted as a weak positive correlation. In this case, outliers are
344 considered to be excluded after the cross-tabulation calculation is applied. Strength of correlations is
345 shown by different colors in Table 5. In most cases, the coefficient tendencies are dependent on
346 pavement conditions. However, only in the case of curve radius being less than 100m is the correlation
347 between the number of accidents on both dry and wet pavements and skid resistance negative. In other
348 words, the number of SVA reduces with the increase in skid resistance in the curved sections with a
349 radius less than 100m. This is a new finding for MECL. The results obtained from the calculation are
350 summarized below.

- 351 ● Summarized results in **dry** pavement conditions
- 352 In the case of AVS being more than 60 km/h
- 353 ✓ The number of SVA could increase with an increase in AADT
- 354 In the case of curve radius being more than 100 m
- 355 ✓ The number of SVA could increase with an increase in AADT
- 356 In the case of curve radius being less than 100 m
- 357 ✓ The number of SVA could fall with an increase in skid resistance
- 358 ● Summarized result in **wet** pavement conditions
- 359 In the case of AVS being less than 60 km/h
- 360 ✓ The number of SVA could fall with an increase in skid resistance
- 361 In the case of curve radius being more than 100 m
- 362 ✓ The number of SVA could increase with an increase in AVS
- 363 In the case of curve radius being less than 100 m
- 364 The number of SVA could fall with an increase in skid resistance

Table 5 Calc results of Pearson's correlation coefficient between SVA and each aspect.

		Pavement condition	Uncertain Aspects			Quantitative road aspect	
			AADT	AVS	SR	CR	
SR= Skid resistance							
CR = Curve radius							
D= Dry surface							
W= Wet surface							
Uncertain aspects	AADT (>30000 vehicles/day)	D	-	0.0	-0.1	-0.2	
		W	-	0.2	-0.2	0.0	
	AADT (<30000 vehicles/day)	D	-	-0.5	-0.1	-0.4	
		W	-	0.2	-0.2	0.2	
	AVS (+60km/h)	D	0.5	-	0.1	-0.2	
		W	0.0	-	-0.1	0.0	
		AVS (-60km/h)	D	0.1	-	-0.1	-0.1
			W	0.0	-	-0.3	-0.2
Quantitative road aspect	Curve radius (+100m)	D	0.6	-0.2	0.1	-	
		W	-0.1	0.3	0.1	-	
	Curve radius (-100m)	D	0.1	0.0	-0.3	-	
		W	0.1	0.1	-0.5	-	

367

368 7.1 Results of correlation in dry pavement condition:

369

370 Case 1: AADT is less than 30,000 vehicles per day.

371

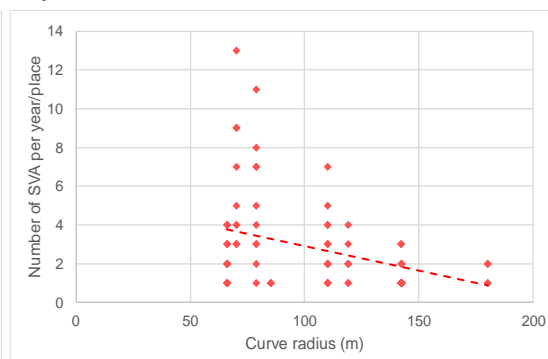
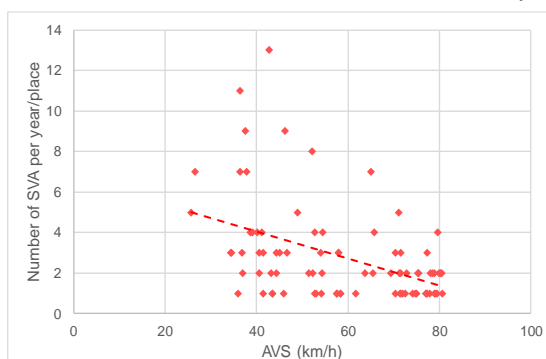
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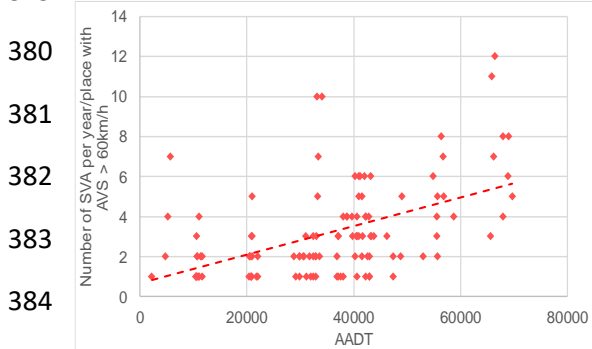
377 Figure 18. Relationship between AVS and the number of SVA with AADT < 30,000

Figure 19. Relationship between curve radius and the number of SVA with AADT < 30,000

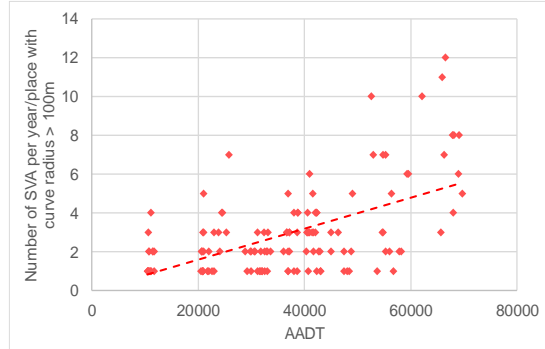
378 Case 2: AVS is more than 60 km/h

379

Case 3: Curve radius is more than 100 m

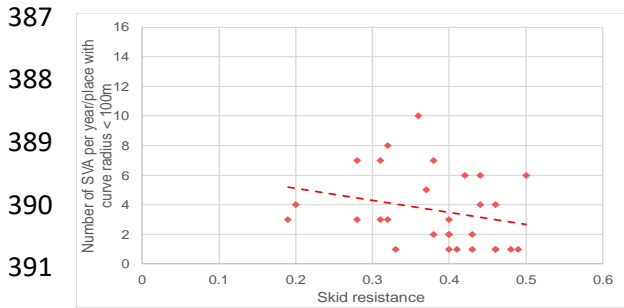


385 Figure 20. Relationship between AADT and the number of SVA with AVS +60km/h



385 Figure 21. Relationship between AADT and the number of SVA with curve radius > 100m

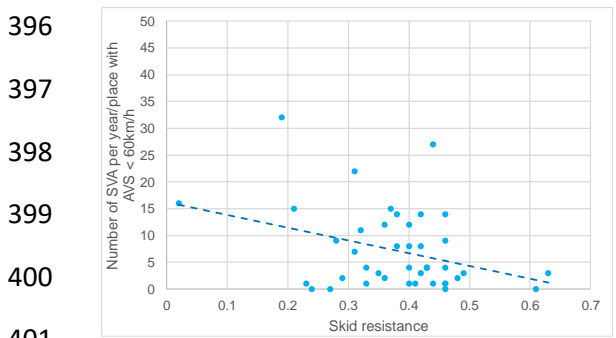
386 Case 4: Curve radius is less than 100 m.



392 Figure 22. Relationship between the skid resistance and the number of SVA with curve radius < 100m

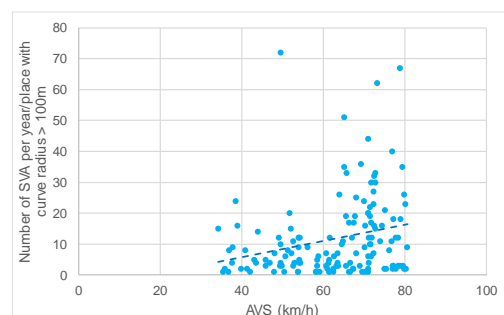
394 7.2 Results of correlation in wet pavement condition

395 Case 5: AVS is less than 60 km/h



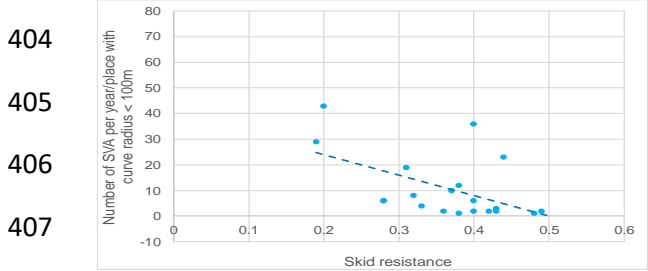
401 Figure 19. Relationship between the skid resistance and the number of SVA with AVS < 60km/h

Case 6: Curve radius is more than 100 m



401 Figure 18. Relationship between AVS and the number of SVA with curve radius > 100m

403 Case 7: Curve radius is less than 100 m



405 Figure 20. Relationship between the skid resistance and the number of SVA with curve radius < 100m

408 **7. Multiple regression analysis and results**

409 The effect on SVA of the combination of factors has been identified using multiple regression analyses.
 410 The previous section has determined Pearson’s correlation coefficients between SVA and each factor.
 411 It is found that the relationship between SVA and each factor has become increasingly clear. This
 412 section focuses on the factors, which have been confirmed to have a correlation with SVA through
 413 Pearson’s correlation coefficients. Firstly, the variable combination of the correlation coefficients which
 414 are more than 0.5, as shown in Table 5, is analyzed. Then, Table 6 can be obtained. The figure
 415 illustrated in Table 6 shows multiple regression coefficient R-squared “R²” and the independent
 416 variables used in the calculation. Nau [39] stated that, “if the dependent variable is a properly
 417 stationarized series, then an R-squared of 25% may be quite good”. Of course, the required size of an
 418 R-squared depends on the variable with respect to a measurement. According to Table 6, most of the
 419 R-squared values are more than 25%. However, it is not obvious whether there is a definite correlation
 420 between SVA and the variables. Therefore, this section aims to carry out a further analysis by using 3
 421 different independent variables with the consideration of previous results, as shown in Table 5.
 422 Moreover, the correlation coefficients, which are more than 0.3, are focused. As a result of the
 423 calculation, Table 7 can be obtained. Considering the dry pavement condition, each R-squared value
 424 is less than the previous result shown in Table 6. On the other hand, R-squared values in wet pavement
 425 conditions are relatively high. The results are clearly shown in Table 8 and 9. If a p value less than 0.05
 426 has been considered statistically significant, AVS is the most influential factor according to a t-statistics
 427 and a p value in Table 8, then, the skid resistance is the most influential factor in Table 9. This result is
 428 new to MECL and will influence the maintenance policy in Tokyo. Further interpretation of the analysis
 429 results can be seen in Table 10.

430 *Table 6: Calculation result of multiple regression analysis with 2 independent variables.*

Pavement condition	Variable condition				Variable			
	AADT	AVS	SR	CR	AADT	AVS	SR	CR
Dry	<30,000 vehicles/day	–	–	–	–	R²=0.23	–	–
	–	+60 km/h	–	–	R²=0.26	–	–	–
Wet	–	–	–	+100 m	R²=0.31	–	–	–
	–	–	–	-100 m	–	–	R²=0.28	–

431 *Table 7.: Calculation result of multiple regression analysis with 3 independent variables*

Pavement condition	Variable condition				Variable			
	AADT	AVS	SR	CR	AADT	AVS	SR	CR
Dry	<30,000 vehicles/day	–	–	–	–	R²=0.23	–	–
	<30,000 vehicles/day	+60 km/h	–	–	–	–	–	R²=0.21
Wet	–	+60 km/h	–	+100 m	R²=0.13	–	–	–
	–	-60 km/h	–	+100 m	–	–	R²=0.66	–
	–	-60 km/h	–	-100 m	–	–	R²=0.41	–

432 Table 8. Result of multiple regression analysis in the case of AVS -60km/h & curve radius +100m

	Coefficient	Standard error	t statistic	P value	Lower 95%	Upper 95%
Intercept	50.65	14.29	3.55	0.01	15.69	85.60
Curve radius	-0.06	0.02	-2.42	0.05	-0.11	0.00
Skid resistance	-15.80	8.47	-1.87	0.11	-36.52	4.92
AVS	0.64	0.23	2.80	0.03	1.21	0.08

434 Table 9. Result of multiple regression analysis in the case of AVS -60km/h & curve radius -100m

	Coefficient	Standard error	t statistic	P value	Lower 95%	Upper 95%
Intercept	33.79	35.10	0.96	0.35	-41.50	109.08
Curve rad	0.24	0.37	0.66	0.52	-0.55	1.04
Skid R	-63.80	23.67	-2.70	0.02	-114.57	-13.03
AVS	-0.40	0.34	-1.19	0.25	-1.13	0.32

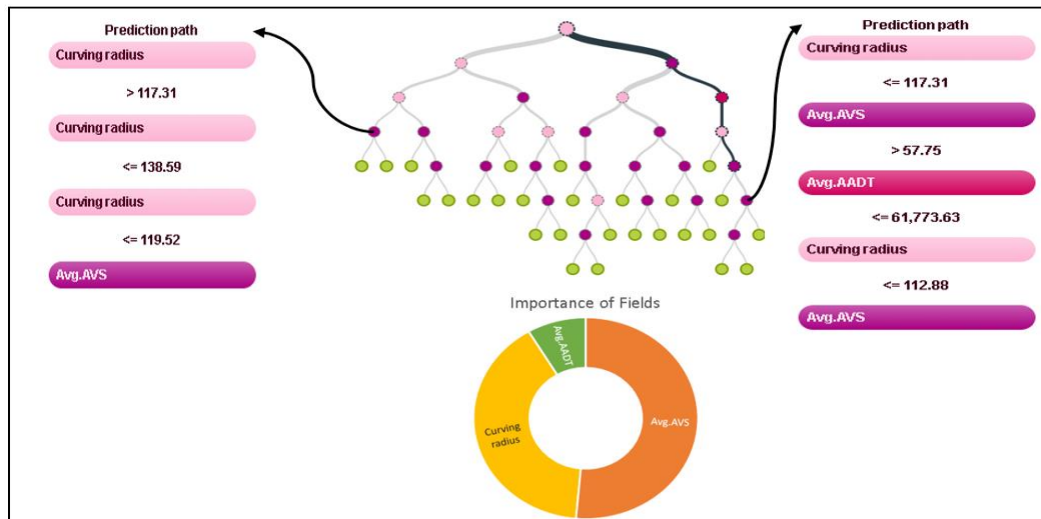
436 Table 10. Interpretation of the analysis result

Condition		Results
AVS	Curve radius	
Less than 60 km/h	More than 100m	SVA increases with an increase in AVS
	Less than 100m	SVA reduces with an increase in skid resistance of a pavement

438 **8. Machine learning analysis**

439 The conventional traffic road safety accident records and analyses have opinions of experts and
 440 human interventions and this creates a lack of structure and ambiguity in the research-practice
 441 relationship [40][41]. Supporting the automation process with a decision-maker and covering more data
 442 in the system in real-time is the future direction with huge dynamic changes, including drivers'
 443 behaviors, severe weather, and smart transportation. Therefore, as a part of this study, ML has been
 444 conducted. The ML methods provide innovation trends, create models to find the accident-prone zone
 445 and different accident-factors, and mines to determine the association between these factors. The data
 446 mining is expected to overcome shortcomings produced by the Statistical analyses [42]. The data-driven
 447 methods have the potential to handle extremely large amounts of data and provide a high level of
 448 prediction accuracy y in the highway-safety analysis [43]. The techniques to be used in this study are
 449 clustering and classification, which have been used for analysis of the road accidents [44][45]. These
 450 analyses have shown the ability to help the transport authorities in improving safety requirements and
 451 recognizing the accidents' root causes [46]. Moreover, ML models have been proven as an effective
 452 analytical tool for the multiple factors associated with Road Safety [47][48].

453 In the beginning, cleaning and normalizing the data are carried out to run the models for
 454 predictions, where the input is set as predictors targeting one output, such as the number of accidents
 455 or predicting the locations of an accident, and the method provides many prediction paths for different
 456 factors. However, the limit of the data appears as a challenge and proves the importance of gathering
 457 more data for future technologies. This is important for learning and validation of well-balanced analytics
 458 and avoiding both overfitting and underfitting, where reliable predictions are essential. In training/ testing
 459 data split by choosing subsets for generating the 80%/20% and 60%/40% split of the dataset (two
 460 splitting data ratio), the 20% & 40% test data are not part of the training subset and are applied to predict
 461 and test the performance. For exploring the hidden patterns and analysis, the decision tree (DT) model
 462 prediction has been conducted as a machine learning (ML) theory. The decision tree has the power to
 463 simplify the data depending on the available attributes by rules to find a prediction path. Moreover, there
 464 are more selections to model and predict utilizing other predictors and many options for inputs for future
 465 research (see Figure 26).



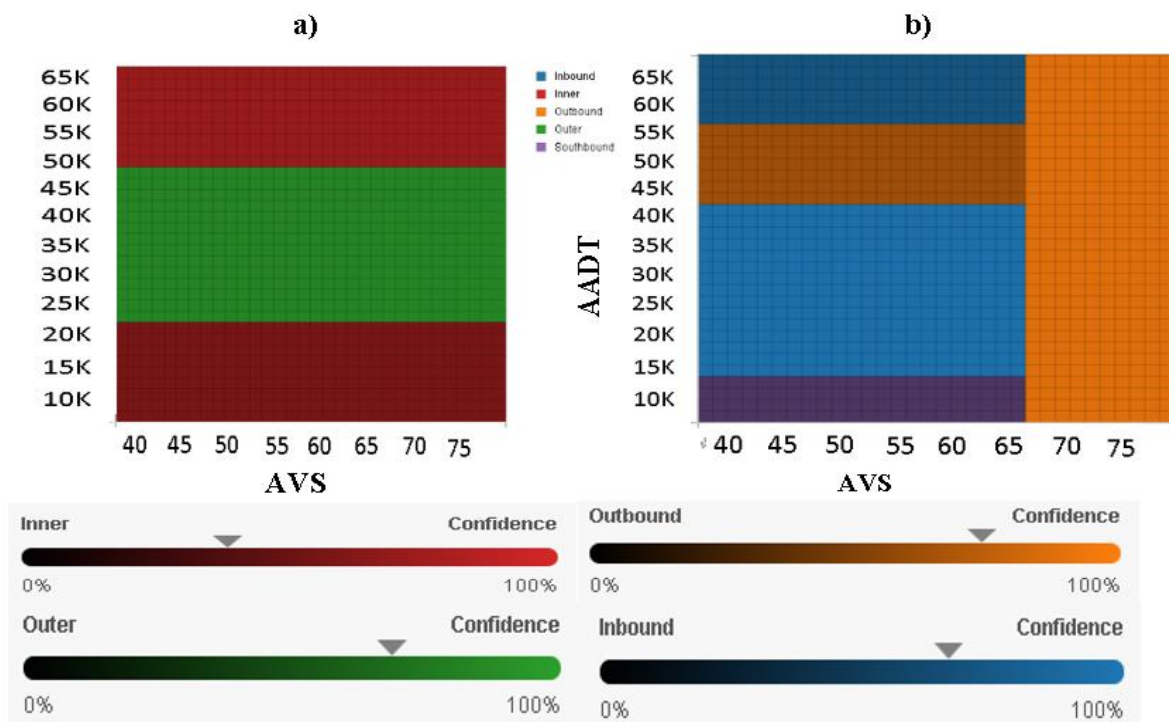
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467

Figure 21. The DT, with an example showing the prediction paths and analyzing the data set.

468 The DT is secondary here for proving the power of ML in analyzing safety data which enables one to
 469 review and visualize descriptive statistics of the dataset. However, this method requires big data to
 470 obtain maximum benefit in analysis. This use of ML emphasizes one of the primary safety concepts,
 471 which is that lessons must be learned from the accidents but there must also be benefits from
 472 technology in the field. The model reaches 83.3 % and 75% accuracies for 80%/20% and 60%/40%
 473 splits, respectively, with the inbound direction as the positive class, while the data set has four rules
 474 linked to the accidents: inbound, inner, outbound, and outer (see Figure 27).

475 Three groups have been found to be related to AADT (<=23k,23-50k,>=50k) and to the AVS for specific
 476 locations selected as inputs for the predictions. Multiple options can be generated, and precise
 477 thresholds have been found in the complex relations which manifest the power of ML.



478

479

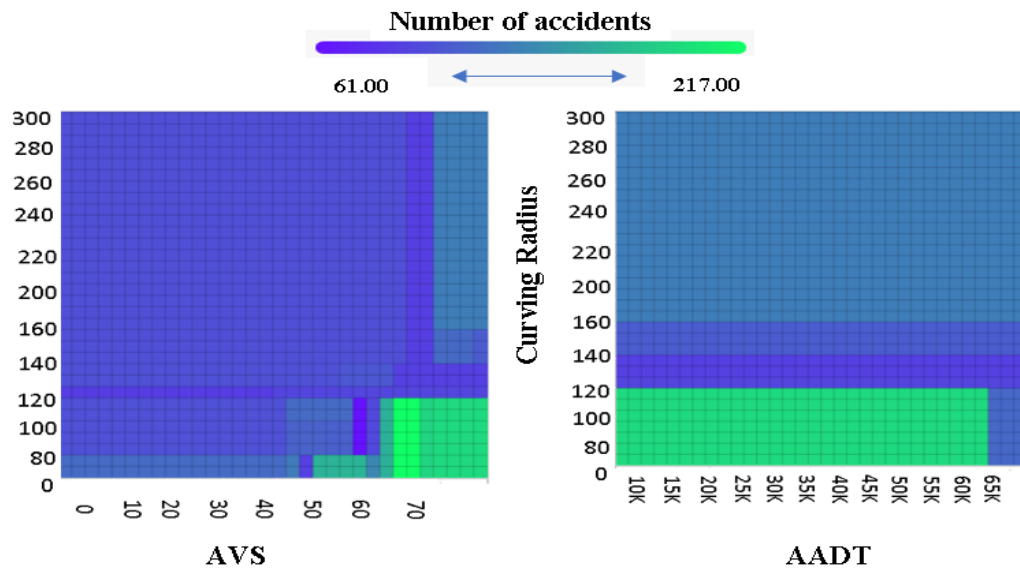
480

Figure 22. The Partial Dependence Plots (PDP) targeting the direction shows the marginal effect of inputs of cases on the predicted results of the ML, a) Inner Circular Route, b) Route 2 Meguro Line

481 There are some specific spots linking the inputs with the number of accidents. For instance, the
 482 AVS above 60 km/h and curving radius below 119 m forms an apparent effect for the number of
 483 accidents, for example, number of accidents is predicted to be 165 with curving radius 111.6m, which
 484 was a 95 with 119.2m. Also, this linked to AVS, where the speeds over 46.6 km/h have been noted as
 485 critical points for increased accidents and others highlighted points over speeds 61.4 km/h, with fixed
 486 input of AADT 30.8K.

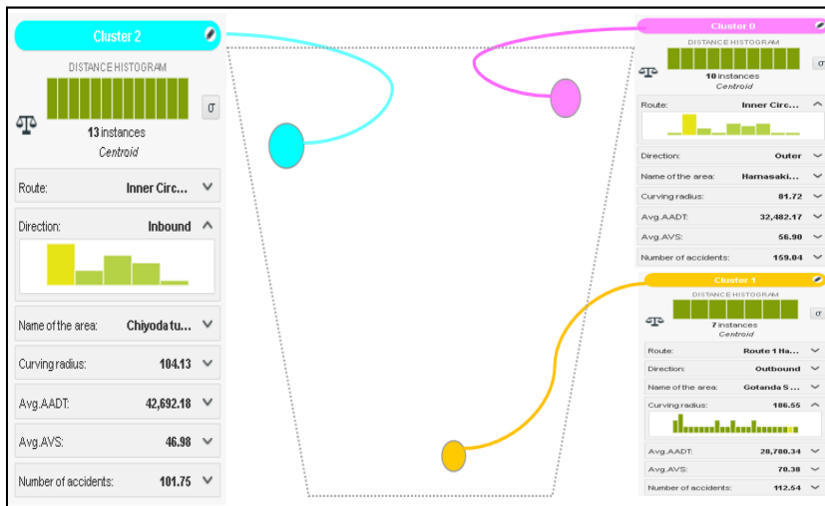
487 The factor AVS and curving radius have more importance in that field and the analysis proves they
 488 are strong predictors.

489 Moreover, many slides of relations between the inputs can be produced for each assuming
 490 selected contributions; this method of ML is essential for designers and analyzing the safety data
 491 accurately. This analysis closely matches and confirms the previous study in that AVS has influences
 492 on SVA, and AADT and curve radius affects SVA. The sharp curves and increased AADT are factors
 493 presenting as dominating the number of accidents (see Figure 28).
 494



495 *Figure 23. The Partial Dependence Plots (PDP), shows the marginal effect of inputs of cases have on the predicted results of ML, a) Input*
 496 *AADT = 3082.38, b) Input AVS = 58 Km/h.*
 497

498 For a further exposition of ML techniques in such cases, a clustering method is applied as intelligent
 499 methods used to present and extract data groups of interest are searched. It is shown that ML is a
 500 powerful analysis method for safety. To analyze the unsupervised dataset, ML is chosen with the K-
 501 means algorithm (canonical clustering), where the number of clusters is three. However, the remainder
 502 of the work is supervised ML. Utilizing cluster analysis involves separating datasets into subsets of
 503 instances (clusters), and the algorithm affirms similarities and that the groups are closer to one another
 504 if they are more similar and farther away if they are dissimilar (see Figure 29 and Table 11).



505

506

Figure 29. The 3-cluster diagram nodes and histograms.

507

Table 11. The details of the clusters.

Centroid name	Instances	Minimum inter-centroid	Mean inter-centroid distance	Maximum inter-centroid	Distance sum squares	Distance standard deviation	Distance sum	Distance median	Distance maximum	Distance minimum	Distance variance	Distance mean
Cluster 0	10	0.78	0.87	0.96	4.20	0.17	6.27	0.61	0.92	0.42	0.03	0.63
Cluster 1	7	0.93	0.95	0.96	3.22	0.17	4.61	0.67	0.89	0.39	0.03	0.66
Cluster 2	13	0.78	0.86	0.93	5.78	0.19	8.32	0.64	1.13	0.38	0.04	0.64

508

509 The prediction targets provide various analysis and different levels of accuracy, which present
 510 that the ML is a powerful tool for predictions and advance analytics. Thus, comparison of the
 511 models has been conducted (See Table 12). The Random Forest (RF), Gradient Boost (GB),
 512 Support Vector Machine (SVM) and optimal Ensemble respectively show better accuracy.

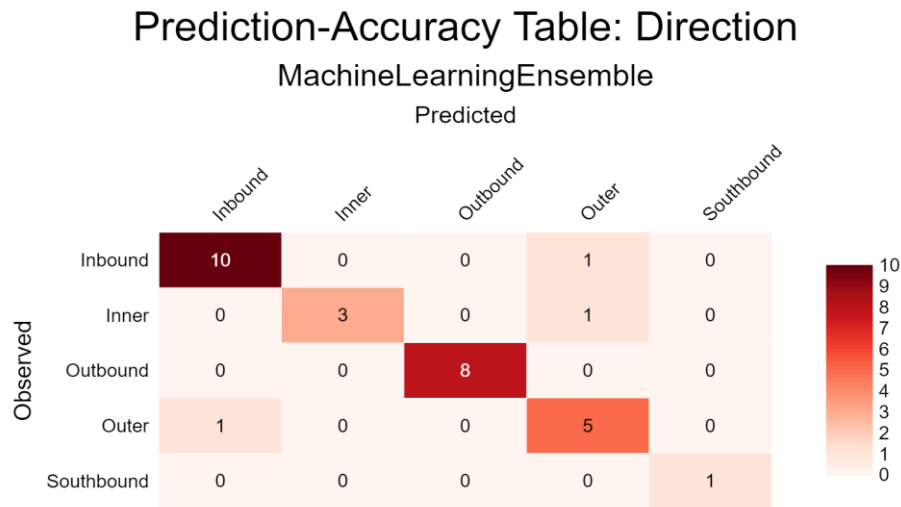
513 Table 11: The comparison of four (4) models and Ensemble with training data set and the optimal ensembles: model 2(Gradient Boost).

	Underlying model	Model type	Training RMSE	Training R ²
Model 1	RandomForest	trees = 500	0.11	0.7891
Model 2	GradientBoost	booster = gbtrees	0.04	0.9791
Model 3	SupportVectorMachine	cost = 1	0.17	0.5343
Ensemble	Ensemble	All models	0.10	0.8269
Optimal Ensemble	Ensemble	Optimal	0.04	0.9791

514

515 From the comparison models, the model spots the areas correlated to the safety factors.
 516 Some areas are predicted as more affected by factors and number of accidents than others. For a
 517 diagnostic, the heat map shows the observed and the predicted values (confusion matrix) and
 518 presents the prediction accuracy (see Table 14).

519 Table 12: The Prediction-Accuracy table showing the observed and predicted values, as a heatmap for the ensemble model as the routes are
 520 output.



Fitted model (comparison): n = 24 cases used in estimation (Training sample); 30 observed/predicted pairs with 90% accuracy;

521

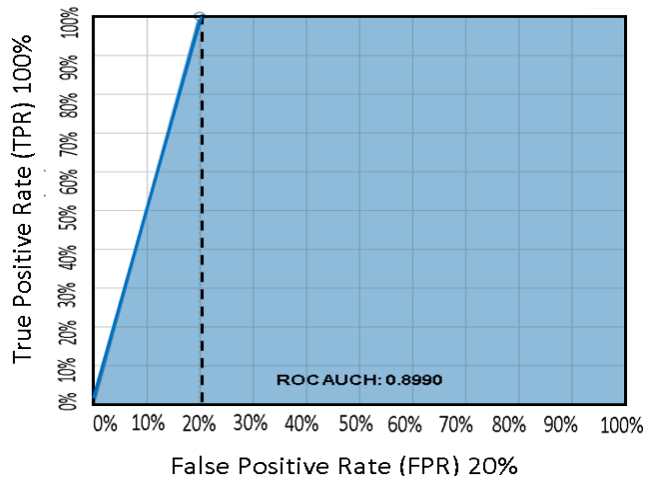
522 From the DT model the model is validated and the outcomes of the prediction are labelled as either
 523 positive or negative. If the prediction is positive and the actual value is also positive, then it is called a
 524 true positive (TP); with the same concepts, false positives (FP), true negatives (TN), and false negatives
 525 (FN) are realised. The four outcomes can be formed as a confusion matrix, with acceptable confidence
 526 values shown below (see Table 15).

527 Moreover, the area under the curve (AUC) was measured under the ROC curve. The decision tree
 528 achieves higher AUC values of 0.89 (see Figure 30).

529

Table 13. The evaluation results of the performance per class in the confusion matrix.

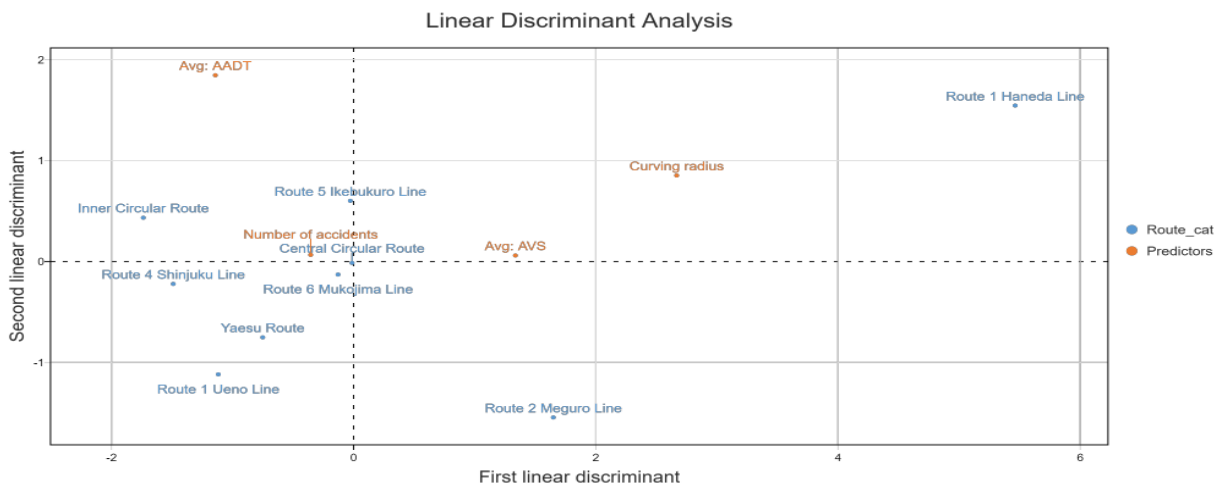
ACTUAL VS. PREDICTED	Inbound	NEGATIVE CLASS	ACTUAL	RECALL	F	Phi		
INBOUND	1	0	1	100%	0.67	0.63		
NEGATIVE CLASS	1	4	5	80%	0.89	0.63		
PREDECTED	2	4	6	90% AVG.RECALL	Avg. F = 78 %	Avg.Phi = 0.63		
PRECISION	50%	100%	75 % AVG. PRECISION	83.33% ACCUARCY	TP	FN	TP	TN



530

531 *Figure 24. The ROC curve, which shows that the area under the curve (AUC) is 0.89, evaluates the model with 80% training data vs. 20% test*
 532 *data.*

533 ML has beneficial and precise information presenting the ability to advance analysis compared
 534 with the traditional statistical analysis. From the LDA model, the AVS and AADT inputs have more effect
 535 on the number of accidents displayed as near points; also, the curving radius (CR) and AVS are inputs
 536 influencing some locations together (see Figure 31).
 537



538 *Figure 31. The Scatterplot from the LDA model targeting routes and four predictors (CR, AADT, AVS and the number of accidents).*

539 ML is one of the industry's future revolutions. Likewise, there is the benefit of learning and reduction
 540 of human error and intervention through configuration with the smart life (autonomic-smart cities), long
 541 term advantages that can be gained with such an application [49][50].

542 Finally, The ML is not just a prediction tool as it has other merits, including the visualization of data,
 543 learning and real-time analysis for assisting the decision-maker in a proactive way.

544 **9. Discussion**

545 This study determines influential factors of SVA and the combinations of the factors that have
 546 a significant effect on SVA. It also demonstrates that the skid resistance is the main influential
 547 factor under various conditions. Furthermore, this study determines whether there is a relationship
 548 between ESAL and skid resistance.

549 In addition, according to TRL [51], their pavement design manual “Oversea Road Note 31”
550 specified Equivalent Single Axle Load (ESAL) as the pavement design factor. In fact, MECL has
551 never tried to quantify the relationship, so this study provides new insights for MECL in order to
552 update its practice; plus, skid resistance in the Metropolitan Expressway is not measured regularly,
553 and ESAL is also not available on a yearly basis. Thus, the relationship between ESAL and skid
554 resistance might not be precisely identified. Furthermore, pavement material can be very different
555 in each location depending on the local source of materials. These aspects could influence the
556 results. Therefore, to identify the relationship between ESAL and skid resistance is a future task,
557 and it is recommended that continuous observation of skid resistance be conducted to solve this
558 issue [51][52][53][22]. Finally, from the DT analysis, the methodology of ML is a promising
559 technique that can genuinely capture the variety of patterns from safety road data and overcome
560 uncertainty. Some benefits can be explored and used in the future, such as real-time analysis and
561 decision-maker support. The application of ML opens new doors to gathering more data and
562 applying valuable inputs that can present a wider picture of accidents. The technique leads to
563 automation of the field and allows the process to be smarter. In this case, the importance of
564 gathering more attributes in the future will be essential for the implementation of advanced analysis
565 for reducing SVA [54].

566 10. Conclusions

567 MECL has been established to reduce traffic congestion around the Tokyo area, and traffic
568 congestion has significantly decreased. However, road safety on the expressway has been a big issue.
569 Although there has been a decrease in traffic congestion, the number of single-vehicle accidents (SVA)
570 has increased because AVS has risen. Therefore, this study focuses on SVA and aims to identify the
571 conceivable factors causing SVA from the viewpoint of uncertainty, sustainability and quantitative road
572 factors. The identification of specific local parameters that influence the road safety will improve societal
573 sustainability. Weather conditions, skid resistance, AADT and AVS have been defined as uncertainty
574 parameters. Furthermore, curve radius in each location, which is a representative physical condition of
575 the road, has been defined as a quantitative factor. This study collects 10 years of data sets from 2009
576 to 2019. From the analysis, ML can improve safety, manage risks, analyze and capture the hidden
577 patterns in the data and address accidents. Analyzing road accidents can be performed locally or
578 internationally and presents the root cause of the incidents and the correlations between many factors
579 in different systems accurately. In this study, Pearson’s correlation analysis and multiple regression
580 analysis have been adopted. Then, the influence of ESAL, which has not been considered by MECL so
581 far, is determined using the correlation analysis.

- 582 • First, in Pearson’s correlation analyzes, weather conditions are found to influence SVA
583 significantly. In particular, rainy days, which make the pavements’ surface wet, have caused a
584 large number of SVA or about 6.7 times higher than those incurred in the days without
585 precipitation which forms 68% (see Figure 25). In addition, AADT and curve radius could have
586 an effect on SVA in dry pavement conditions. On the other hand, the combination of skid
587 resistance and AVS could also have an influence on SVA in wet conditions. As a result, the
588 significance of each factor might depend on the pavement condition.
- 589 • Second, another method for correlation analysis called “cross tabulation analysis” has been
590 applied to further understand the detailed characteristics of the correlation. As a result of the
591 analysis, in the case of less than AADT 30000 vehicles/day in dry pavement conditions, it is
592 clear that even if AVS increases, SVA does not increase. On the other hand, a sharper curve
593 radius could increase the number of accidents in the same situation. In wet pavement
594 conditions, SVA could increase with an increase in AVS. In contrast, SVA could fall with an
595 increase in skid resistance.
- 596 • Third, multiple regression analysis is applied based on the correlation results of the cross-
597 tabulation analyses. This analysis aims to identify the significance in terms of the effect on SVA
598 due to the combination of independent variables. Consequently, two statistically meaningful
599 results can be identified. It has become apparent that AVS is an important factor as well as the

600 skid resistance being a very important factor in wet pavement conditions. Consequently, a
 601 suitable management of AVS and skid resistance is considered to be one of the most important
 602 strategies for MECL to mitigate SVA.

- 603 • Fourth, this study ascertains that there is a clear relationship between skid resistance and ESAL
 604 as many other studies identified. It also identifies whether ESAL would be applicable for the
 605 safety management of the Metropolitan Expressway. Based on the result, the relationship could
 606 not be clearly identified. This might be because there were insufficient ESAL data. However, if
 607 monthly data are considered, it can be observed that the skid resistance increases after any
 608 pavement reconstruction.
- 609 • Fifth, the ML is the future technology which provides advanced analysis comparing with the
 610 traditional research (Statistical models) as well as offering precise outcomes and other benefits
 611 supporting decision-making on time and ability to learn from the road safety data.

612 Lastly, considering all of the results, this study could clearly suggest suitable and sustainable
 613 countermeasures corresponding to each of the conditions referred to. The countermeasures are
 614 summarized in Table 17, where the darker the color of the results implies the more likelihood there is it
 615 will occur. When considering the reduction of the number of SVA, accidents in wet pavement conditions
 616 have to be analyzed because the wet pavement conditions can cause the frequency of SVA to be seven
 617 times higher than those in dry pavement conditions. This implies that the skid resistance needs to be
 618 improved, or the facility, which encourages drivers to reduce vehicle speed, needs to be placed in order
 619 to reduce accidents. This study has identified the influential causes of SVA and effective
 620 countermeasures especially in wet pavement conditions. These findings are now provided to MECL
 621 and this policy enables a more sustainable strategy in asset management. Although this study could
 622 not identify a clear relationship between skid resistance and ESAL, the apparent relationship between
 623 SVA and skid resistance has been demonstrated. For future work, the researchers will be focused on
 624 predicting and analyzing accidents on the road using more data, including more road safety external
 625 parameters.

626 *Table 14. Sustainable countermeasure policies corresponding to each independent variable condition.*

Pavement condition	Condition of each aspect			Results	Countermeasure
	AADT	AVS	Curve radius		
Dry	-30,000 vehicles/day	-	-	SVA will not increase even if AVS increase	•Place sign boards and marks which encourage drivers to be vigilant about the curves
		-	-	SVA will reduce if curving radius increase	
		-	-	SVA will reduce if curving radius increase	
	-	+60 km/h	-	SVA will increase if AADT increases	•Place sign boards and marks which encourage drivers to reduce vehicle speed
	-	-	+100 m	SVA will increase if AADT increases	
	-	-	+100 m	SVA will increase if AADT increases	
Wet	-	-60 km/h	-	SVA will reduce if skid resistance increases	•Improve skid resistance of a pavement
	-	-	+100 m	SVA will increase if AVS increase	•Place sign boards and marks which encourage drivers to reduce vehicle speed
	-	-	+100 m	SVA will increase if AVS increases	
	-	-	-100 m	SVA will reduce if skid resistance increase	•Improve skid resistance of a pavement
	-	-60 km/h	-100 m	SVA will reduce if skid resistance increase	

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